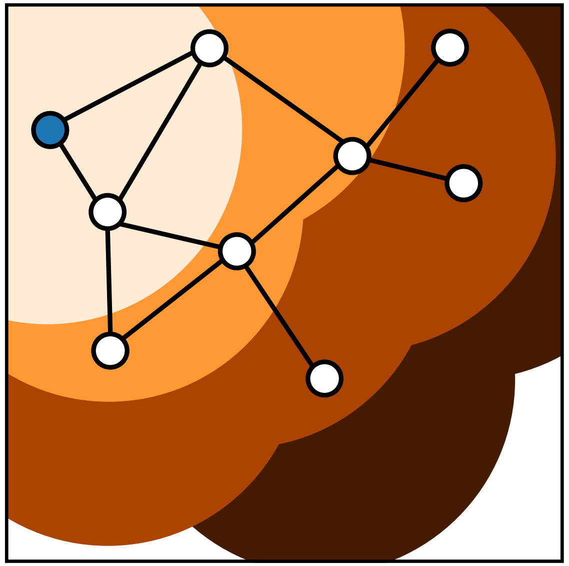
Discrete Event Systems
Verification of Finite Automata (Part 2)



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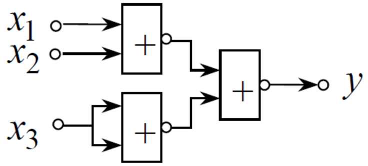
Most materials from Lothar Thiele and Romain Jacob

Last week in
Discrete Event Systems

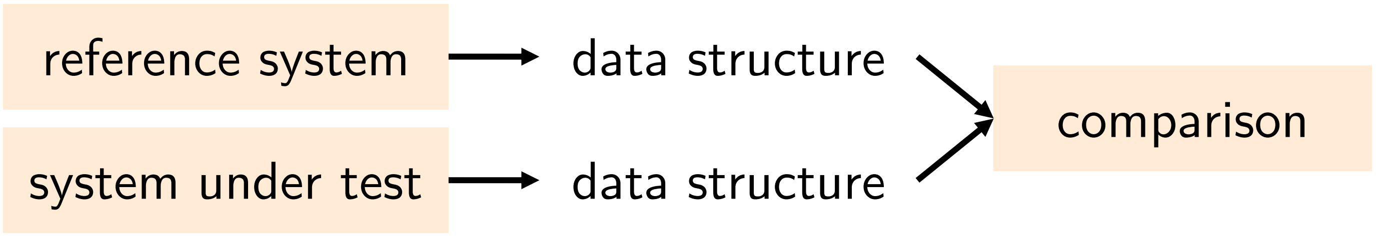
Verification Scenarios

Example

$y = (x_1 + x_2) \cdot x_3$

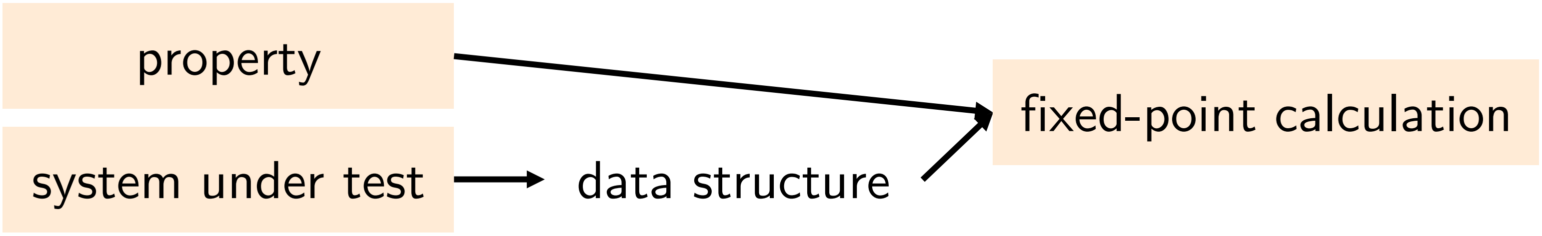


Comparison of specification and implementation



Proving properties

"The device can always be switched off."

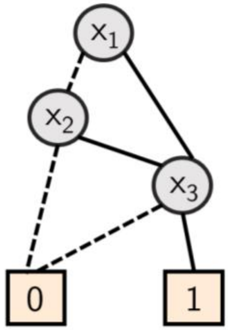


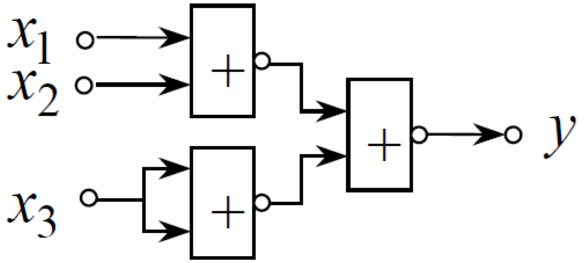
Comparison using BDDs

- Boolean (combinatorial) circuits: Compare specification and implementation, or compare two implementations.
- Method:
  - Representation of the two systems in ROBDDs, e.g., by applying the ***APPLY*** operator repeatedly.
  - Compare the structures of the ROBDDs.
- Example:

$$y = (x_1 + x_2) \cdot x_3$$

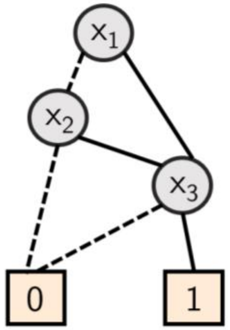
APPLY





$$y = \overline{\overline{x_1 + x_2} + \overline{x_3 + x_3}}$$

APPLY

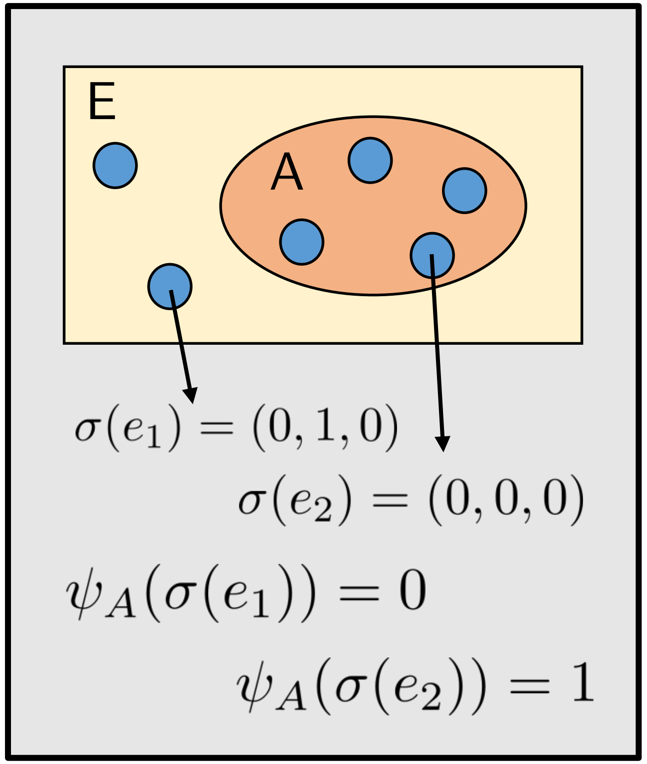


compare

Sets and Relations

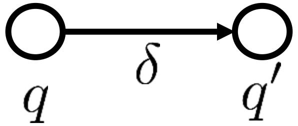
characteristic function of subset A

- Representation of a subset $A \subseteq E$:
  - Binary encoding $\sigma(e)$ of all elements $e \in E$
  - Subset A is represented by $a \in A \Leftrightarrow \psi_A(\sigma(a))$



- Relation function: describe state transitions

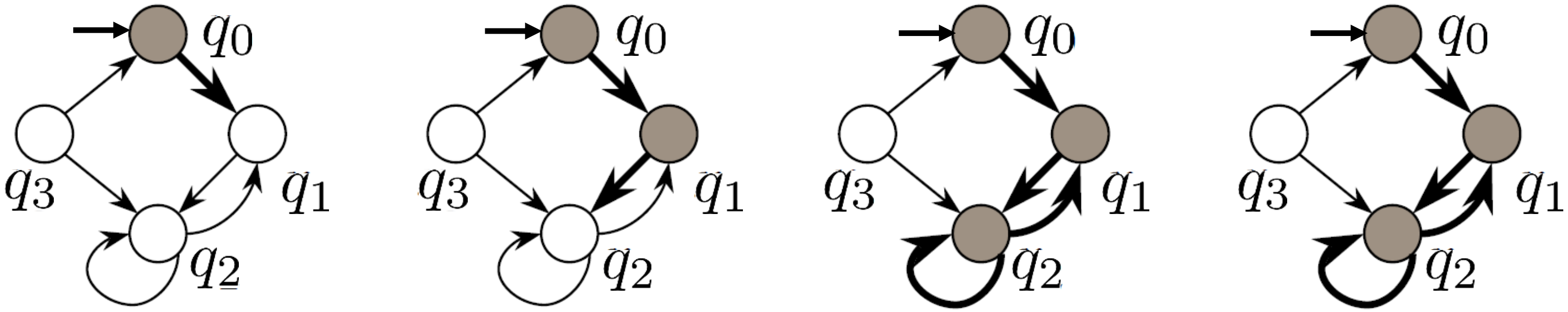
$$\psi_\delta(\sigma(q), \sigma(q')) = \psi_\delta(q, q')$$



Reachability of States

- Problem: Is a state $q \in Q$ reachable by a sequence of state transitions?
- Method:
  - Represent set of states and the transformation relation as ROBDDs.
  - Use these representations to transform from one set of states to another. Set Q_i corresponds to the set of states reachable after i transitions.
  - Iterate the transformation until a fixed-point is reached, i.e., until the set of states does not change anymore (steady-state).
- Example:

$Q_0 = \{q_0\}$ $\quad$ $Q_1 = \{q_0, q_1\}$ $\quad$ $Q_2 = \{q_0, q_1, q_2\}$ $\quad$ $Q_3 = \{q_0, q_1, q_2\}$



This week in

Discrete Event Systems

	Topic	Contents
	Efficient state representation	- Set of states as Boolean function - Binary Decision Diagram representation
	Computing reachability	- Leverage efficient state representation - Explore successor sets of states
Today	Proving properties	- Temporal logic (CTL) - Encoding as reachability problem

Temporal Logic

- Verify properties of a finite automaton, for example
  - Can we always reset the automaton?
  - Is every request followed by an acknowledgement?
  - Are both outputs always equivalent?

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- Specification of the query in a formula of temporal logic.
- We use a simple form called Computation Tree Logic (CTL).

- Let us start with a minimal set of operators.
  - Any atomic proposition is a CTL formula.
  - CTL formula are constructed by composition of other CTL formula.

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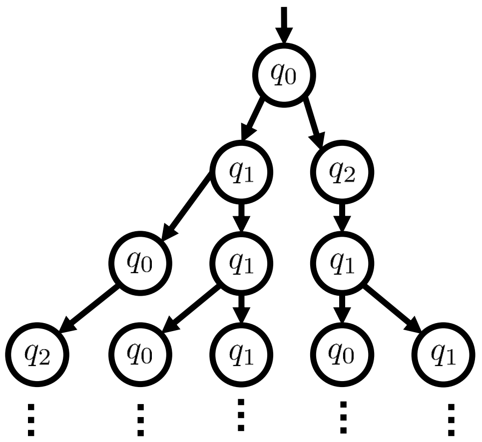
There exists other logics (e.g. LTL, CTL*)

Formulation of CTL properties



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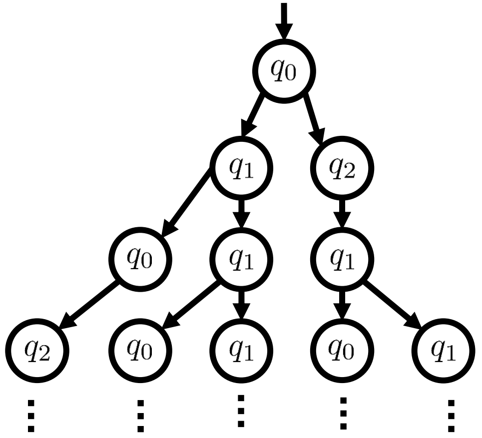


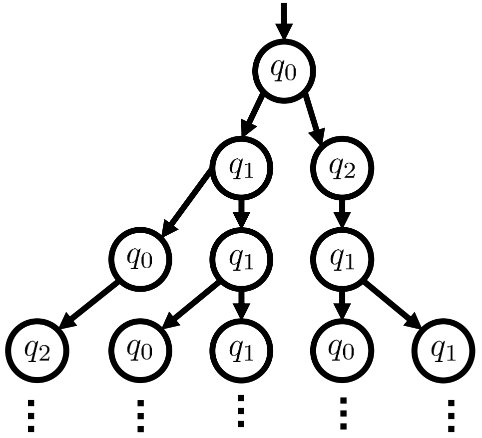
Based on atomic propositions (ϕ) and quantifiers

Aϕ → «**A**ll ϕ», ϕ holds on all paths

Eϕ → «**E**xists ϕ», ϕ holds on at least one path

Quantifiers over paths

Formulation of CTL properties



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$E\phi$	→ «**E**xists ϕ»,	ϕ holds on at least one path	
$X\phi$	→ «Ne**X**t ϕ»,	ϕ holds on the next state	Path-specific quantifiers
$F\phi$	→ «**F**inally ϕ»,	ϕ holds at some state along the path	
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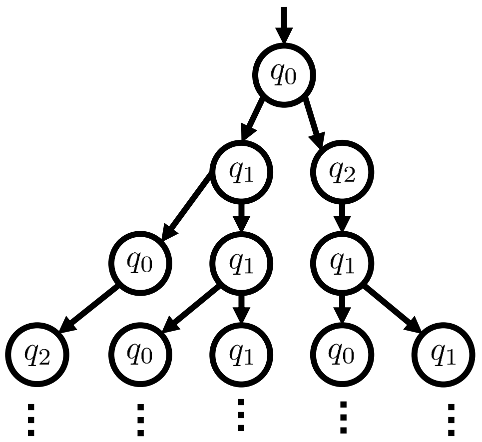

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Path-specific quantifiers

CTL quantifiers work in pairs: we need one of each! {A,E} {X,F,G,U}ϕ

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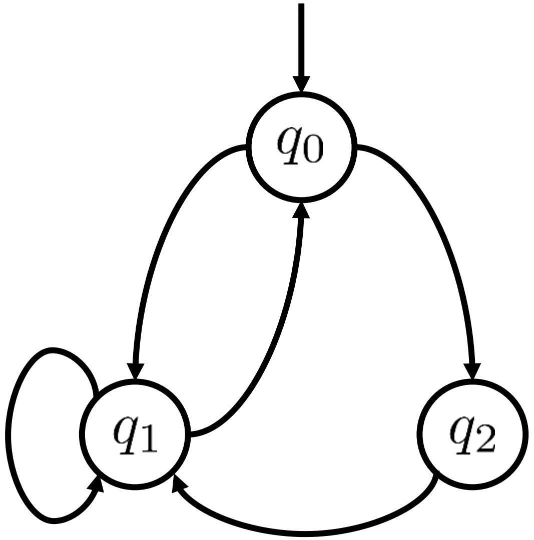
Automaton



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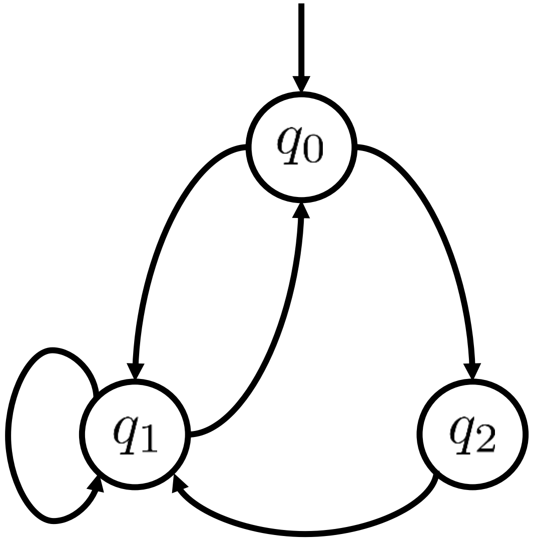
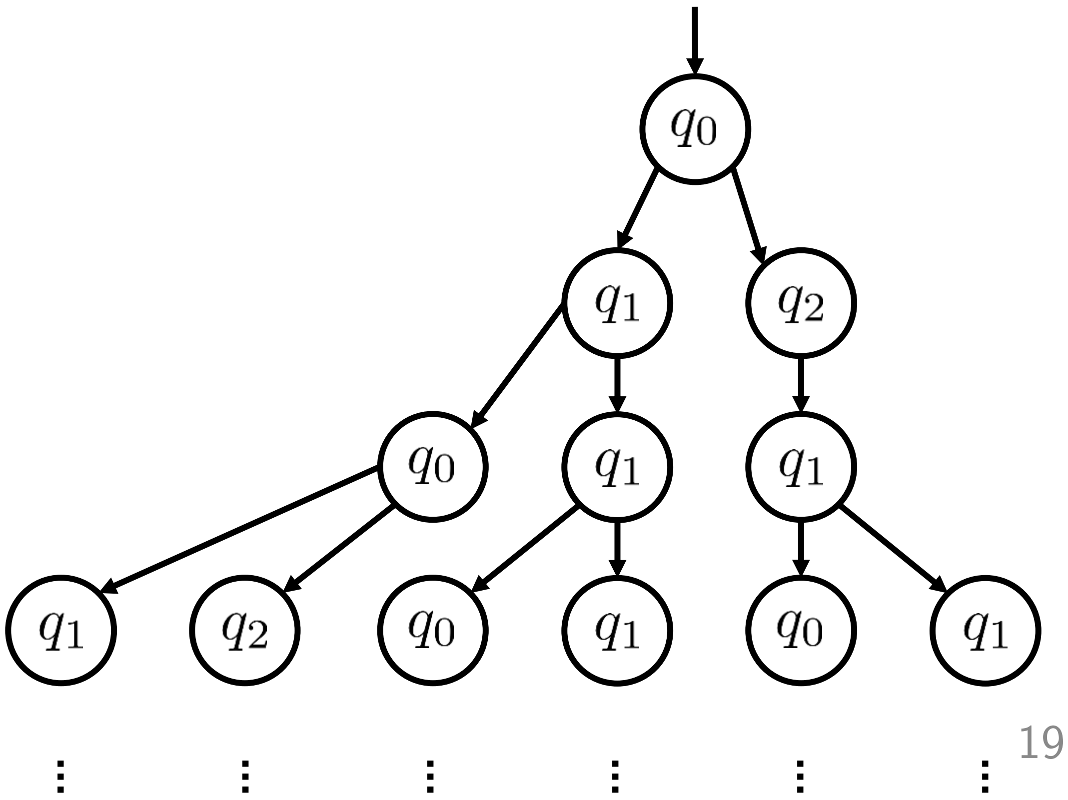


Computation tree



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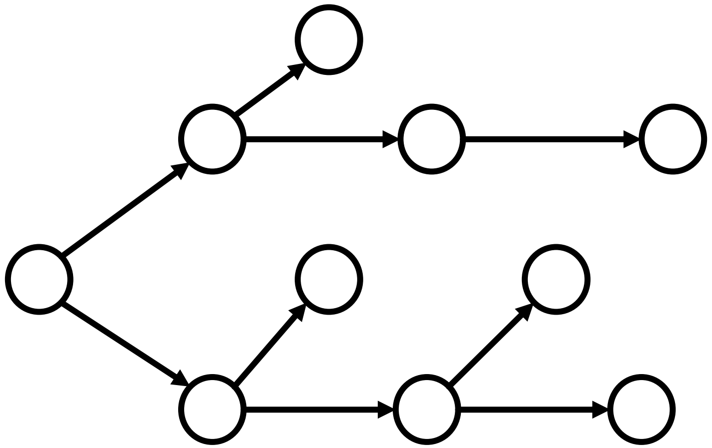
CTL works on computation trees

