## Chapter 6 NETWORK CALCULUS

Discrete Event Systems Fall 2007

### Overview

- Motivation / Introduction
- · Preliminary concepts
- · Min-Plus linear system theory
- · The composition theorem
- Adversarial queuing theory
- Instability of FIFO
- · Stability of LIS

- Sections 1.2, 1.3, 1.4.1
- Section 3.1
- Section 1.4.2

in Book "Network Calculus" by Le Boudec and Thiran





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### What is Network Calculus/Adversarial Queuing Theory?

· Problem:

Distributed

Computing

- Queuing theory (Markov/Jackson assumptions) too optimistic.
- Online theory too pessimistic.
- Worst-case analysis (with bounded adversary) of queuing / flow systems arising in communication networks
- Network Calculus
  - Algebra developed by networking ("EE") researchers
- · Adversarial Queuing Theory
  - Worst-case analysis developed by algorithms ("CS") researchers

### An example



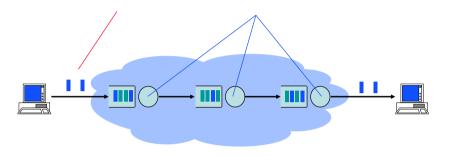
- assume R(t) = sum of arrived traffic in [0, t] is known
- required **buffer** for a bit rate c is  $\sup_{s < t} \{R(t) R(s) c \cdot (t-s)\}$





### Arrival and Service Curves

• Similarly to queuing thoery, Internet integrated services use the concepts of *arrival curve* and *service curves* 





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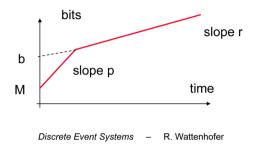
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### **Arrival Curves**

• Arrival curve  $\alpha$ :  $R(t) - R(s) \le \alpha(t-s)$ 

### Examples:

- leaky bucket  $\alpha(u) = ru + b$
- reasonable arrival curve in the Internet  $\alpha(u) = \min (pu + M, ru + b)$



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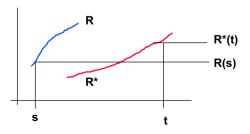
### Arrival Curves can be assumed sub-additive

- Theorem (without proof):  $\alpha \text{ can be replaced by a } \textit{sub-additive} \text{ function}$
- sub-additive means:  $\alpha(s+t) \le \alpha(s) + \alpha(t)$
- concave  $\Rightarrow$  subadditive

### Service Curve

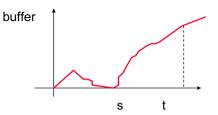
• System S offers a service curve  $\beta$  to a flow iff for all t there exists some s such that

$$R^*(t) - R(s) \ge \beta(t-s)$$





Theorem: The constant rate server has service curve  $\beta(t)$ =ct



**Proof**: take s = beginning of busy period. Then,

$$R^*(t) - R^*(s) = c \cdot (t-s)$$
  
 $R^*(t) - R(s) = c \cdot (t-s)$ 

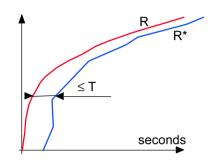


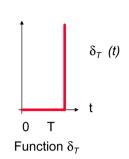
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### The guaranteed-delay node has service curve $\delta_{\scriptscriptstyle T}$





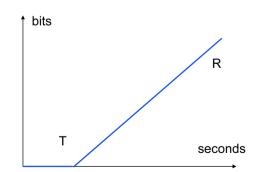


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### A reasonable model for an Internet router

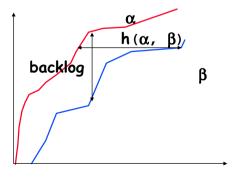
· rate-latency service curve



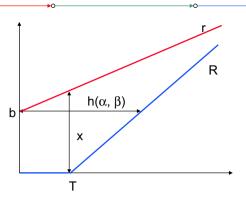
## Tight Bounds on delay and backlog

If flow has arrival curve  $\alpha$  and node offers service curve  $\beta$  then

- backlog  $\leq$  sup  $(\alpha(s) \beta(s))$
- delay  $\leq h(\alpha, \beta)$



### For reasonable arrival and service curves



- delay bound: b/R + T
- backlog bound: b + rT



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### Another linear system theory: Min-Plus

- Standard algebra: R, +,  $\times$  a  $\times$  (b + c) = (a  $\times$  b) + (a  $\times$  c)
- Min-Plus algebra: R, min, +  $a + (b \land c) = (a + b) \land (a + c)$



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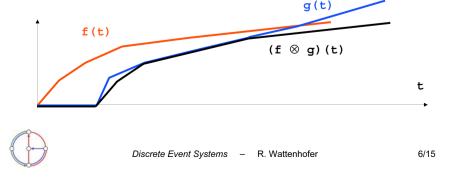
### Min-plus convolution

• Standard convolution:

$$(f*g)(t) = \int f(t-u)g(u)du$$

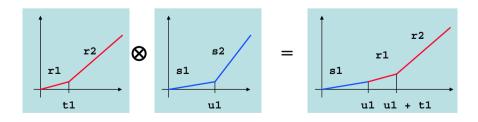
• Min-plus convolution

$$f \otimes g(t) = \inf_{u} \{ f(t-u) + g(u) \}$$



## Examples of Min-Plus convolution

- $f \otimes \delta_T(t) = f(t-T)$
- convex piecewise linear curves, put segments end to end with increasing slope





### Arrival and Service Curves vs. Min-Plus

- We can express arrival and service curves with min-plus
- Arrival Curve property means

$$R \le R \otimes \alpha$$

· Service Curve guarantee means

$$R^* \ge R \otimes \beta$$

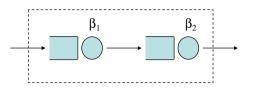


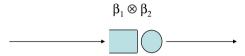
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### The composition theorem

• **Theorem**: the concatenation of two network elements offering service curves  $\beta_i$  and  $\beta_2$  respectively, offers the service curve  $\beta_1 \otimes \beta_2$ 





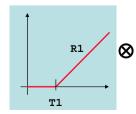


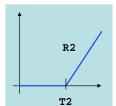
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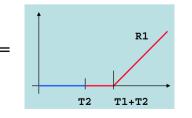
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### Example: Tandem of Routers









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### Pay Bursts Only Once

 $\alpha \xrightarrow{D_1} \xrightarrow{D_2} \beta_2$ 

$$D_1 + D_2 \le (2b + RT_1)/R + T_1 + T_2$$

 $\alpha \xrightarrow{\beta_1 \otimes \beta_2}$ 

$$D \le b / R + T_1 + T_2$$

end to end delay bound is less

### **Adversarial Queuing Theory**

- We will revise several models of connectionless packet networks.
- We have a bounded adversary which defines the network traffic.
  - Like network calculus
- Our objective is to study stability under these adversaries.
  - If a network is stable, we study latency.
- [Thanks to Antonio Fernández for many of the following slides.]



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### **Network Model**

- The general network model assumed is as follows
  - A network is a directed graph.
  - Packets arrive continuously into the nodes of the network.
  - Link queues are not bounded.
  - A packet has to be routed from its source to its destination.
  - At each link packets must be scheduled: if there are several candidates to cross, one must be chosen by the scheduler.
- To make the analyses simpler initially, we assume
  - All packets have the same unit length.
  - All links have the same bandwidth.

Adversarial Queuing Theory Model

- This allows to consider a synchronous system, that is, the network evolves in steps. In each step each link can be crossed by at most one packet.