Automaton of interest



Requires fully-defined transition functions

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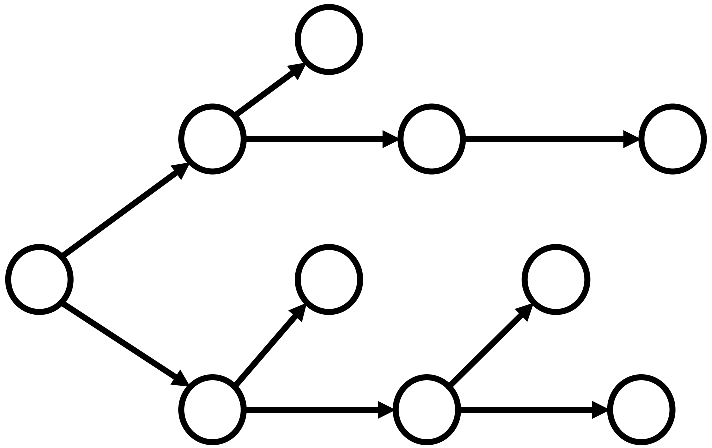
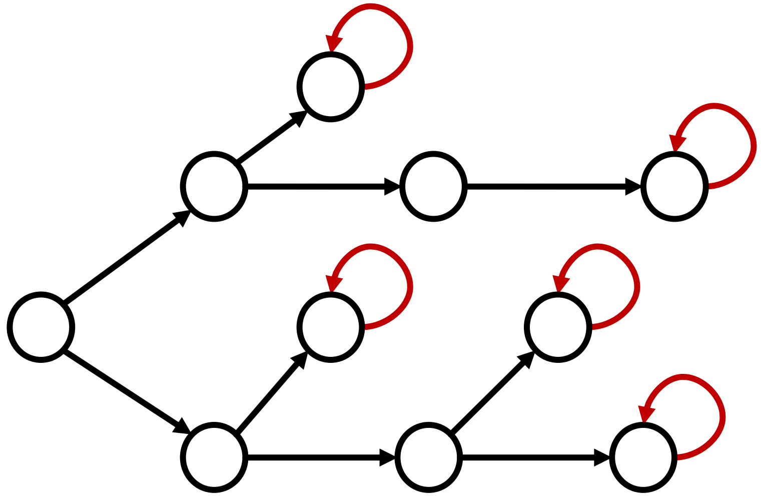


Requires fully-defined transition functions

Automaton to work with



Each state has at least one successor (can be itself)

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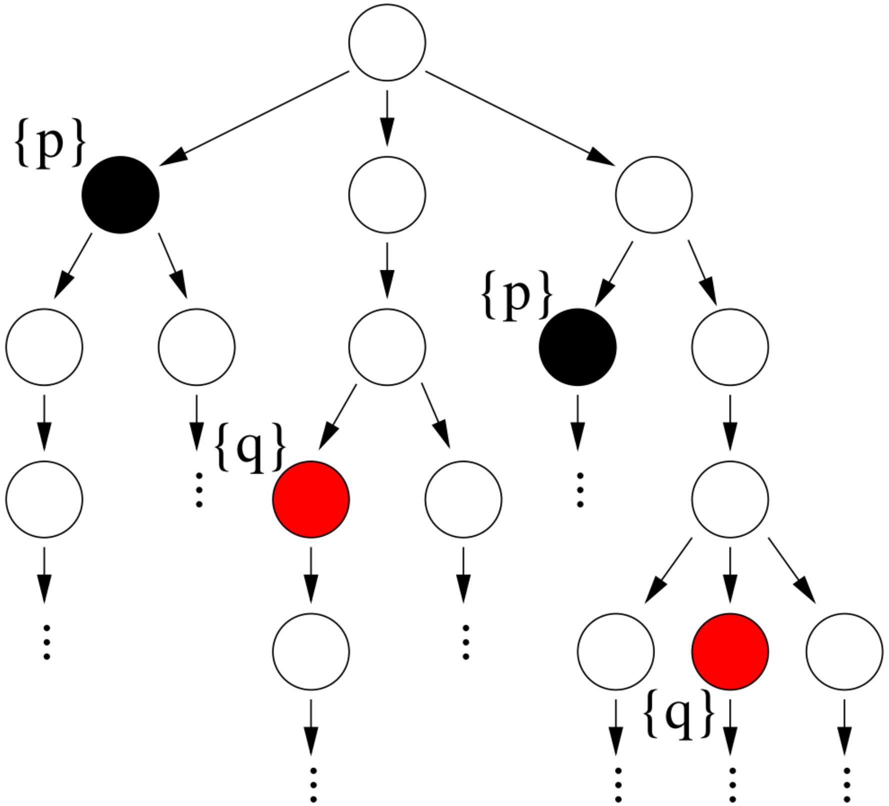
Visualizing CTL formula

- We use this computation tree as a running example.
- We suppose that the black and red states satisfy atomic properties p and q, respectively.
- The topmost state is the initial state; in the examples, it always satisfies the given formula.



M satisfies $\phi \iff q_0 \vDash \phi$ where q_0 is the initial state of M

Visualizing CTL formula

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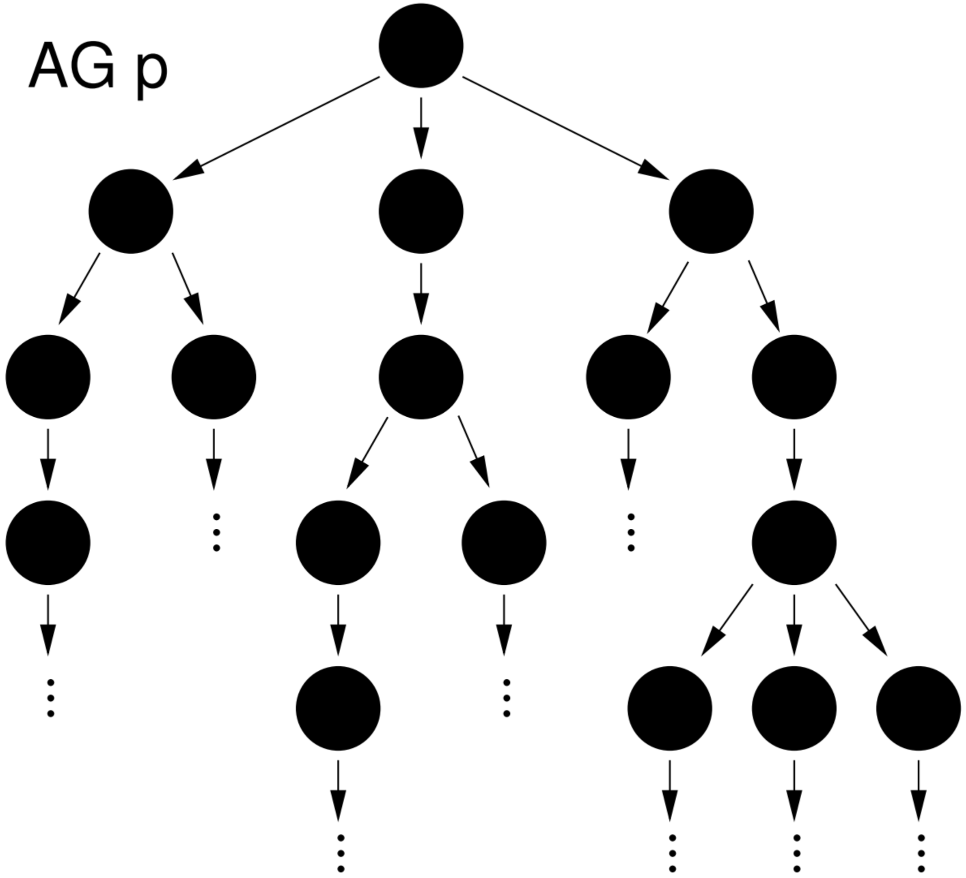
AG p



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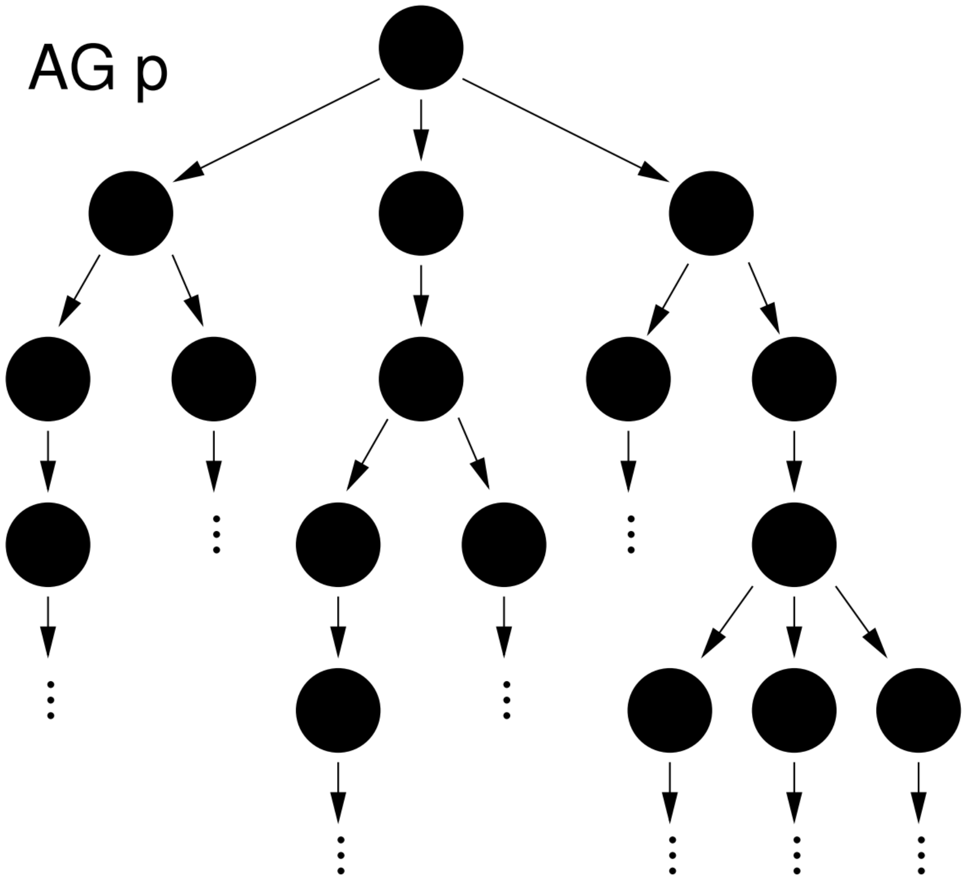

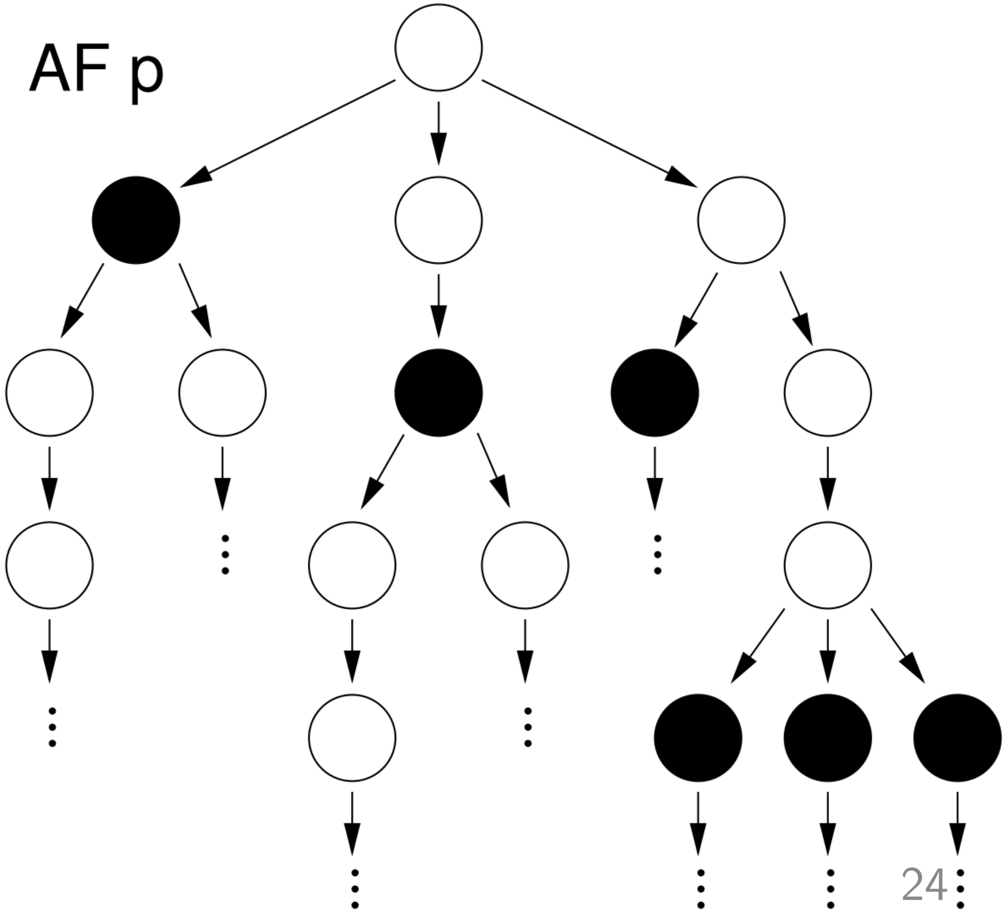

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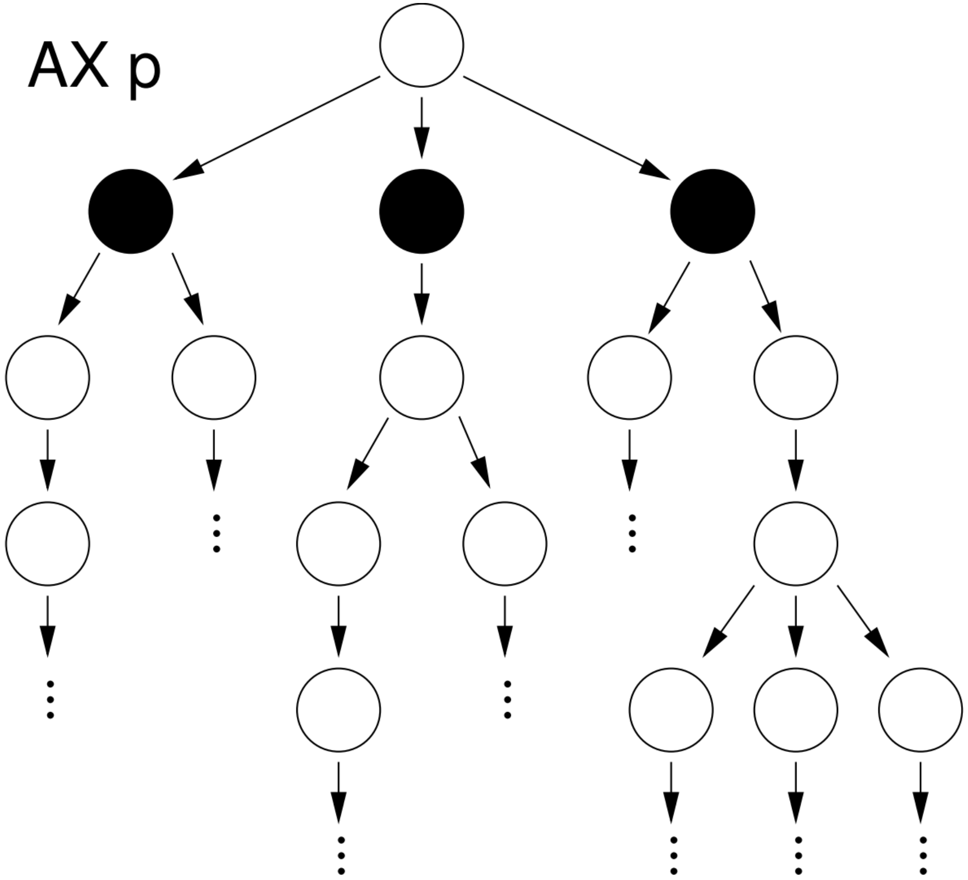
AX p



Visualizing CTL formula

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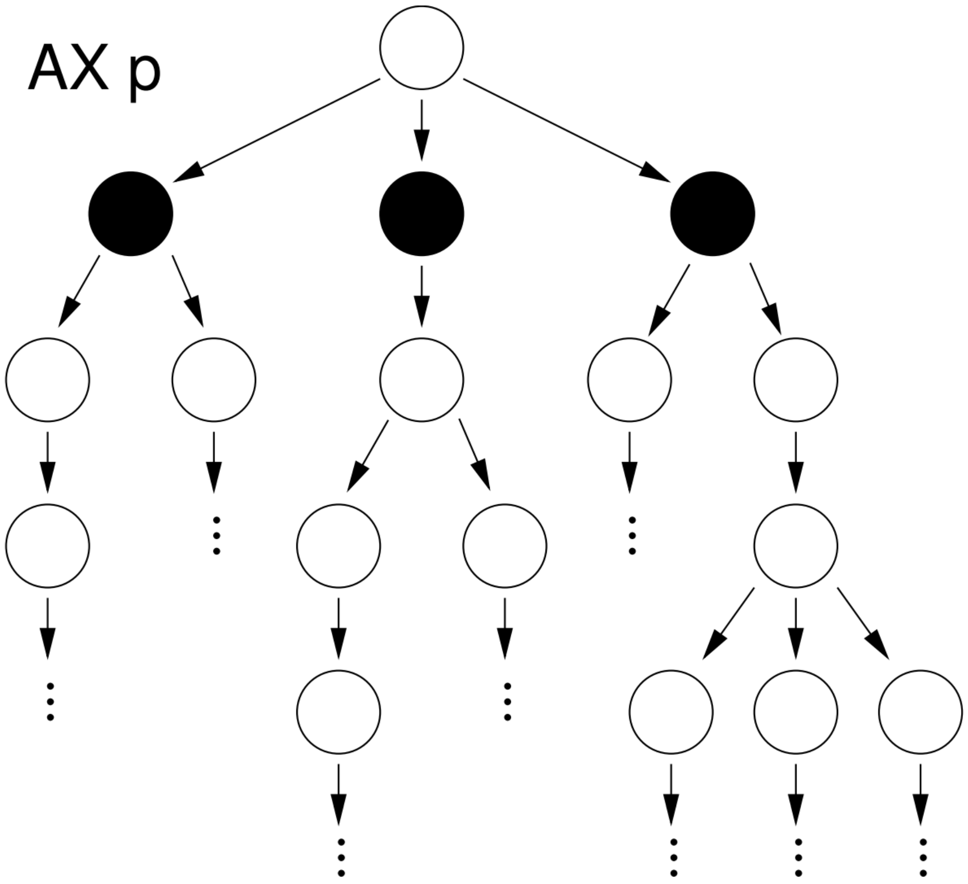

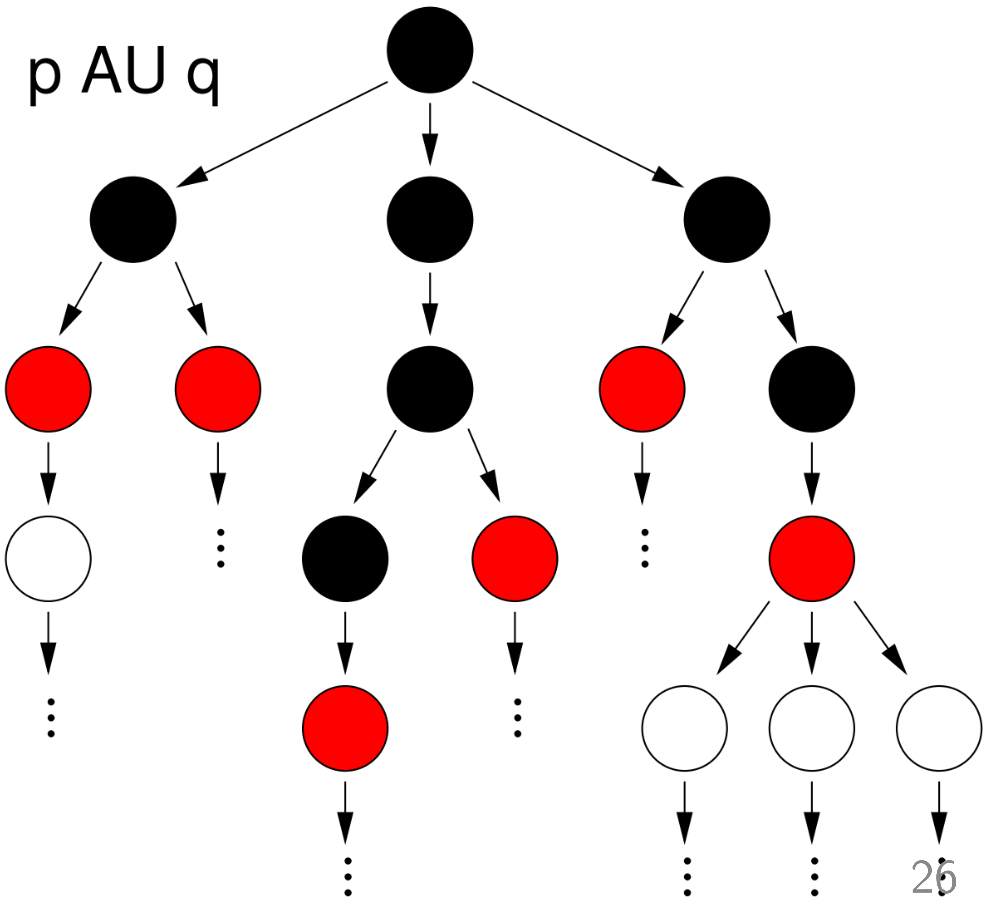

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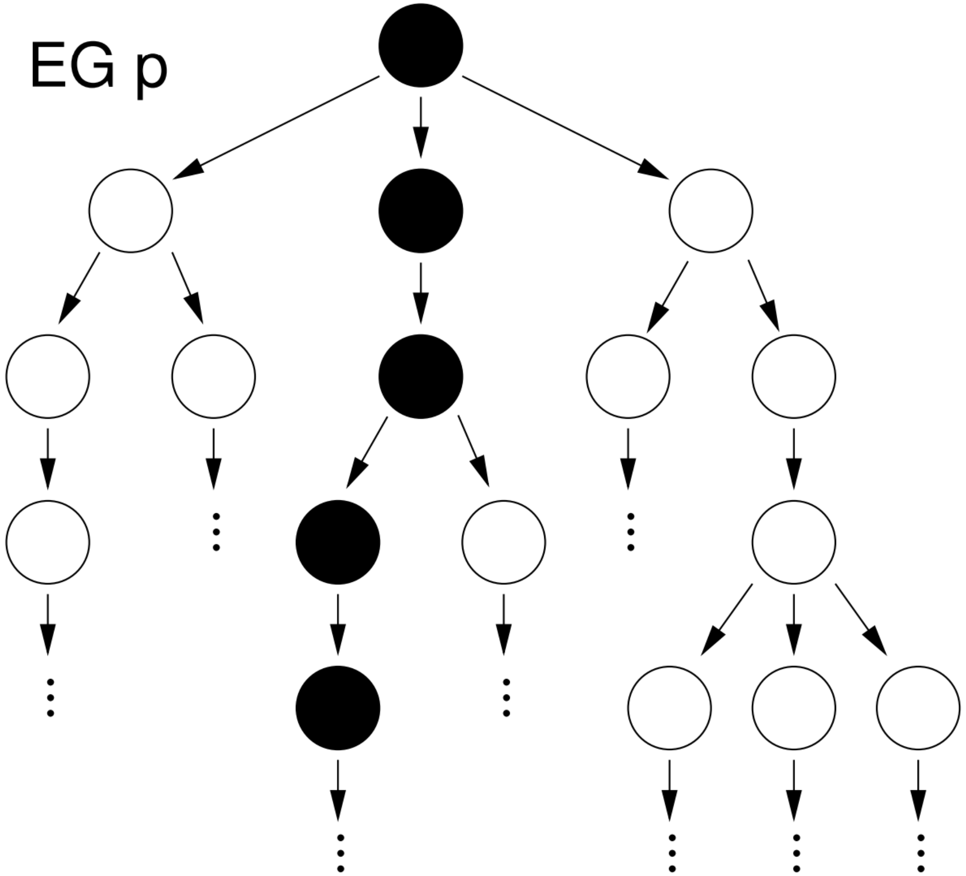
Visualizing CTL formula

EG p



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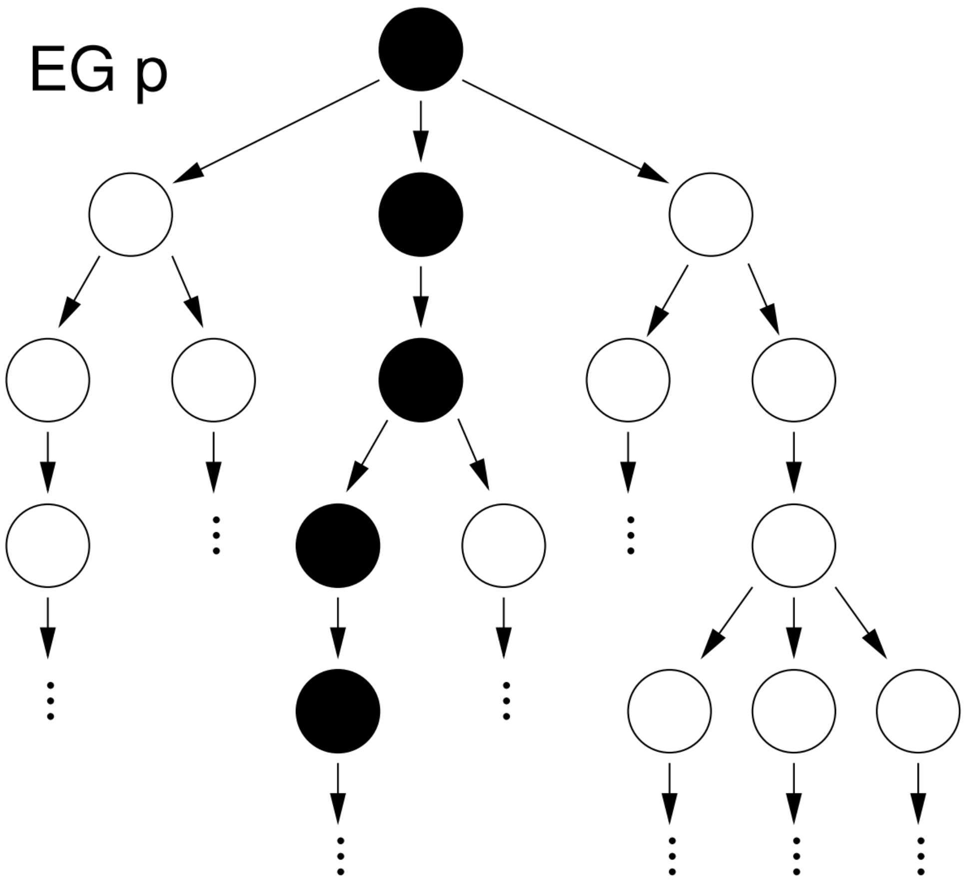

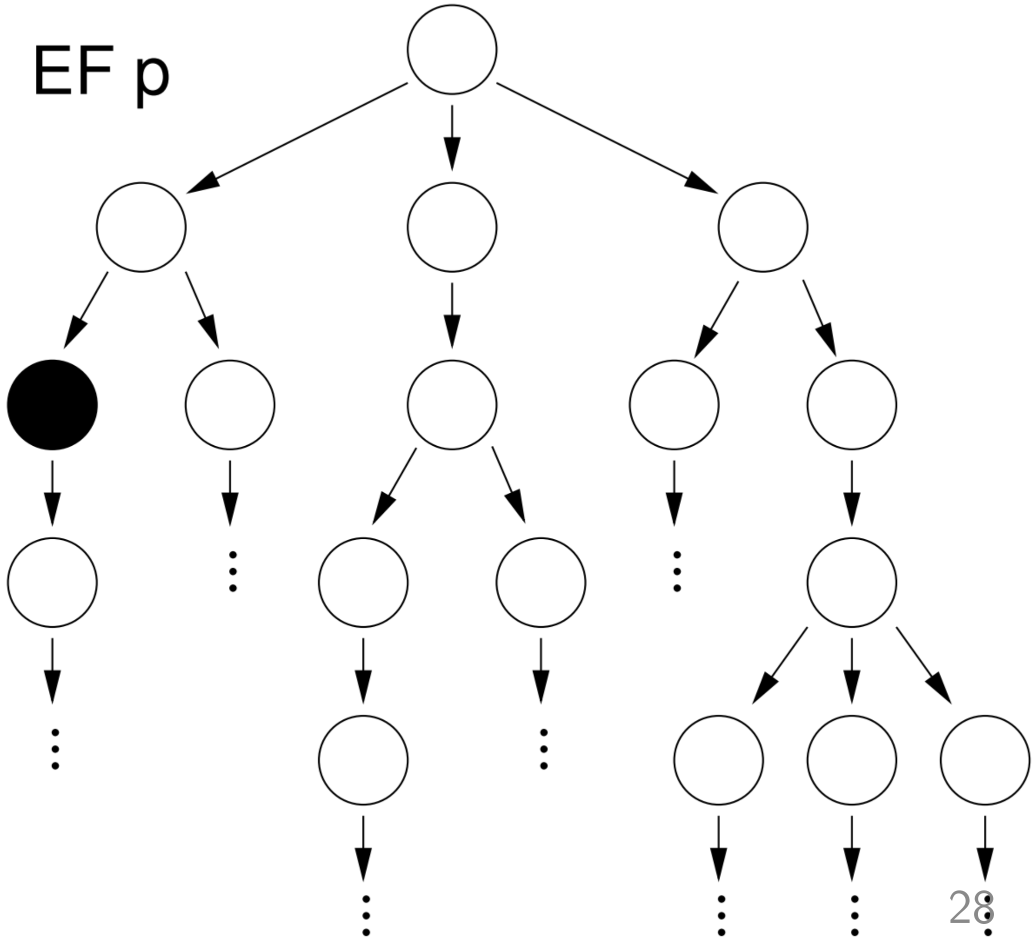

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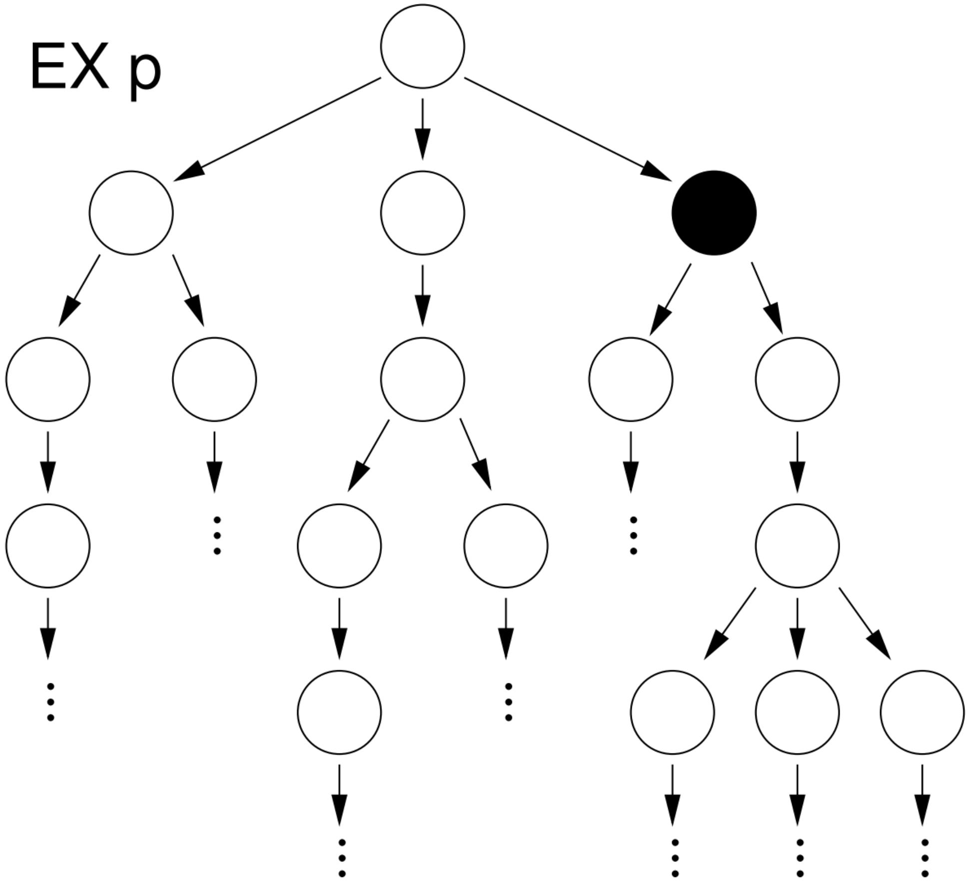
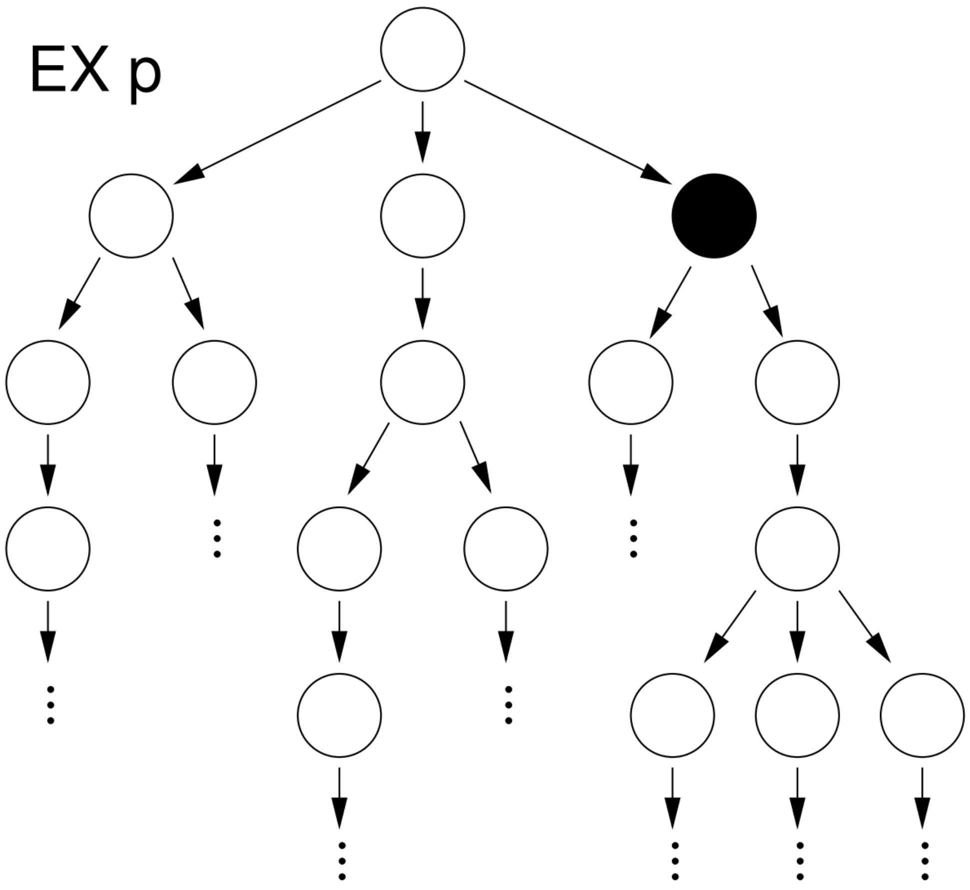
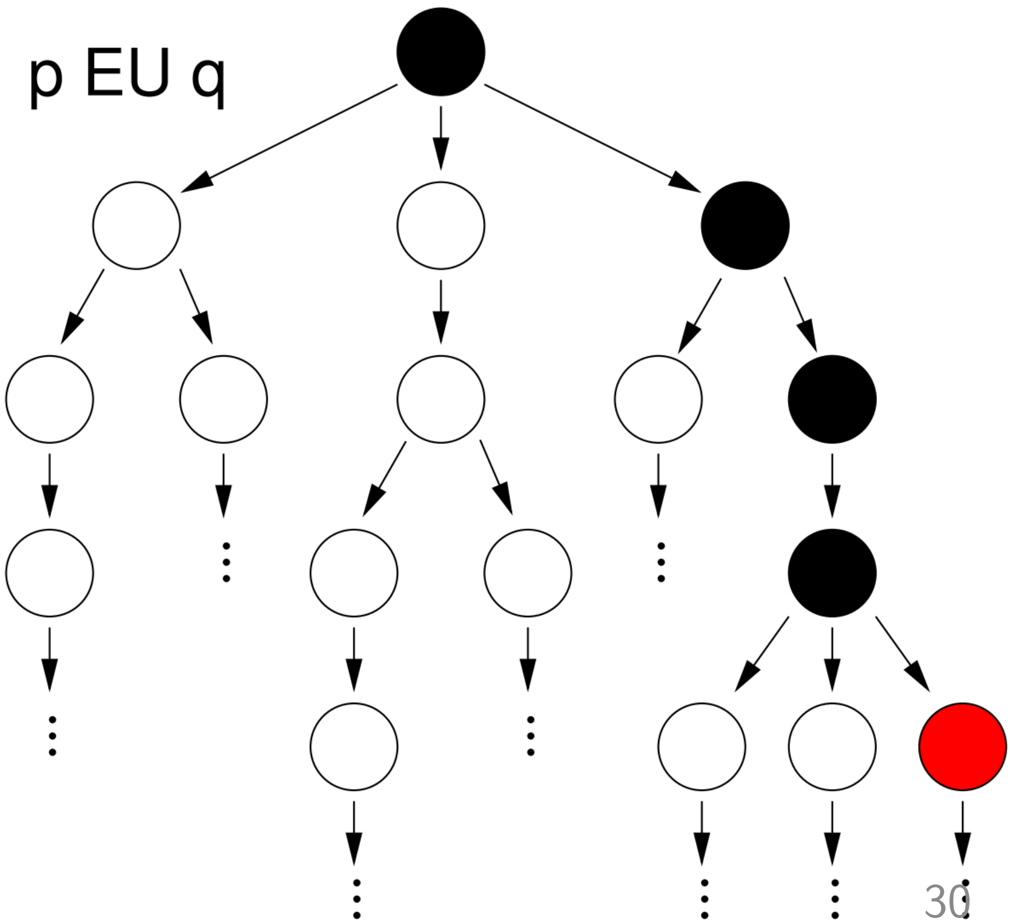
Visualizing CTL formula

EX p



Visualizing CTL formula





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Formulation of CTL properties

Can be more than one pair

AG ϕ_1 where ϕ_1 = EF ϕ_2 $\equiv$ AG EF ϕ_2

A and F are convenient, but not necessary

E,G,X,U are sufficient to define the whole logic.

$$\mathrm{AF}\phi \equiv \neg \mathrm{EG}(\neg\phi)$$
$$\mathrm{AG}\phi \equiv \neg \mathrm{EF}(\neg\phi)$$
$$\mathrm{AX}\phi \equiv \neg \mathrm{EX}(\neg\phi)$$
$$\mathrm{EF}\phi \equiv \mathrm{true}\,\mathrm{EU}\phi$$

No need to know that one ▸

$$\phi_1 \mathrm{AU} \phi_2 \equiv \neg([(\neg\phi_1)\mathrm{EU}\neg(\phi_1 + \phi_2)] + \mathrm{EG}(\neg\phi_2))$$