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• [Borodin, Kleinberg, Raghavan, Sudan, Williamson, STOC96]

• [Andrews, Awerbuch, Fernandez, Kleinberg, Leighton, Liu, FOCS96]

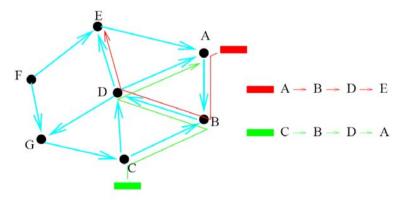
· There is an adversary that chooses the arrival times and the routes of

• The adversary is bounded by parameters (r, b), where b > 1 is an integer and r < 1, such that, for any link e, for any s > 1, at most rs +

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### Example

- We are given two packets, each needs to cross three links.
- There is congestion on the link B→D, the execution needs 4 steps.





### b packets injected in any s-step interval must cross edge e.

all the packets

We have a scheduling problem.



### Stability

- A scheduling policy P is stable at rate (r, b) in a network G if there is a bound C(G, r, b) such that no (r, b)-adversary can force more than C(G, r, b) simultaneous packets in the network.
- A scheduling policy P is universally stable if it is stable at any rate r
   1 in any network.
- A network G is universally stable if it is stable at any rate r < 1 with any greedy scheduling policy.



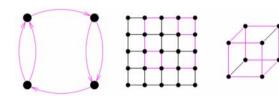
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### Some Results

- Any acyclic directed graph (DAG) is universally stable, even for r = 1 [BKRSW01].
- The ring is universally stable
  - There are never more than O(bn/(1 r)) packets in any queue.
  - A packet never spends more than  $O(bn/(1 r)^2)$  steps in the system.
  - Any added link makes the ring unstable with some greedy policy (for instance with Nearest-to-Go, NTG).
- FIFO is unstable for r > 0.85 with these networks:





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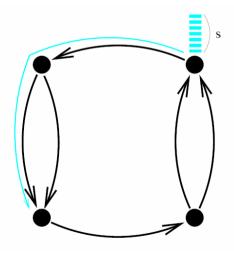
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### **Proof of FIFO Instability**

- Initially we have s packets in a queue with a given configuration.
  - Think of these packets to be inserted in an initial burst
- Then the algorithm proceeds in phases
  - Each phase is a bit longer than the phase before.
  - After each phase, we have the initial configuration, however, with more packets in a specific queue than in the previous phase.
  - By chaining infinite phases, any number of packets in the system can be reached.
- We show here the behavior of the adversary and the system in one phase.
  - Each phase has three rounds.



## Initial Situation



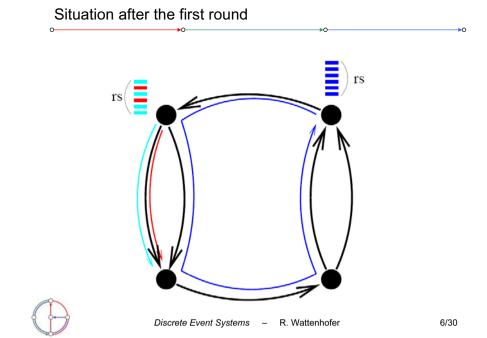


# Injecting packets in the first round (s steps)

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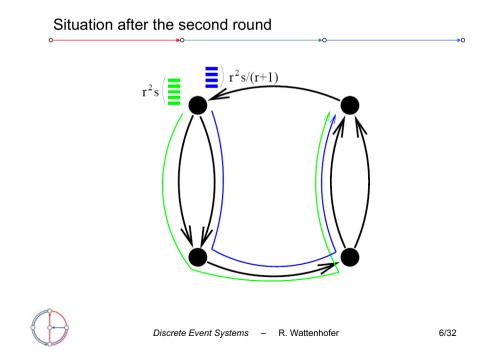
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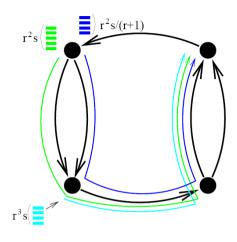


# Injecting packets in the second round (rs steps) r<sup>2</sup>s rs

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### Injecting packets in the third round (r2s steps)