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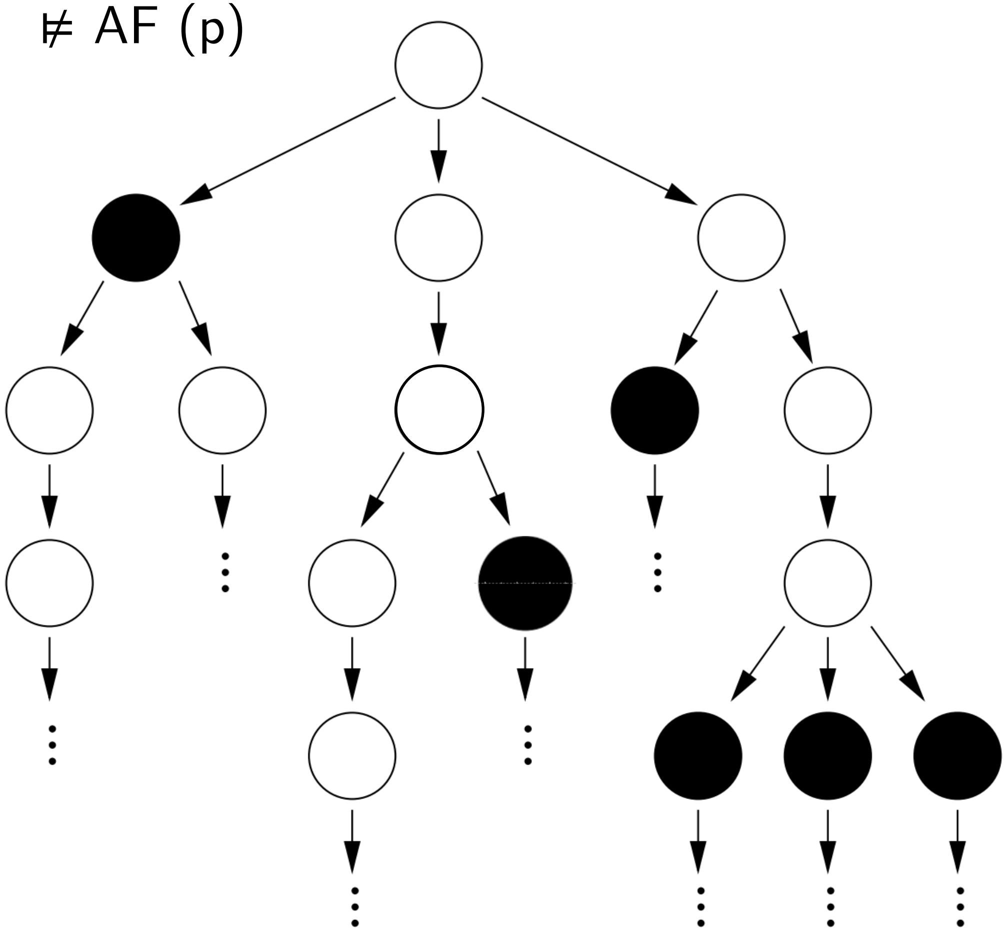
Intuition for "AF p = ¬ EG (¬ p)"

$\not\models$ AF (p)



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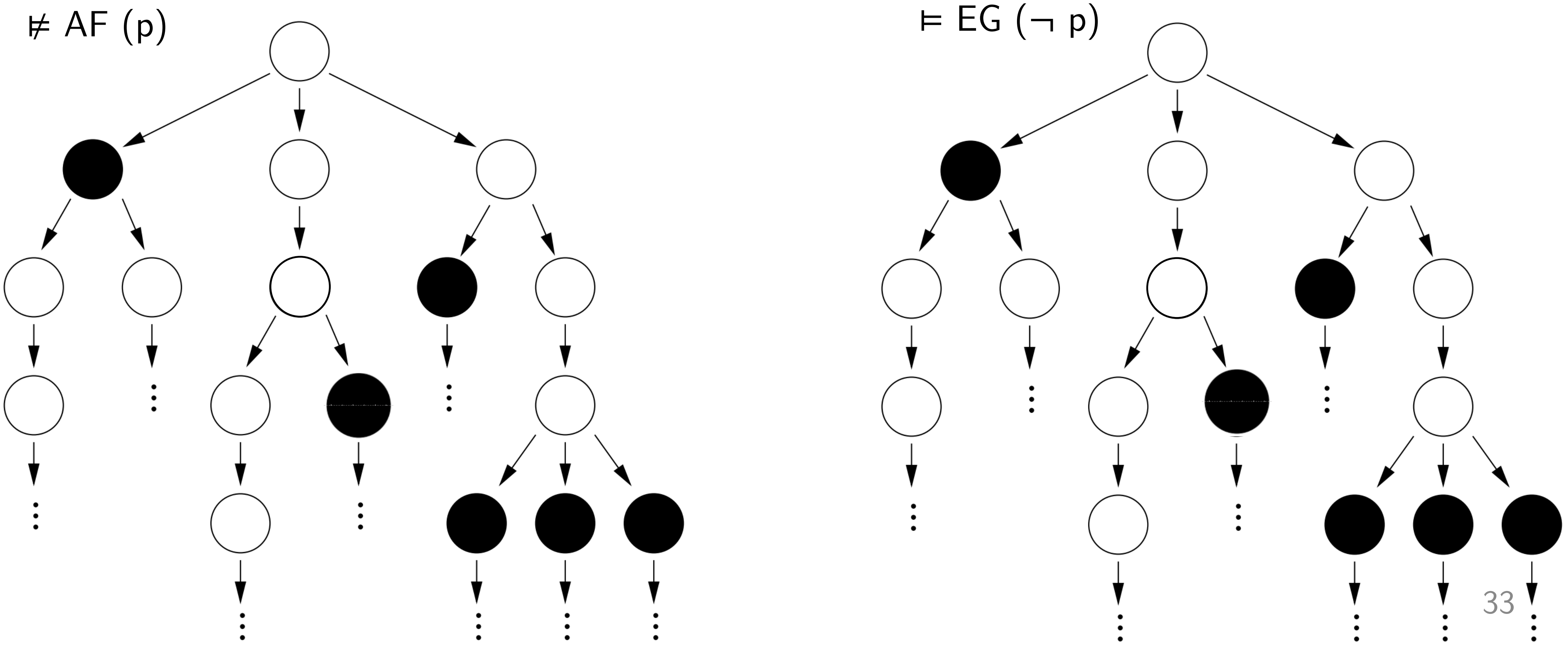

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Interpreting CTL formula

Encoding	Proposition
p	I like chocolate
q	It's warm outside

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- AG p

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Interpreting CTL formula

Encoding	Proposition
p	I like chocolate
q	It's warm outside

- AG p — I will like chocolate from now on, no matter what happens.

Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
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Interpreting CTL formula

Encoding	Proposition
p	I like chocolate
q	It's warm outside

- AG p — I will like chocolate from now on, no matter what happens.
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Over paths:
$A\phi \rightarrow$ **A**ll ϕ
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Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
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Interpreting CTL formula

Encoding	Proposition
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- AG p — I will like chocolate from now on, no matter what happens.
- EF p — It's possible I may like chocolate someday, at least for one day.
- AF EG p — There will be always sometime in the future (AF) that I may suddenly start liking chocolate for the rest of time (EG).

Over paths:
$A\phi$ → **All** ϕ
$E\phi$ → **Exists** ϕ

Path-specific:
$X\phi$ → Ne**X**t ϕ
$F\phi$ → **F**inally ϕ
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$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

Interpreting CTL formula

Encoding	Proposition
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Over paths:
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$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
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Interpreting CTL formula

Encoding	Proposition
p	I like chocolate
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- EF p — It's possible I may like chocolate someday, at least for one day.
- AF EG p — There will be always sometime in the future (AF) that I may suddenly start liking chocolate for the rest of time (EG).
- EG AF p — This is a critical time in my life. Depending on what happens (E), it's possible that for the rest of time (G), there will always be some time in the future (AF) when I will like chocolate. However, if the wrong thing happens next, then all bets are off and there's no guarantee about whether I will ever like chocolate.

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
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Interpreting CTL formula

Encoding	Proposition
p	I like chocolate
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- p AU q

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Interpreting CTL formula

Encoding	Proposition
p	I like chocolate
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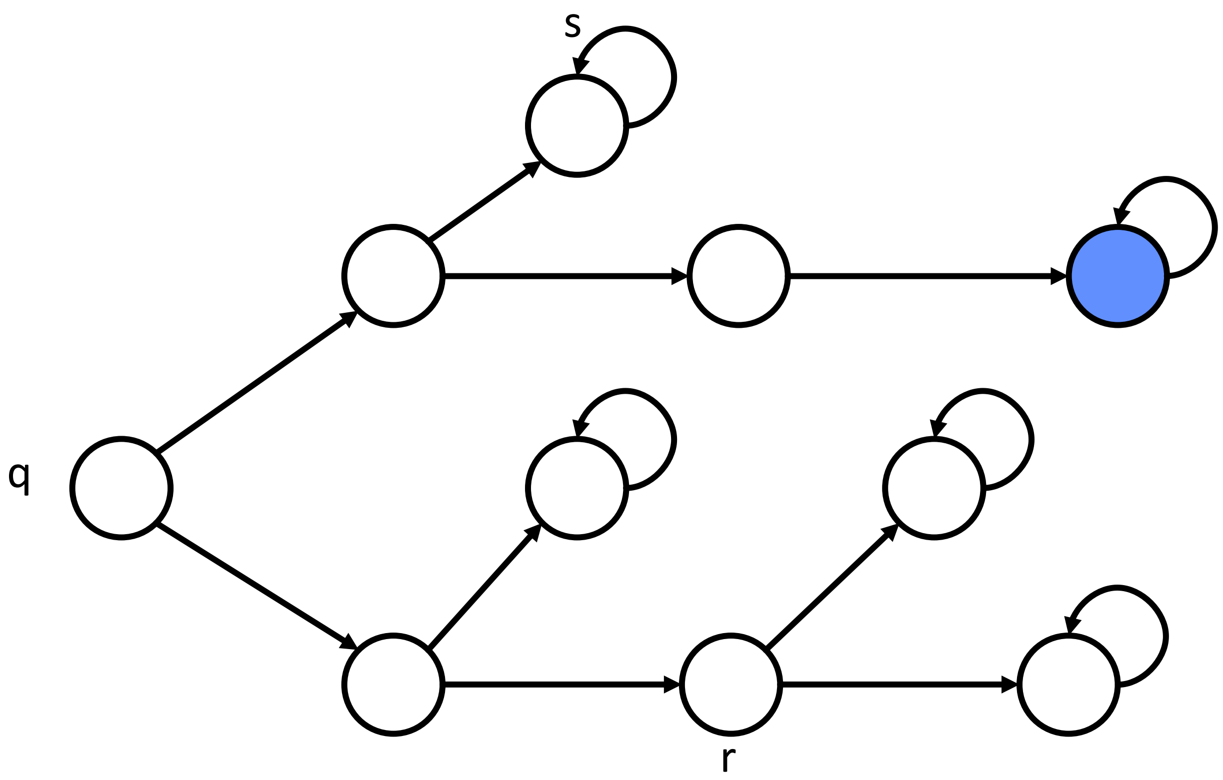
- AG p — I will like chocolate from now on, no matter what happens.
- EF p — It's possible I may like chocolate someday, at least for one day.
- AF EG p — There will be always sometime in the future (AF) that I may suddenly start liking chocolate for the rest of time (EG).
- EG AF p — This is a critical time in my life. Depending on what happens (E), it's possible that for the rest of time (G), there will always be some time in the future (AF) when I will like chocolate. However, if the wrong thing happens next, then all bets are off and there's no guarantee about whether I will ever like chocolate.
- p AU q — No matter what happens, I will like chocolate from now on. But when it gets warm outside, I don't know whether I still like it. And it will get warm outside someday.

Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

EF ϕ : "There exists a path along which at some state ϕ holds."



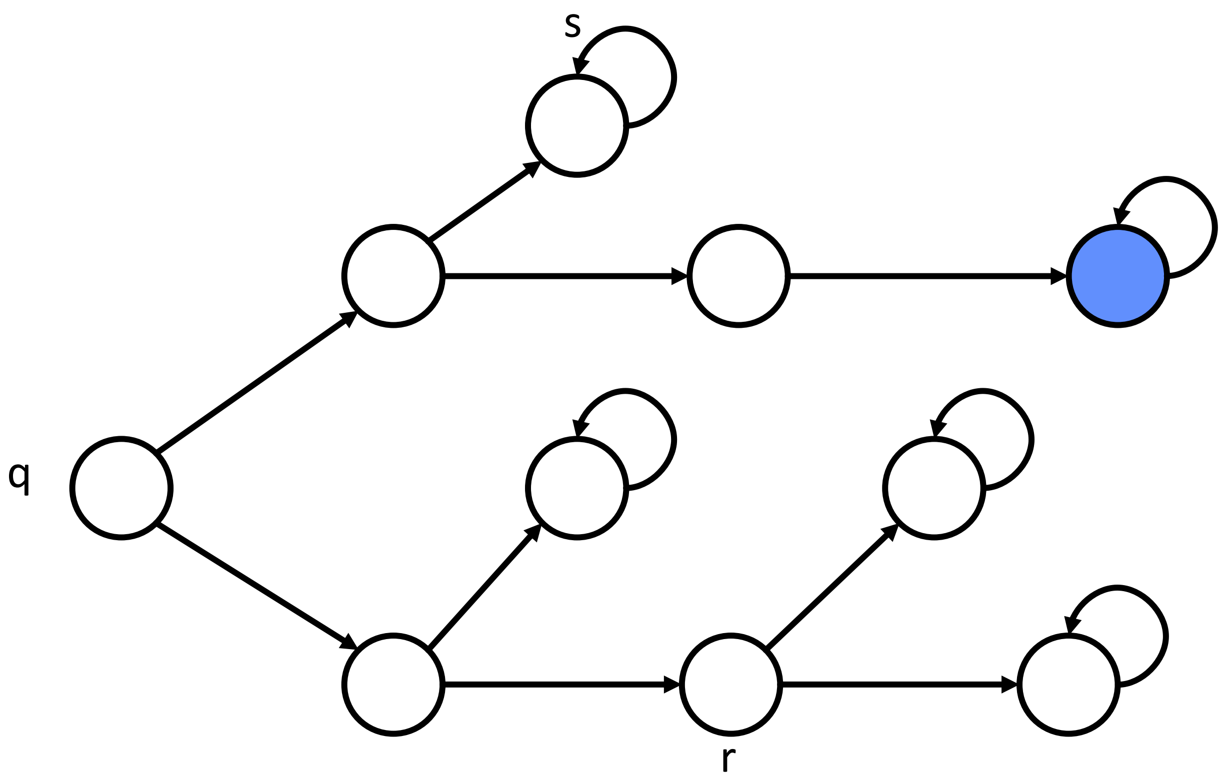
$\models \phi$

$q \models EF\ \phi$

$r \models ?$

$s \models ?$

EF ϕ : "There exists a path along which at some state ϕ holds."



$\models \phi$

$q \models EF\ \phi$

$r \not\models EF\ \phi$

$s \models ?$

Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
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$G\phi \rightarrow$ **G**lobally ϕ
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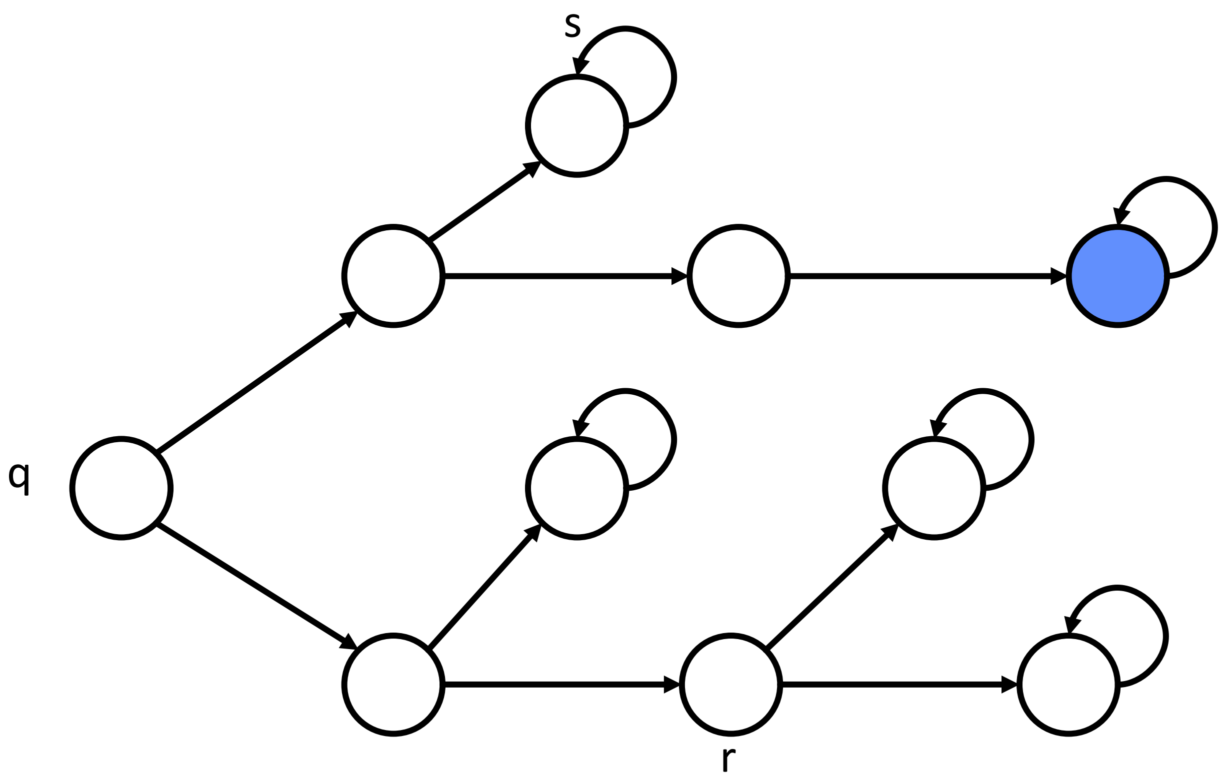


$\bullet \vDash \phi$

$q \vDash EF\ \phi$

$r \nvDash EF\ \phi$

$s \nvDash EF\ \phi$

Over paths:

$A\phi \rightarrow$ **A**ll ϕ

$E\phi \rightarrow$ **E**xists ϕ

Path-specific:

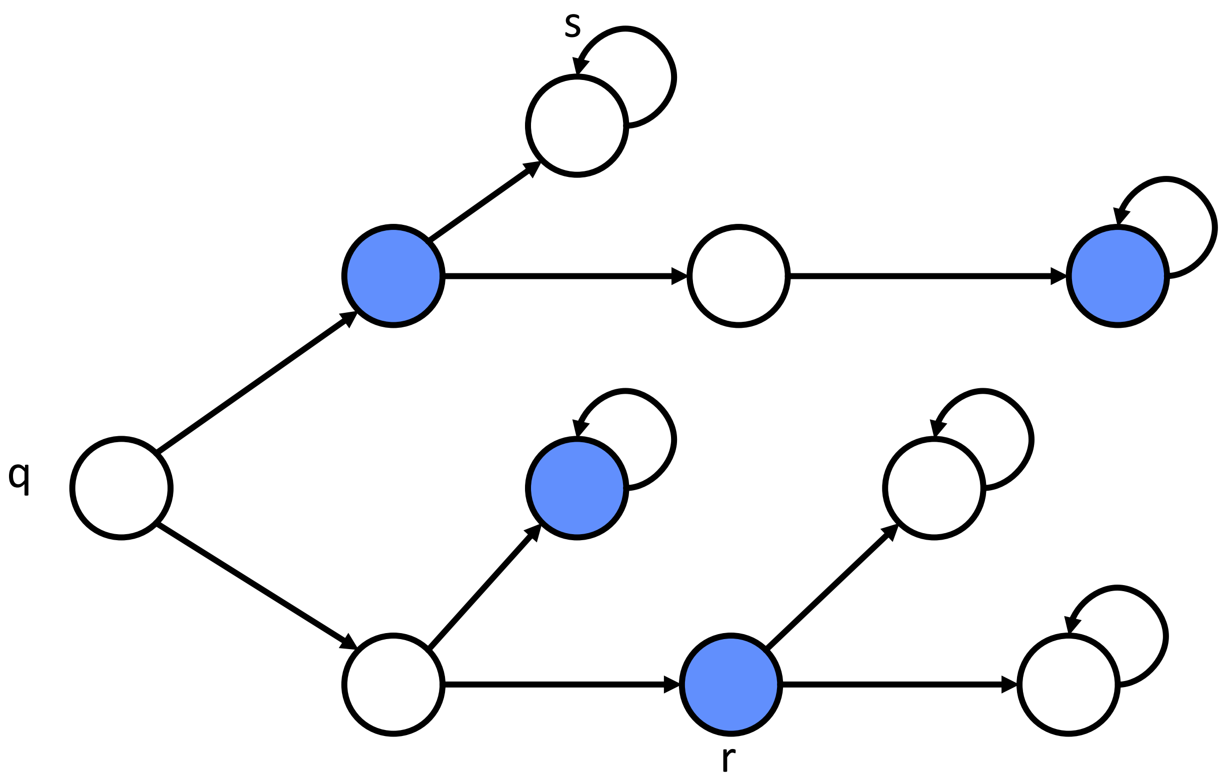
$X\phi \rightarrow$ Ne**X**t ϕ

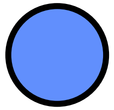
$F\phi \rightarrow$ **F**inally ϕ

$G\phi \rightarrow$ **G**lobally ϕ

$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

AF ϕ : "On all paths, at some state ϕ holds ."





$\vDash \phi$

$q \vDash AF\ \phi$

$r \vDash ?$

$s \vDash ?$

Over paths:

$A\phi \rightarrow$ **A**ll ϕ

$E\phi \rightarrow$ **E**xists ϕ

Path-specific:

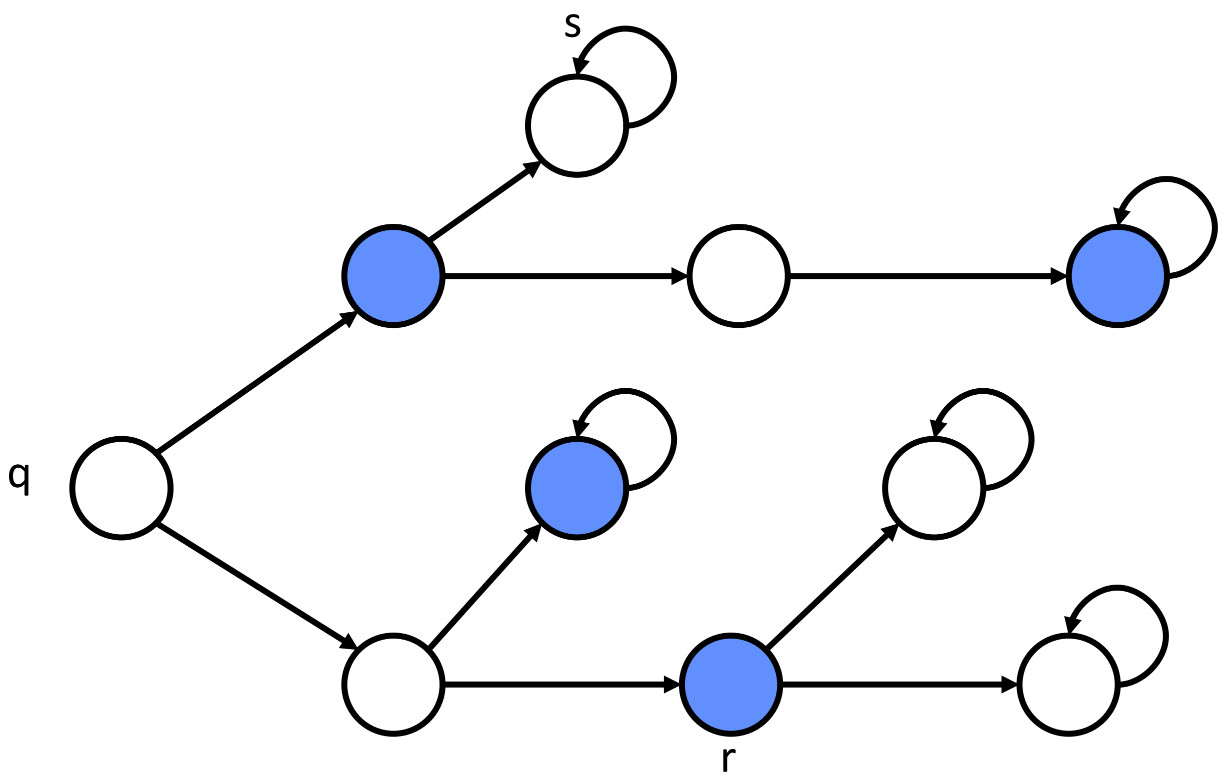
$X\phi \rightarrow$ Ne**X**t ϕ

$F\phi \rightarrow$ **F**inally ϕ

$G\phi \rightarrow$ **G**lobally ϕ

$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

AF ϕ : "On all paths, at some state ϕ holds ."



● $\vDash \phi$

$q \vDash AF\ \phi$

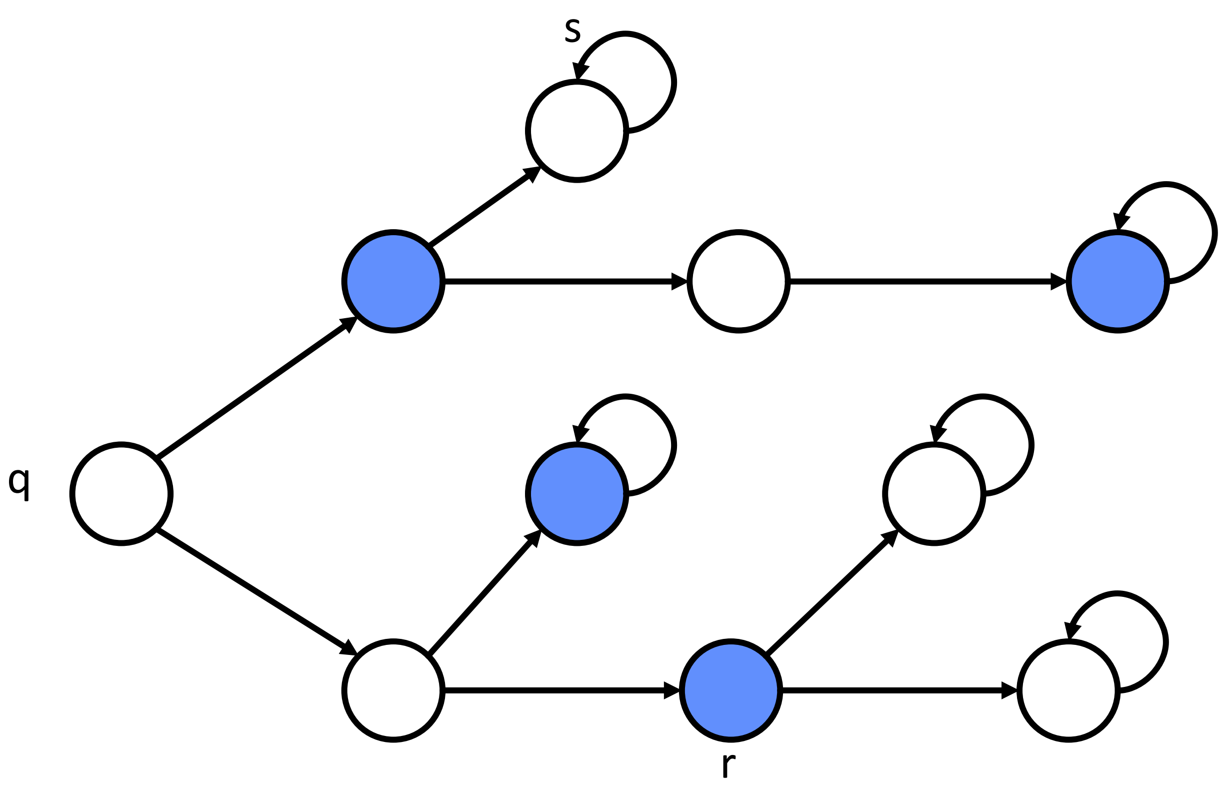
$r \vDash AF\ \phi$

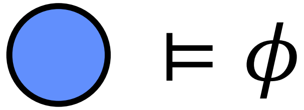
$s \vDash ?$

AF ϕ : "On all paths, at some state ϕ holds ."

Over paths:
$A\phi$ → **A**ll ϕ
$E\phi$ → **E**xists ϕ

Path-specific:
$X\phi$ → Ne**X**t ϕ
$F\phi$ → **F**inally ϕ
$G\phi$ → **G**lobally ϕ
$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2



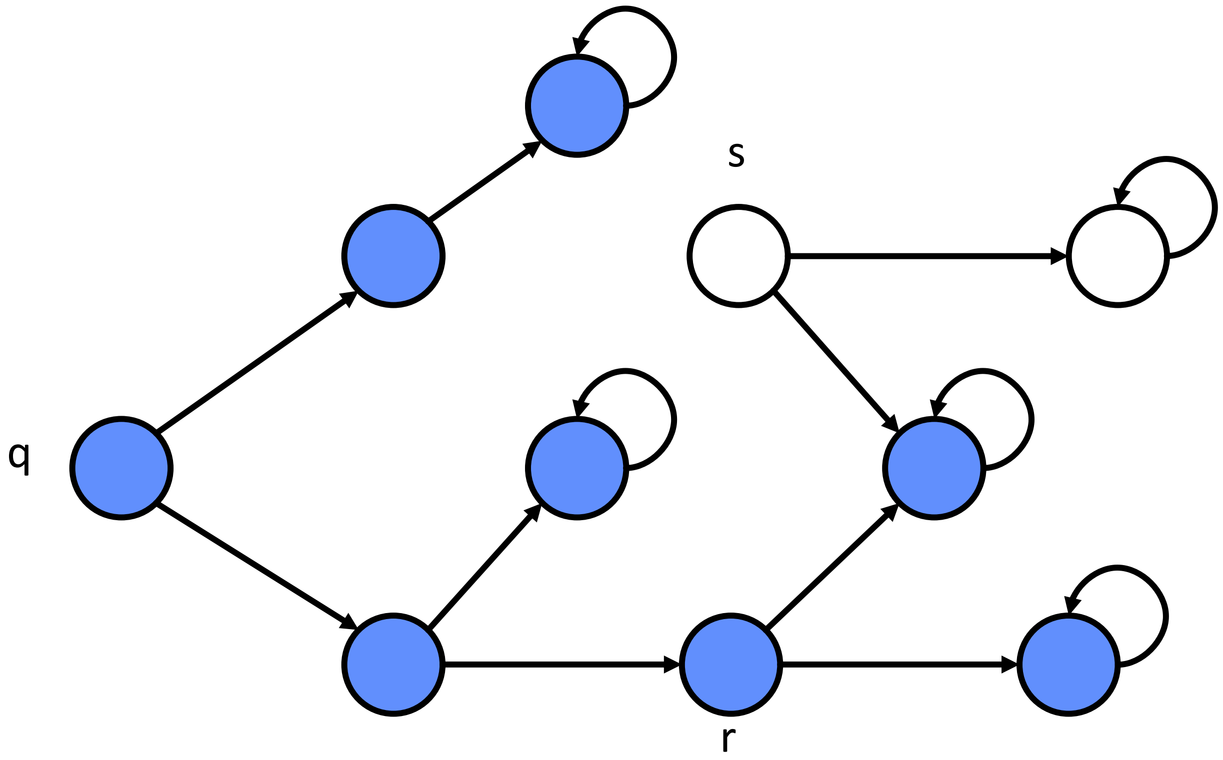


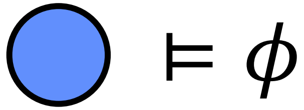
$q \models AF\ \phi$
$r \models AF\ \phi$
$s \not\models AF\ \phi$

Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

AG ϕ : "On all paths, for all states ϕ holds."





$q \models AG\ \phi$

$r \models ?$

$s \models ?$

Over paths:

$A\phi \rightarrow$ **All** ϕ

$E\phi \rightarrow$ **Exists** ϕ

Path-specific:

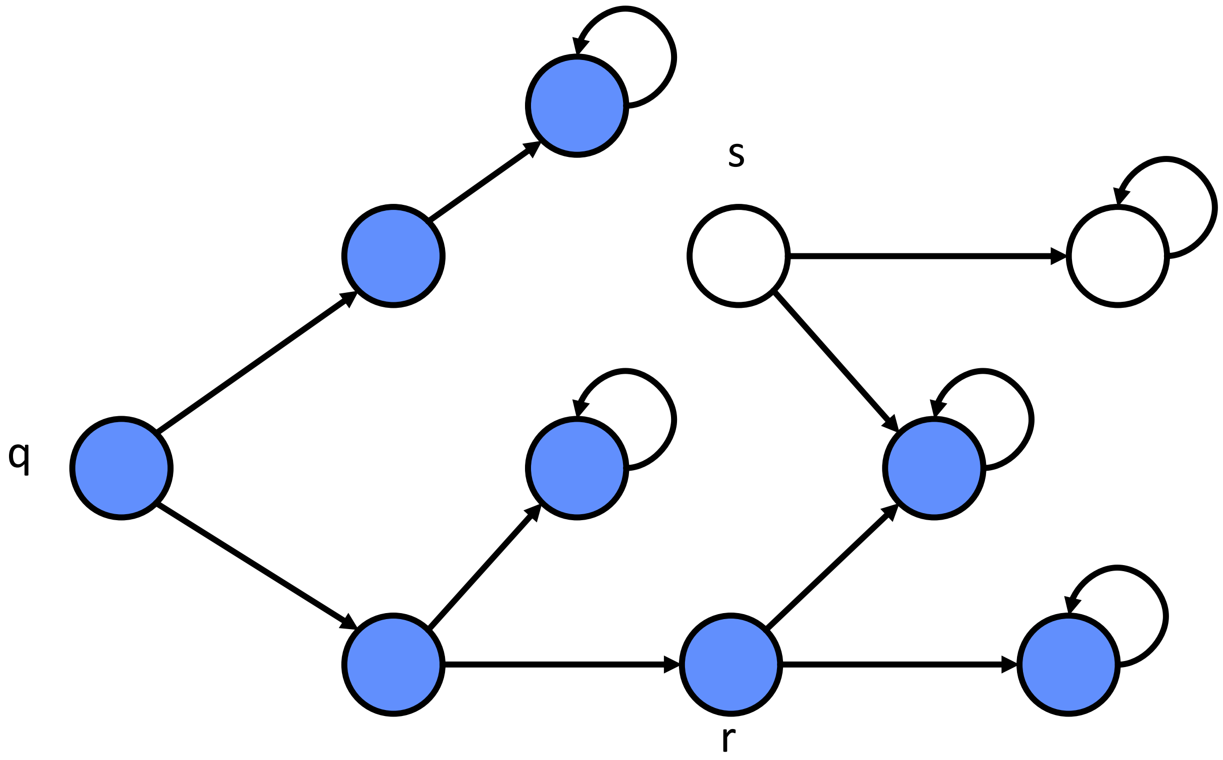
$X\phi \rightarrow$ Ne**X**t ϕ

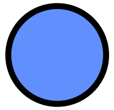
$F\phi \rightarrow$ **F**inally ϕ

$G\phi \rightarrow$ **G**lobally ϕ

$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

AG ϕ : "On all paths, for all states ϕ holds."





$\models \phi$

q $\models$ AG ϕ

r $\models$ AG ϕ

s $\models$?

Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
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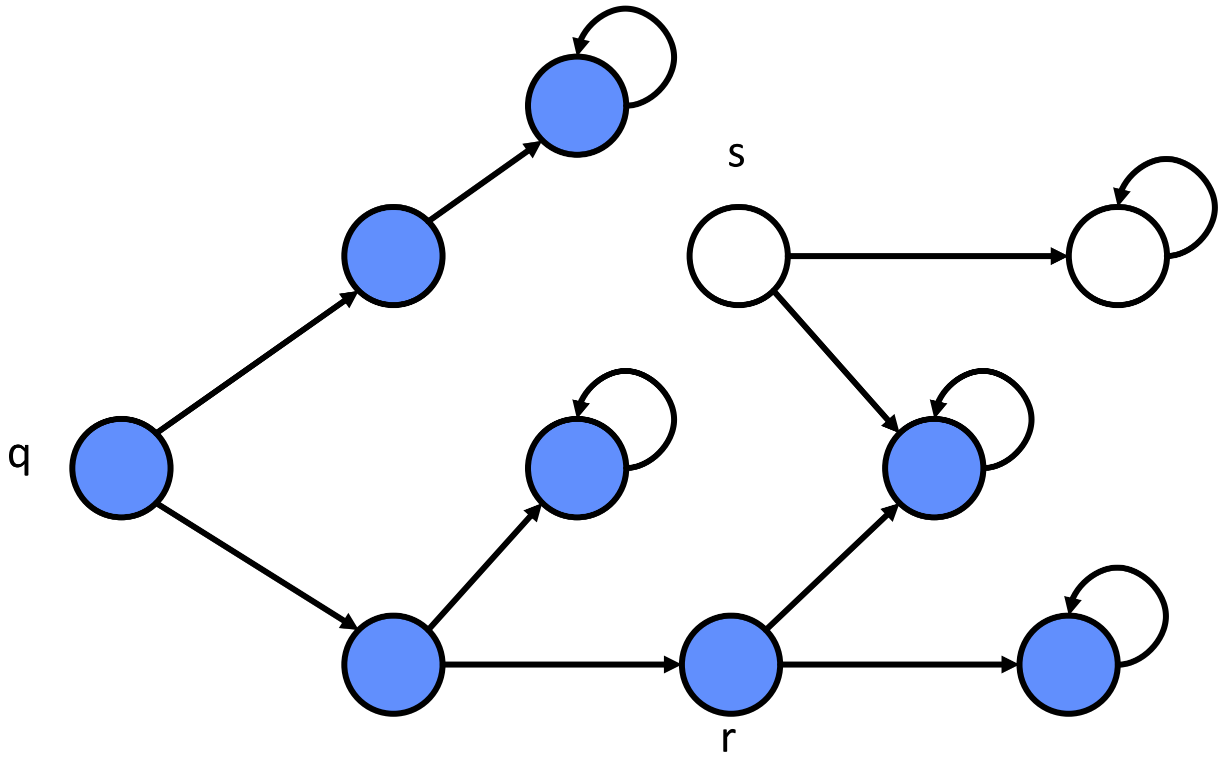

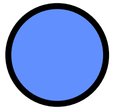

$\models \phi$

$q \models AG\ \phi$

$r \models AG\ \phi$

$s \not\models AG\ \phi$

Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
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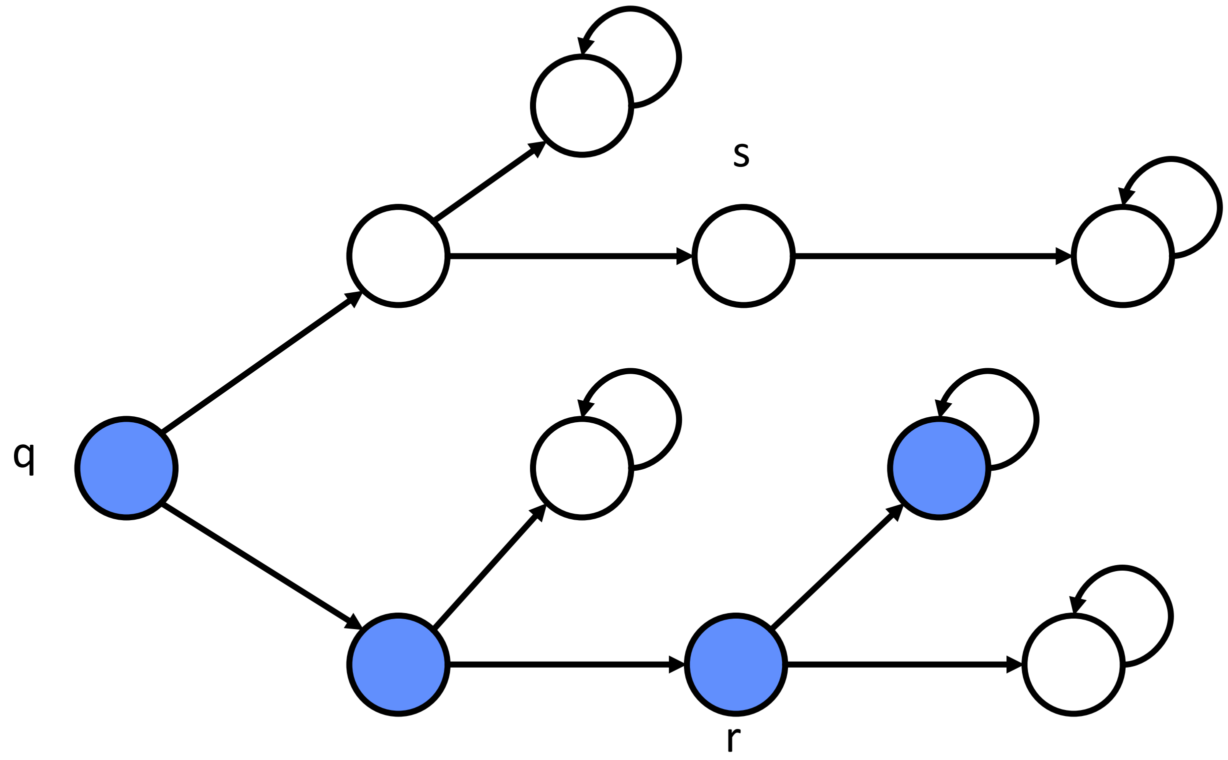
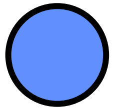
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

EG ϕ : "There exists a path along which for all states ϕ holds."