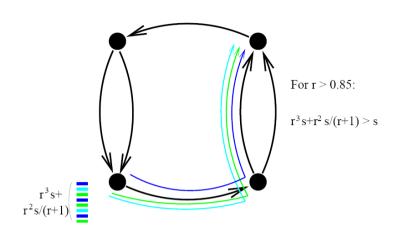




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### Final situation (end of phase, after the third round)





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### More Results

- · Several simple greedy policies are universally stable
  - Longest-in-System (LIS): Gives priority to oldest packet (in the system).
  - Shortest-in System (SIS): Gives priority to newest packet (in the system).
  - Farthest-to-Go (FTG): Gives priority to the packet farthest from destination.
  - Nearest-to-Source (NTS): Gives priority to the packet closest to its origin.
- All mentioned greedy policies can suffer delays that are exponential in d, where d is the maximum routing distance.
  - Moreover, any deterministic policy that does not use information about the packet routes to schedule can suffer delays exponential in √d [Andrews Z 04].
  - There are deterministic distributed algorithms that guarantee polynomial delays and queue lengths [Andrews FGZ 05].

### Universal stability of LIS (Longest-in-System)

- Network G, adversary in bucket AQT with parameters r = 1-ε < 1 and b > 1.
- Def.: Class L is the set of packets injected in step L.
- Def.: A class L is active at the end of step t if there are some packets of class  $L' \le L$  in the system at the end of step t.
- Let us consider a packet p injected in step T<sub>0</sub>. Packet p must cross d links, it crosses the ith link in step T<sub>i</sub>.
- Def.: c(t) is the number of active classes at the end of step t.
   Let c = max<sub>T<sub>0</sub> ≤ t < T<sub>d</sub></sub> c(t), that is the maximum number of active classes during the lifetime of packet p.

Lemma:  $T_d - T_0 \le (1 - \varepsilon^d)(c + \frac{b}{1 - \varepsilon}).$ 

- p arrives to the queue of its ith link in T<sub>i-1</sub>.
- Only the packets in c (T<sub>i-1</sub>–T<sub>0</sub>) active classes can block p.
- There are no more than (1-ε)(c+T<sub>0</sub>-T<sub>i-1</sub>) + b packets in these classes (p included), that is at most (1-ε)( c+T<sub>0</sub>-T<sub>i-1</sub>) + b-1 packets can block p. Then,

$$T_{i} \leq T_{i-1} + (1-\varepsilon)(c+T_{0}-T_{i-1}) + b$$

$$= \varepsilon T_{i-1} + (1-\varepsilon)(c+T_{0}) + b.$$

$$T_{d} \leq ((1-\varepsilon)(c+T_{0}) + b) \sum_{i=0}^{d-1} \varepsilon^{i} + \varepsilon^{d} T_{0}$$

$$= ((1-\varepsilon)(c+T_{0}) + b) \frac{1-\varepsilon^{d}}{1-\varepsilon} + \varepsilon^{d} T_{0}$$

$$= (1-\varepsilon^{d})(c+\frac{b}{1-\varepsilon}) + T_{0}$$



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### Theorem: LIS is universally stable

- Each packet leaves the system after  $c = b/((1-\epsilon)\epsilon^d)$  steps.
- In addition one can show that there are at most b+b/ $\epsilon^d$  packets in each queue at all times.

### · That's all folks!



### Lemma: Bounding both classes and steps

- Let t be the first time when either the system features more than c classes, or there is a packet in the system for more than c steps, for some c.
- Clearly, "classes" cannot be violated first, because there can only be c+1 classes if there is at least one packet in the system for at least c+1 steps.
- So we know that "steps" must be violated first. Let p be a first packet which is in the system for at least c+1 steps. (Note that during this time, we had at most c classes.)
- Let c = b/((1-ε)ε<sup>d</sup>). Then the packet p cannot be in the system for more than c steps, because using our previous lemma (and b≥1 and ε>0), the number of steps of p is bounded:

$$(1 - \varepsilon^d)(c + \frac{b}{1 - \varepsilon}) + 1 = c - \varepsilon^d b / (1 - \varepsilon) + 1 < c + 1$$



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