$q \models EG\ \phi$

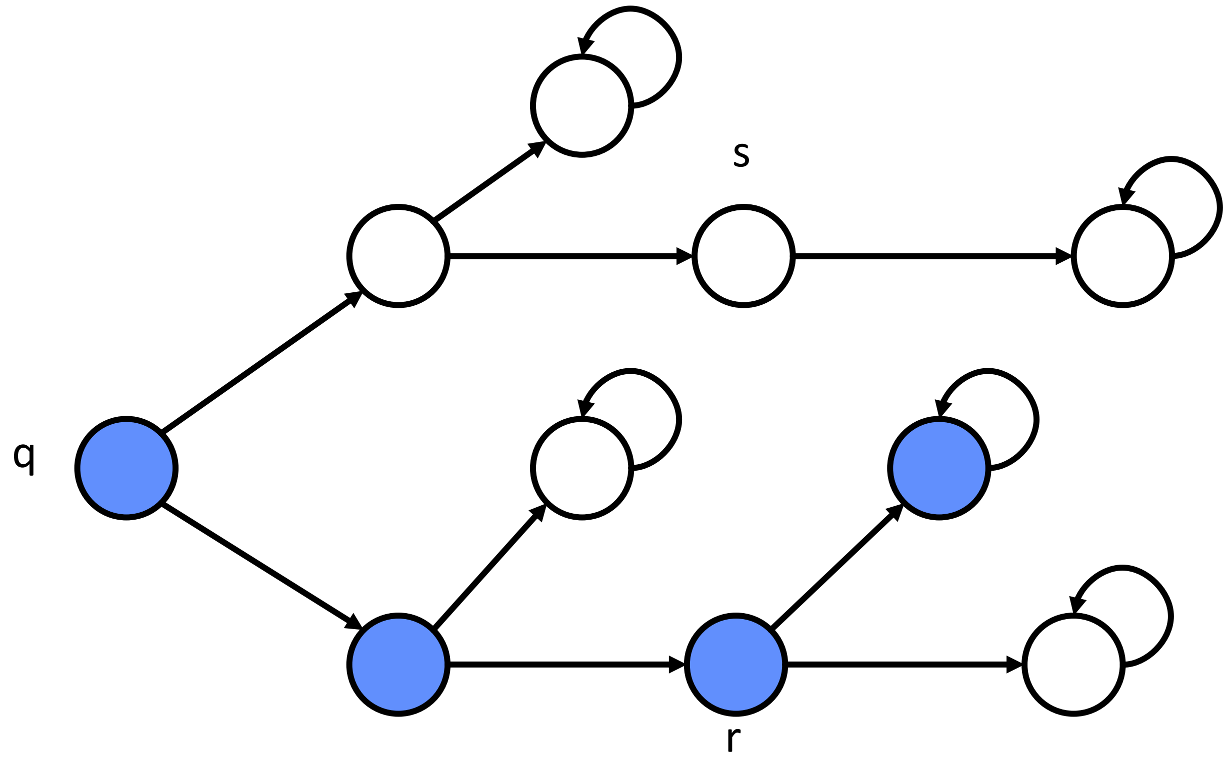
$r \models ?$

$s \models ?$

Over paths:
$A\phi \to$ **A**ll ϕ
$E\phi \to$ **E**xists ϕ

Path-specific:
$X\phi \to$ Ne**X**t ϕ
$F\phi \to$ **F**inally ϕ
$G\phi \to$ **G**lobally ϕ
$\phi_1 U \phi_2 \to \phi_1$ **U**ntil ϕ_2

EG ϕ : "There exists a path along which for all states ϕ holds."



$\vDash \phi$

$q \vDash EG\ \phi$

$r \vDash EG\ \phi$

$s \vDash$?

EG ϕ : "There exists a path along which for all states ϕ holds."

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
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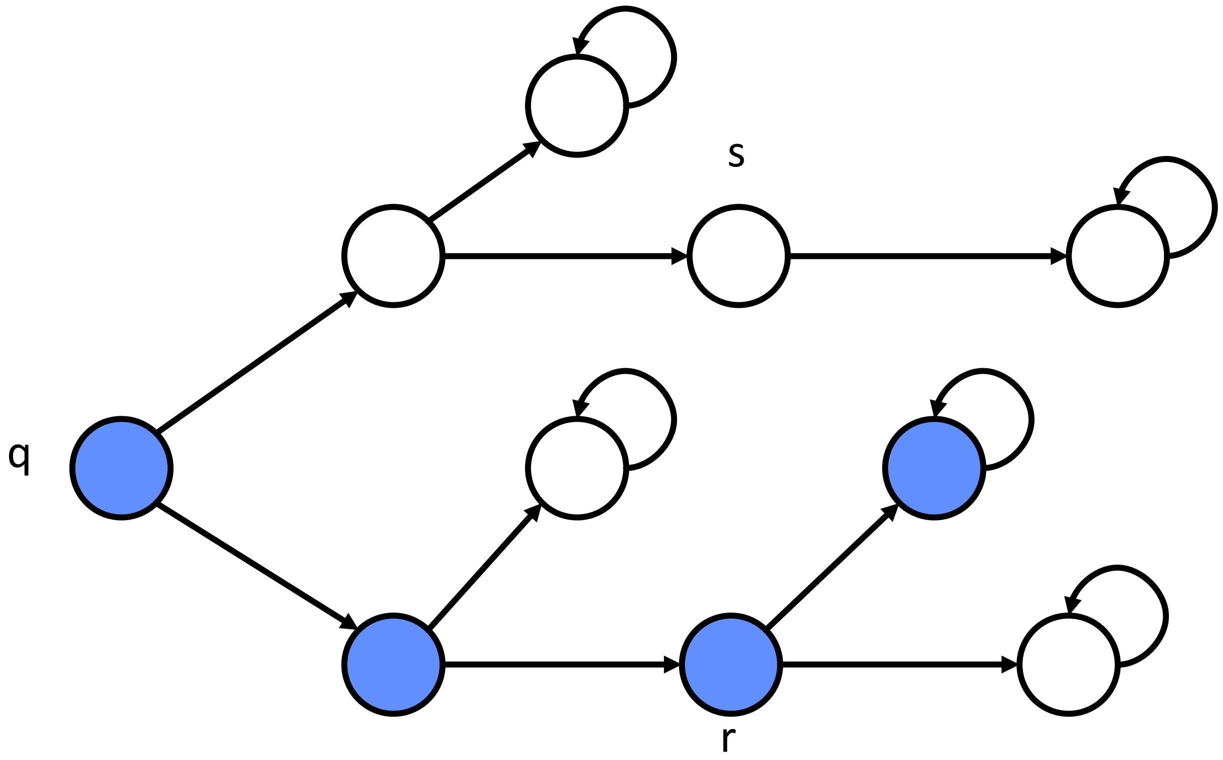


(blue node) $\vDash \phi$

q $\vDash$ EG ϕ

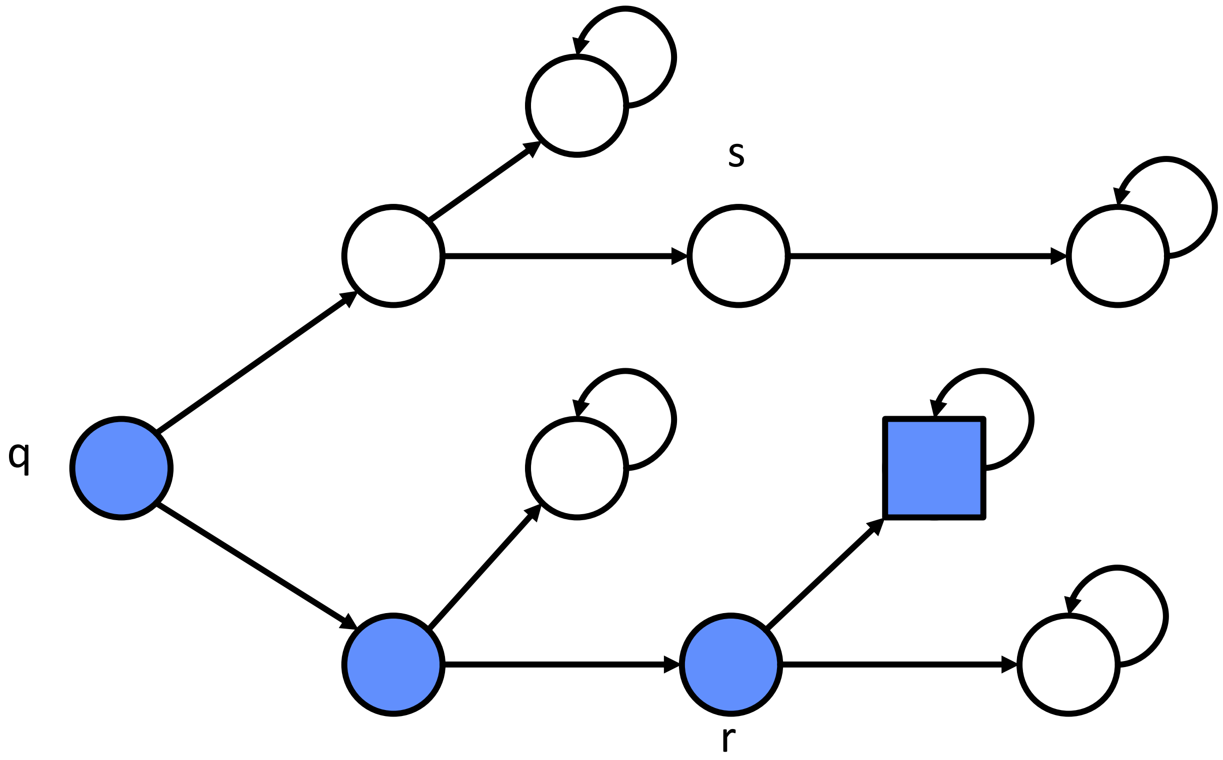
r $\vDash$ EG ϕ

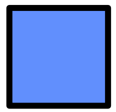
s $\nvDash$ EG ϕ

Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

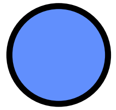
Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

$\phi EU\Psi$: "There exists a path along which ϕ holds until Ψ holds."





$\vDash \Psi$



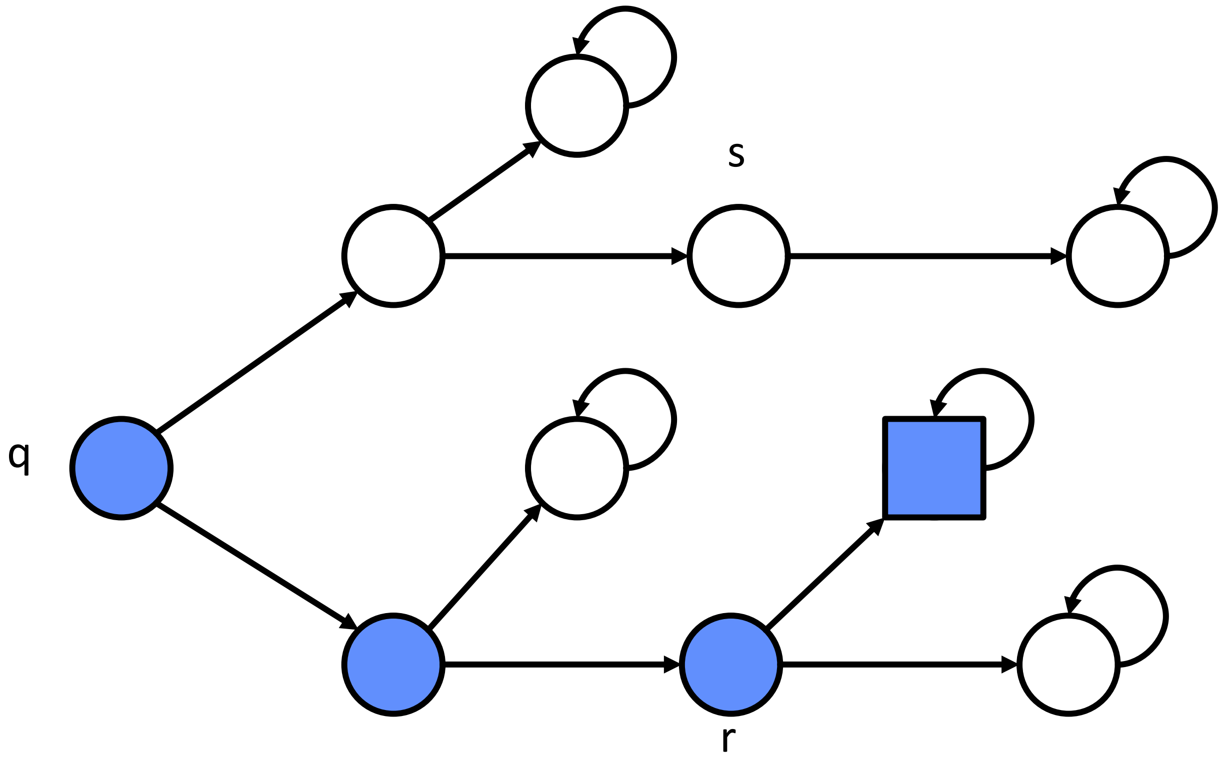
$\vDash \phi$

$q \vDash \phi EU\Psi$
$r \vDash ?$
$s \vDash ?$

Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

$\phi EU\Psi$: "There exists a path along which ϕ holds until Ψ holds."



$\blacksquare \models \Psi$

$\bullet \models \phi$

$q \models \phi EU\Psi$

$r \models \phi EU\Psi$

$s \models$?

$\phi EU\Psi$: "There exists a path along which ϕ holds until Ψ holds."

Over paths:

$A\phi \rightarrow$ **A**ll ϕ

$E\phi \rightarrow$ **E**xists ϕ

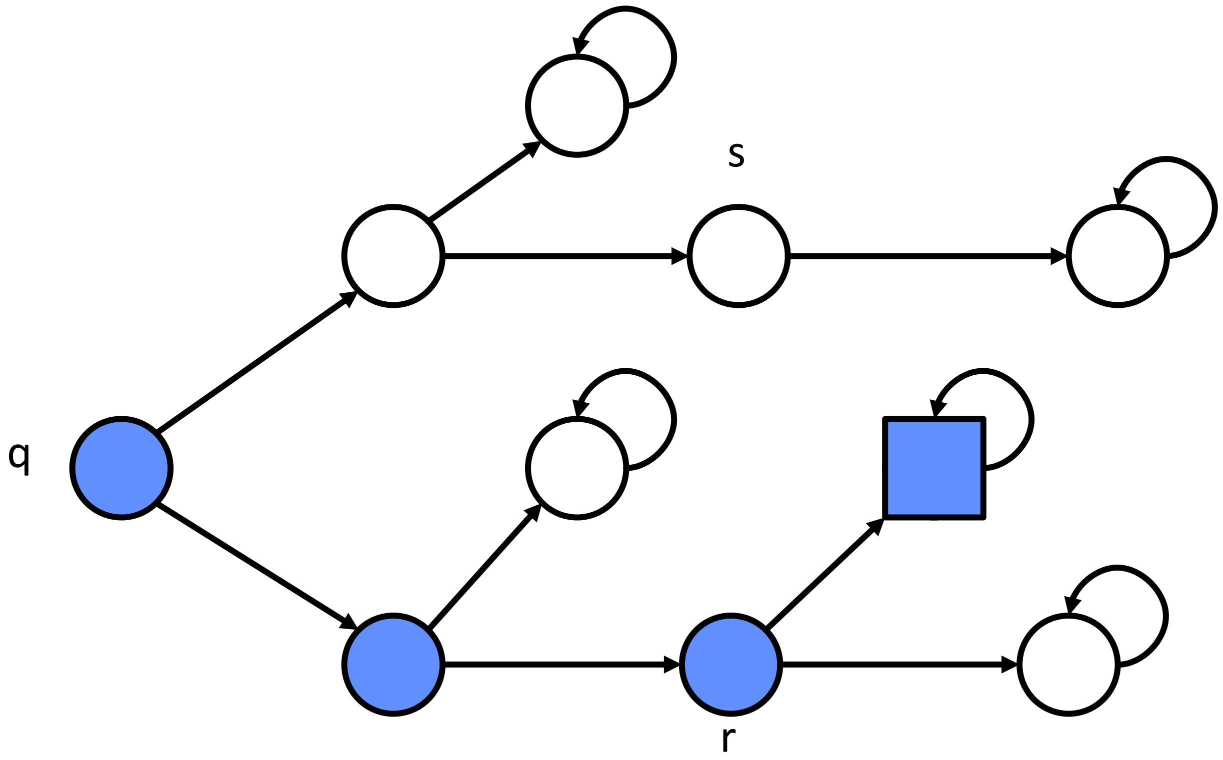
Path-specific:

$X\phi \rightarrow$ Ne**X**t ϕ

$F\phi \rightarrow$ **F**inally ϕ

$G\phi \rightarrow$ **G**lobally ϕ

$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2



■ $\vDash \Psi$

● $\vDash \phi$

$q \vDash \phi EU\Psi$

$r \vDash \phi EU\Psi$

$s \nvDash \phi EU\Psi$

Over paths:

$A\phi \rightarrow$ **All** ϕ

$E\phi \rightarrow$ **Exists** ϕ

Path-specific:

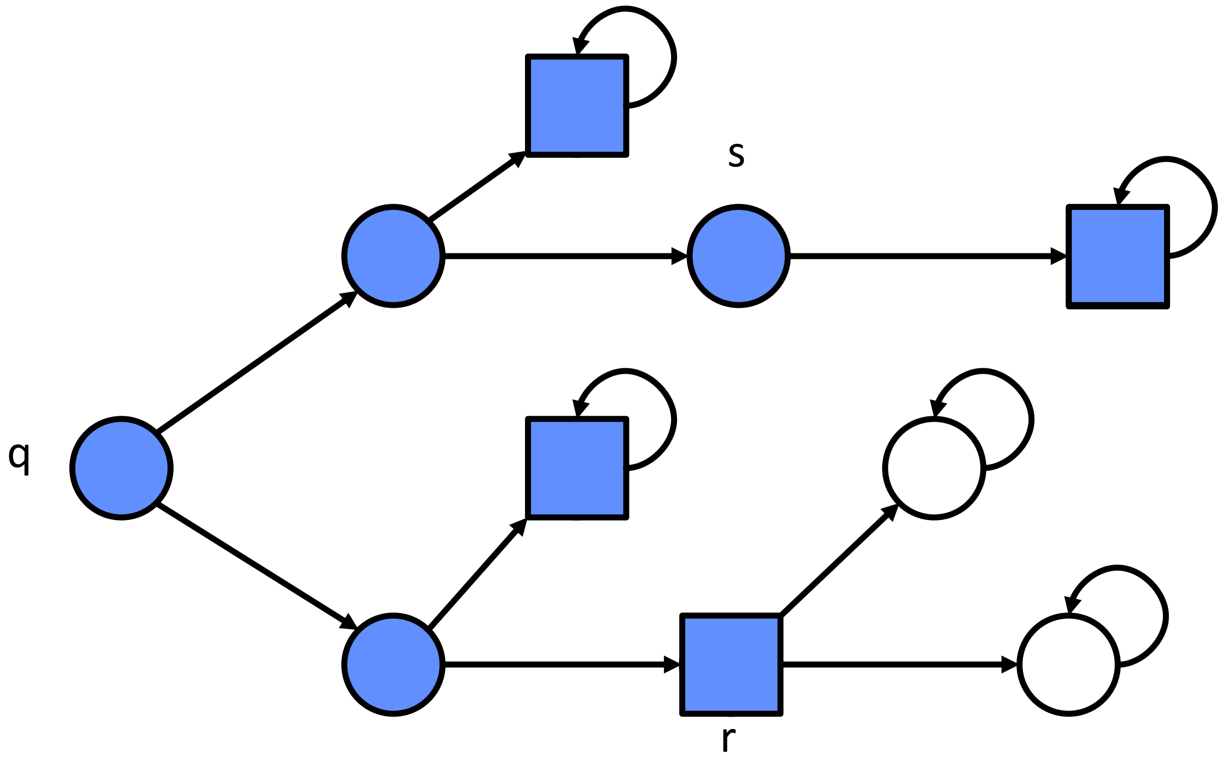
$X\phi \rightarrow$ Ne**X**t ϕ

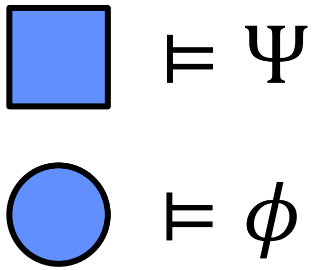
$F\phi \rightarrow$ **F**inally ϕ

$G\phi \rightarrow$ **G**lobally ϕ

$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

$\phi AU\Psi$: "On all paths, ϕ holds until Ψ holds."





$q \vDash \phi AU\Psi$

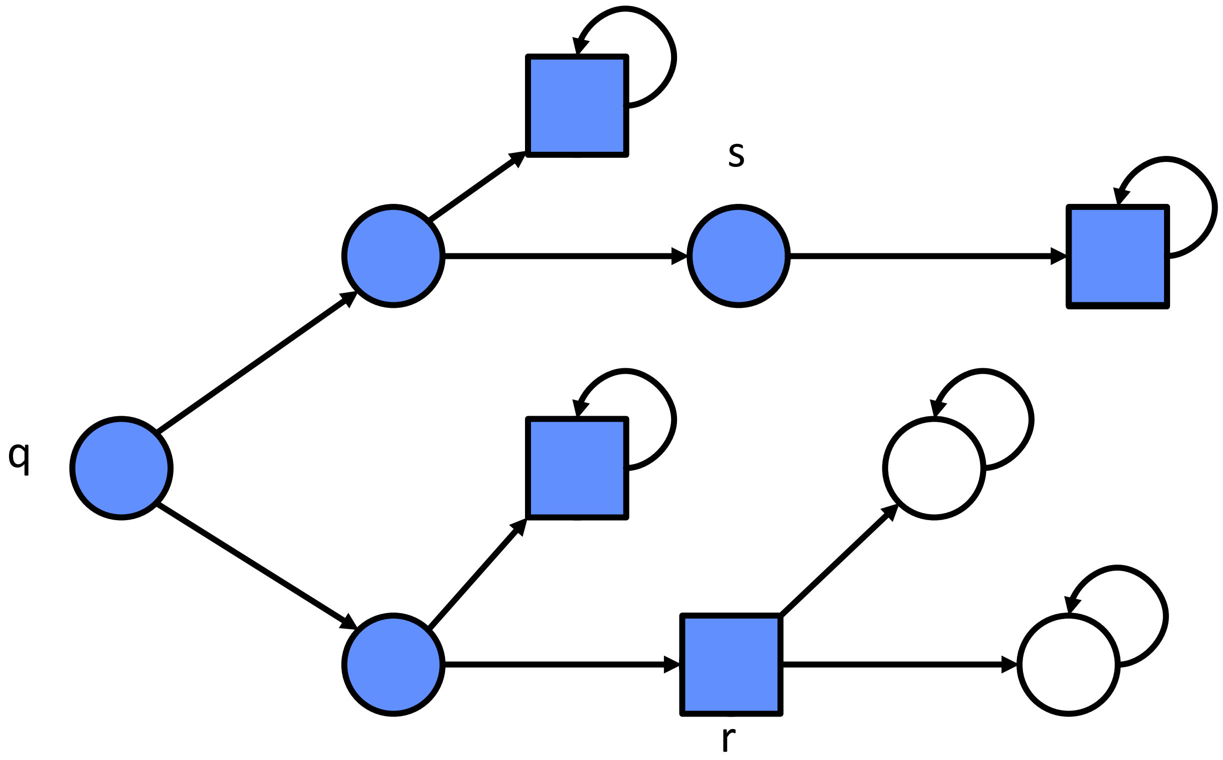
$r \vDash$?

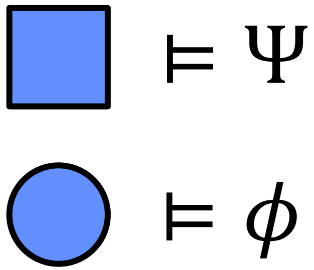
$s \vDash$?

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

$\phi AU\Psi$: "On all paths, ϕ holds until Ψ holds."





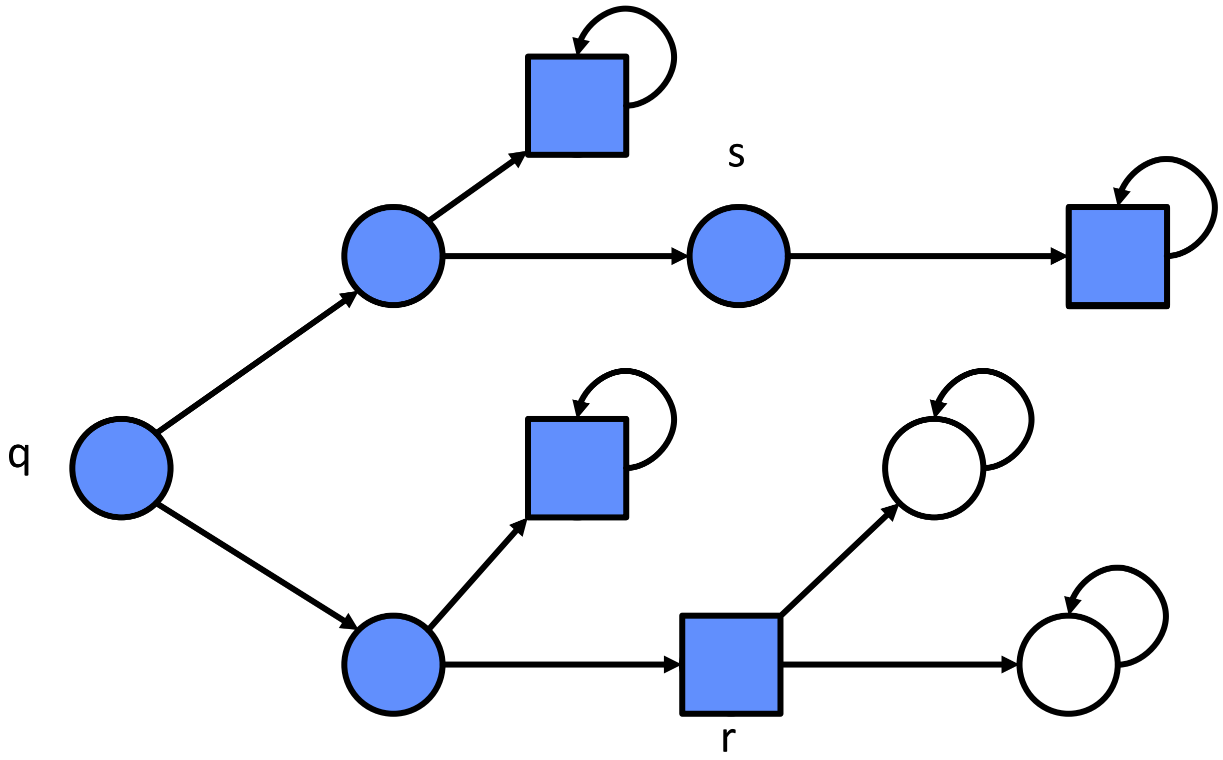
$q \models \phi AU\Psi$

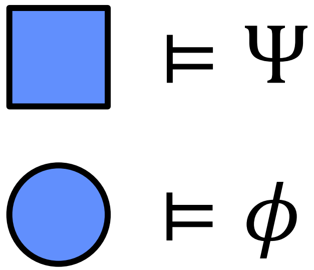
$r \models \phi AU\Psi$

$s \models ?$

$\phi \mathrm{AU} \Psi$: "On all paths, ϕ holds until Ψ holds."

Over paths:	Path-specific:
$A\phi \rightarrow$ **A**ll ϕ	$X\phi \rightarrow$ Ne**X**t ϕ
$E\phi \rightarrow$ **E**xists ϕ	$F\phi \rightarrow$ **F**inally ϕ
	$G\phi \rightarrow$ **G**lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2





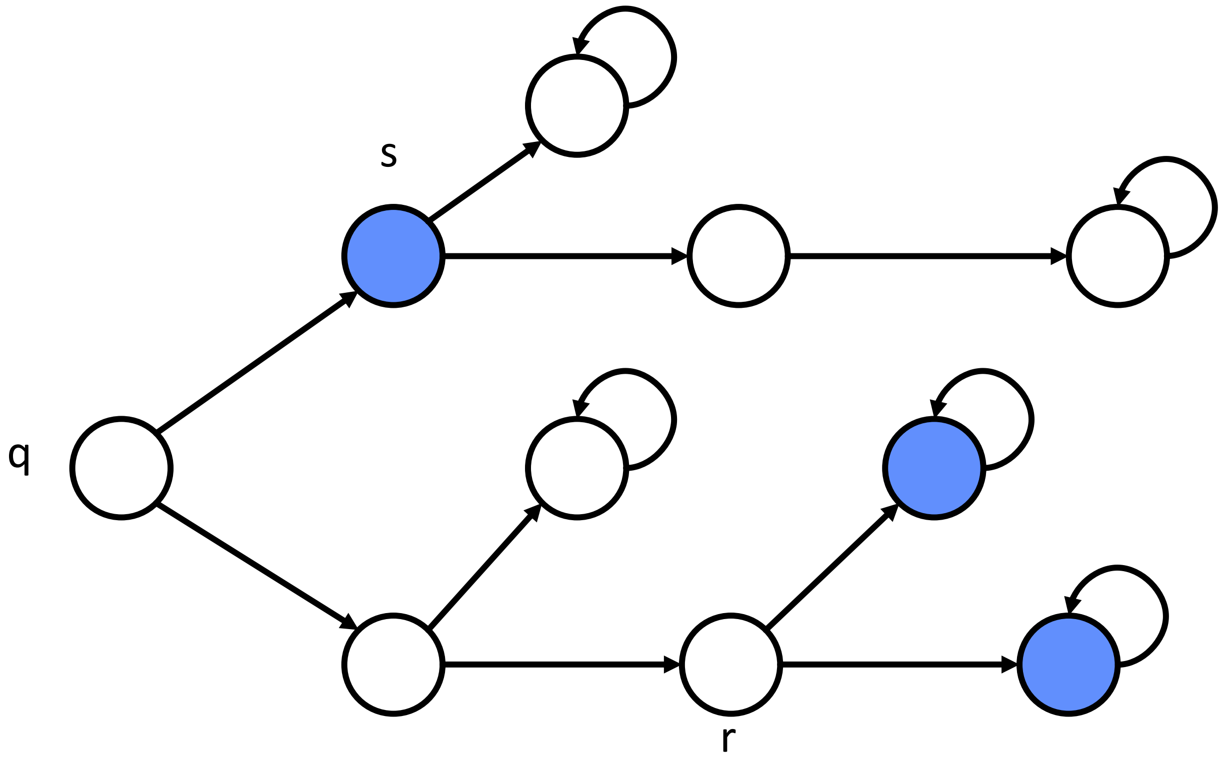
$q \models \phi \mathrm{AU} \Psi$

$r \models \phi \mathrm{AU} \Psi$

$s \models \phi \mathrm{AU} \Psi$

Over paths:	Path-specific:
$A\phi \rightarrow$ **All** ϕ	$X\phi \rightarrow$ Ne**X**t ϕ
$E\phi \rightarrow$ **Exists** ϕ	$F\phi \rightarrow$ **F**inally ϕ
	$G\phi \rightarrow$ **G**lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

$EX\phi$: "There exists a path along which the next state satisfies ϕ."



$\bigcirc \vDash \phi$

$q \vDash EX\phi$

$r \vDash ?$

$s \vDash ?$

Over paths:

$A\phi \rightarrow$ **All** ϕ

$E\phi \rightarrow$ **Exists** ϕ

Path-specific:

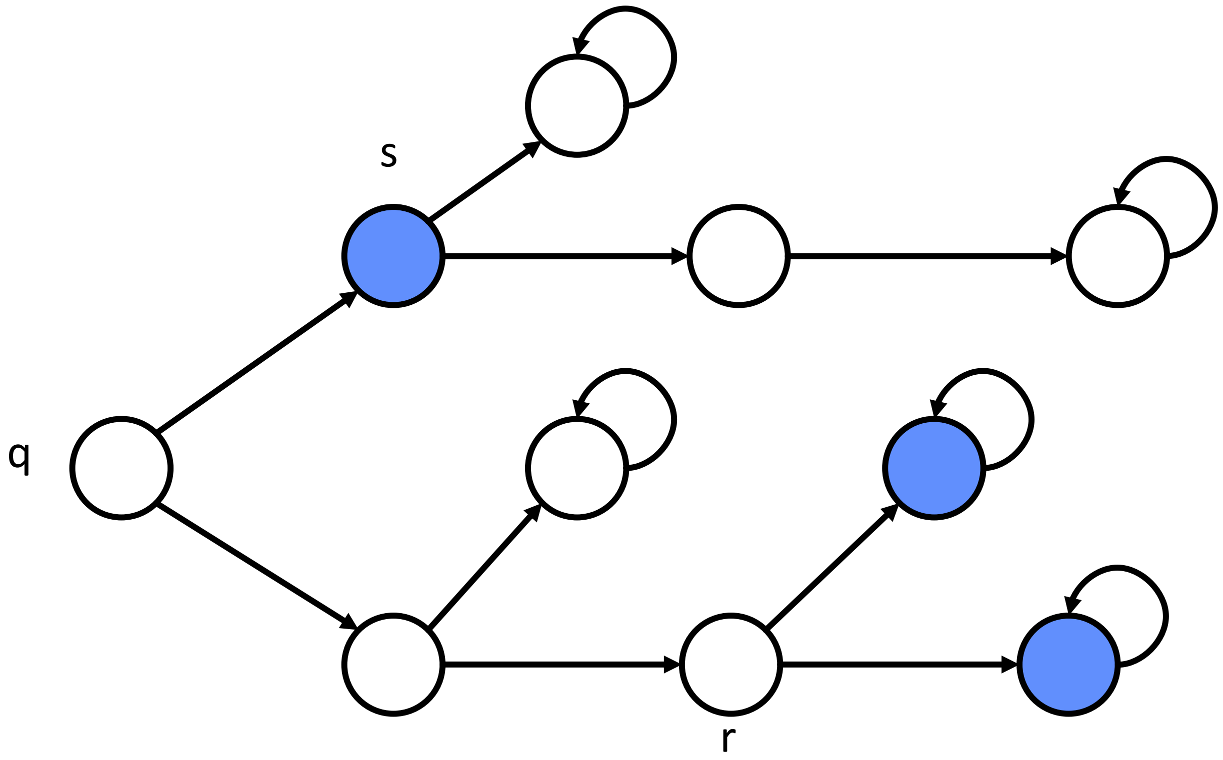
$X\phi \rightarrow$ Ne**X**t ϕ

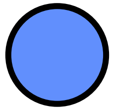
$F\phi \rightarrow$ **F**inally ϕ

$G\phi \rightarrow$ **G**lobally ϕ

$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

$EX\phi$: "There exists a path along which the next state satisfies ϕ."



 $\models \phi$

$q \models EX\phi$

$r \models EX\phi$

$s \models ?$

EXϕ : "There exists a path along which the next state satisfies ϕ."

Over paths:

Aϕ → **A**ll ϕ

Eϕ → **E**xists ϕ

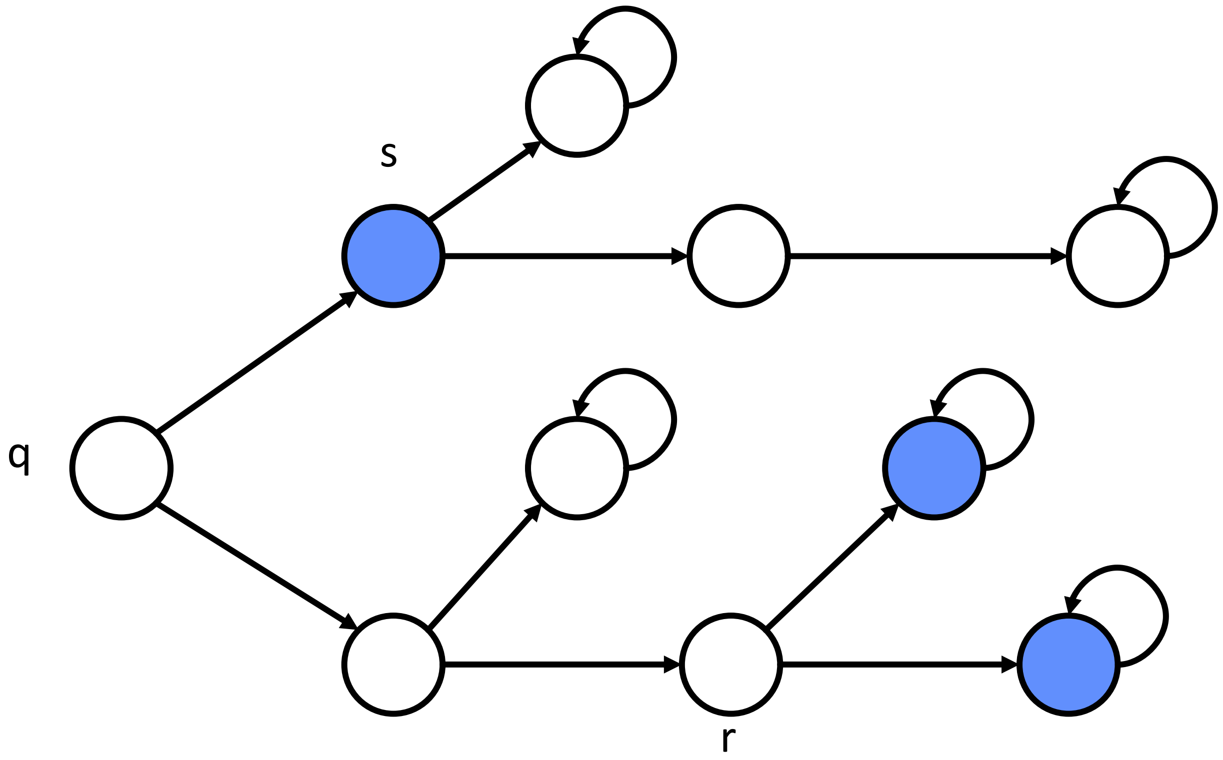
Path-specific:

Xϕ → Ne**X**t ϕ

Fϕ → **F**inally ϕ

Gϕ → **G**lobally ϕ

$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2



● $\models \phi$

q $\models$ EXϕ

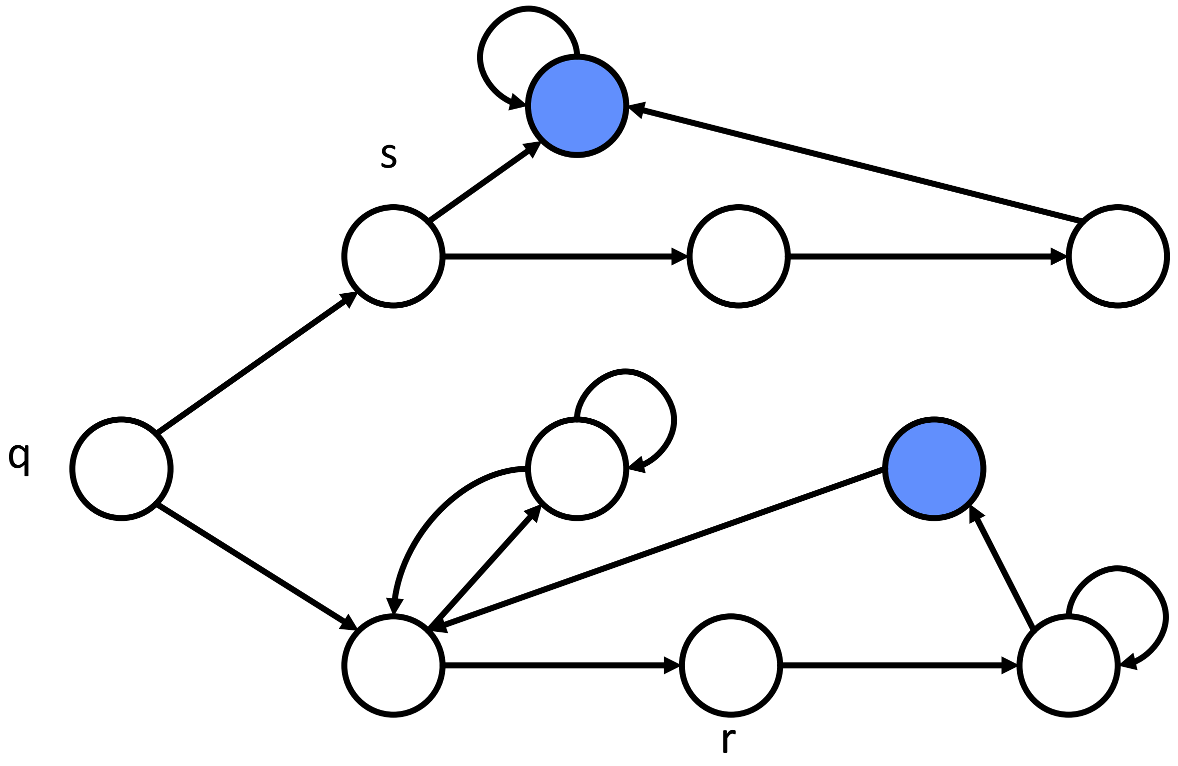
r $\models$ EXϕ

s $\not\models$ EXϕ

Over paths:
$A\phi$ → **A**ll ϕ
$E\phi$ → **E**xists ϕ

Path-specific:
$X\phi$ → Ne**X**t ϕ
$F\phi$ → **F**inally ϕ
$G\phi$ → **G**lobally ϕ
$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

AG EF ϕ : "On all paths and for all states, there exists a path along which at some state ϕ holds."



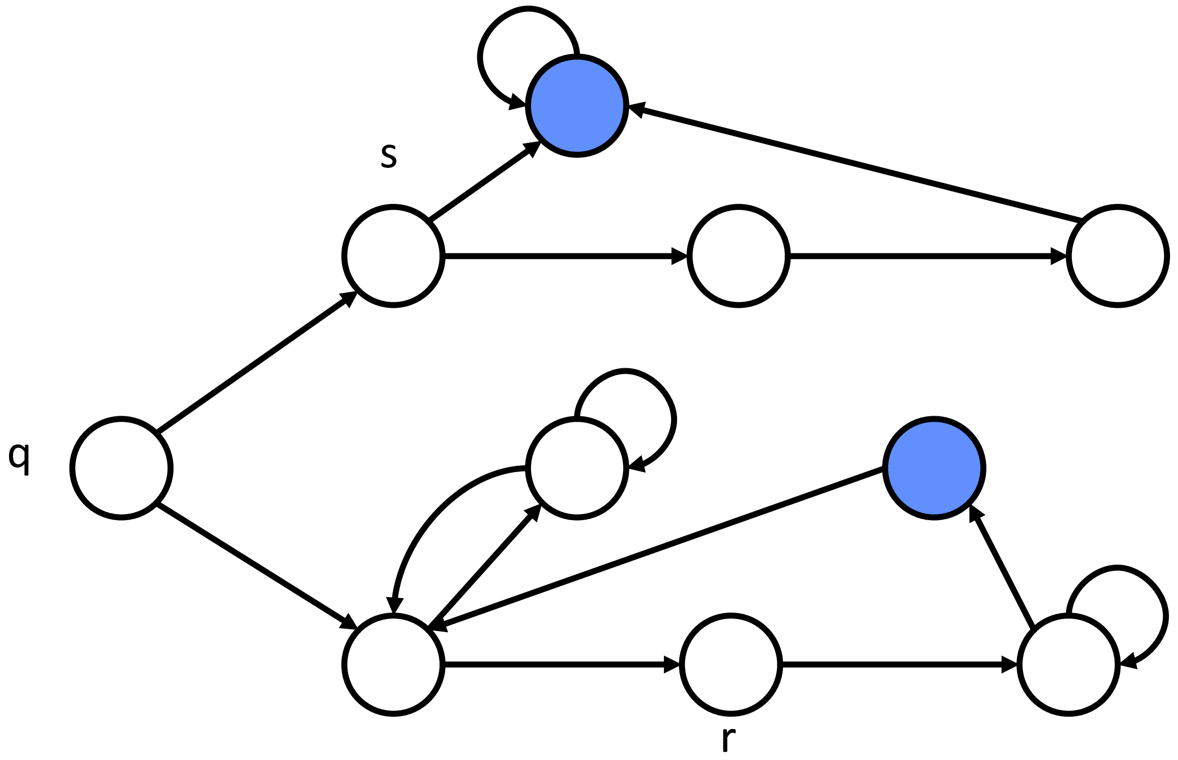
● $\models \phi$

$q \models$ AG EF ϕ
$r \models$?
$s \models$?

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

AG EF ϕ : "On all paths and for all states, there exists a path along which at some state ϕ holds."



(blue node) $\vDash \phi$

q $\vDash$ AG EF ϕ

r $\vDash$ AG EF ϕ

s $\vDash$?

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
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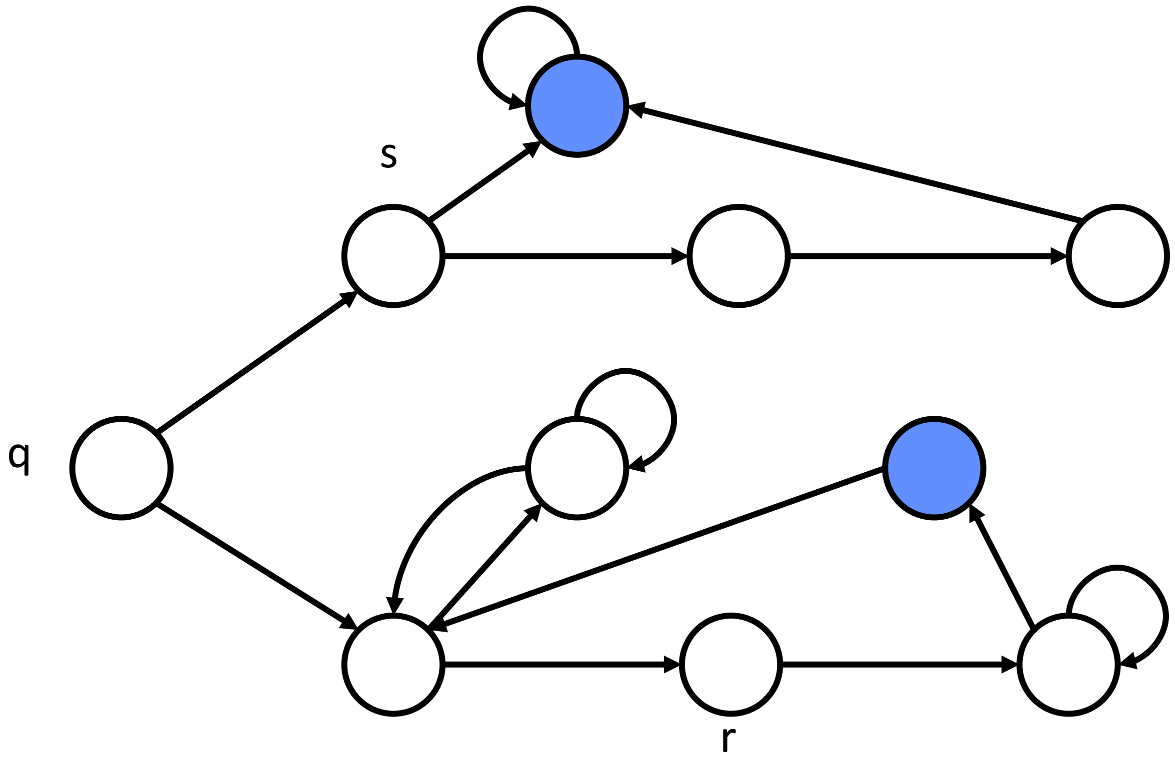
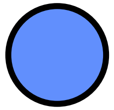




$\vDash \phi$

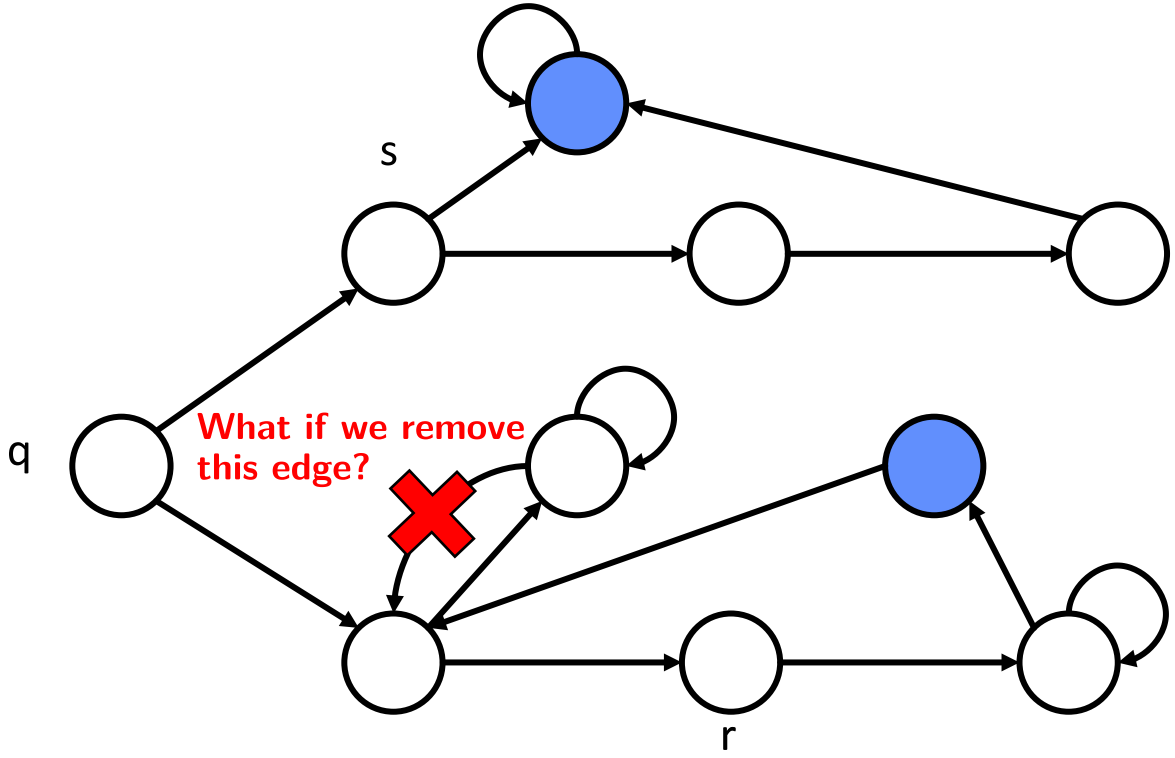
$q \vDash AG\ EF\ \phi$

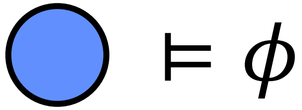
$r \vDash AG\ EF\ \phi$

$s \vDash AG\ EF\ \phi$

AG EF ϕ : "On all paths and for all states, there exists a path along which at some state ϕ holds."

Over paths:	Path-specific:
$A\phi \rightarrow$ **A**ll ϕ	$X\phi \rightarrow$ Ne**X**t ϕ
$E\phi \rightarrow$ **E**xists ϕ	$F\phi \rightarrow$ **F**inally ϕ
	$G\phi \rightarrow$ **G**lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2





$q \vDash ?$

$r \vDash ?$

$s \vDash ?$

AG EF ϕ : "On all paths and for all states, there exists a path along which at some state ϕ holds."

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
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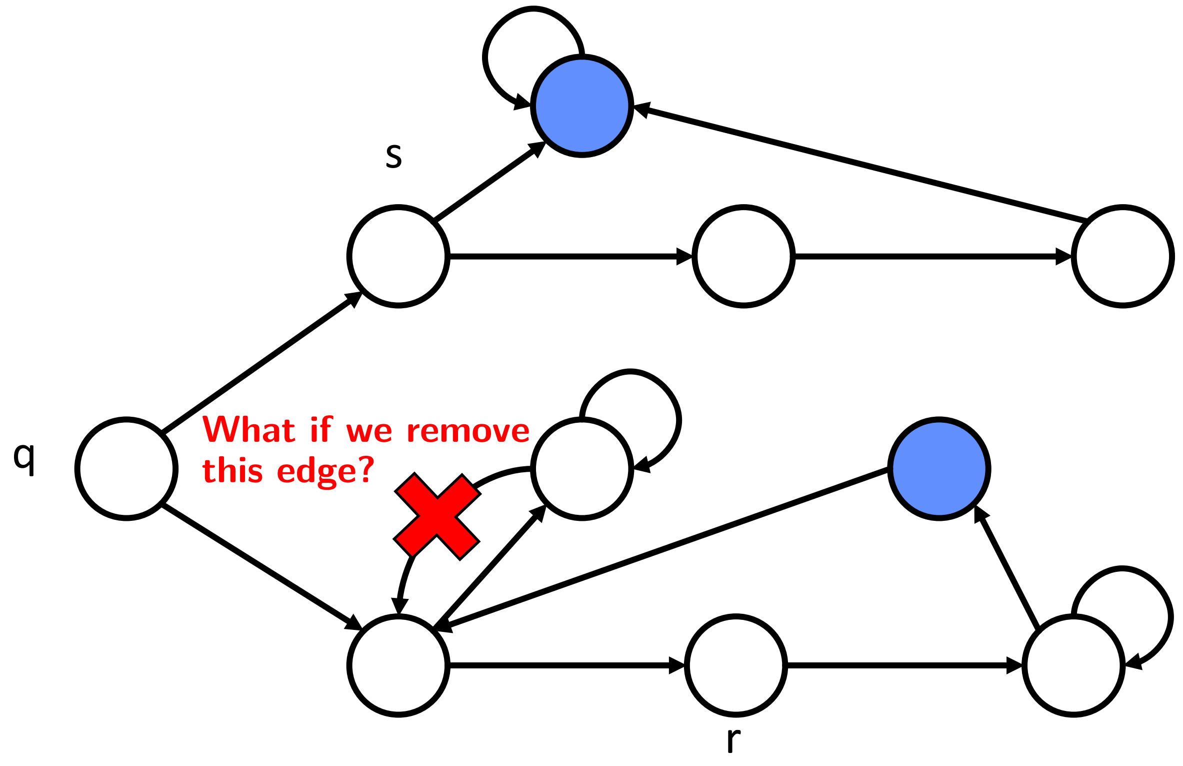
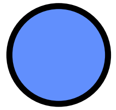


 $\vDash \phi$

q $\nvDash$ AG EF ϕ

r $\nvDash$ AG EF ϕ

s $\vDash$ AG EF ϕ

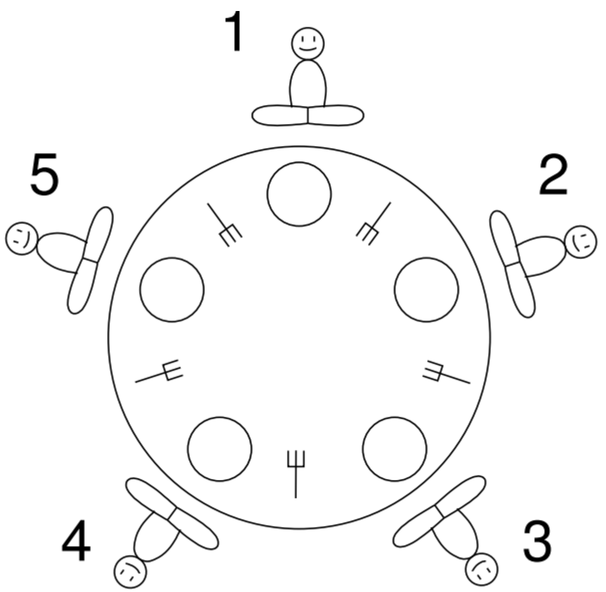
Over paths:	Path-specific:
$A\phi$ → **A**ll ϕ	$X\phi$ → Ne**X**t ϕ
$E\phi$ → **E**xists ϕ	$F\phi$ → **F**inally ϕ
	$G\phi$ → **G**lobally ϕ
	$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

Specifying using CTL formula

Famous problem

Dining Philosophers

- Five philosophers are sitting around a table, taking turns at thinking and eating.
- Each needs two forks to eat.
- They put down forks. only once they have eaten.
- There are only five forks.



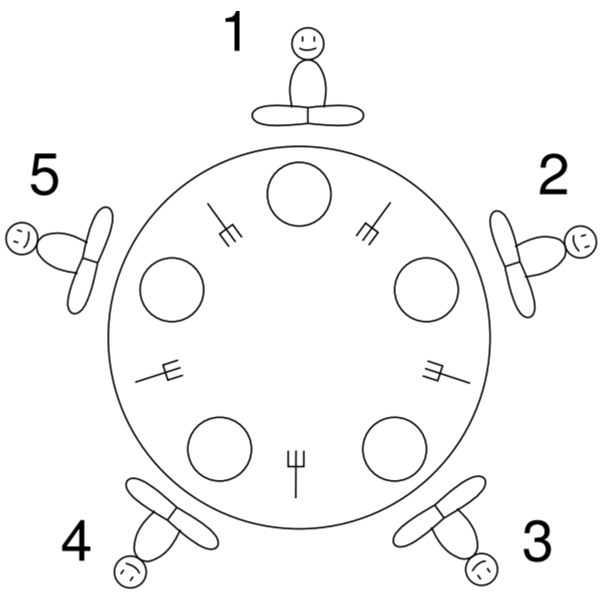
Atomic proposition

e_i : Philosopher i is currently eating.

Over paths:	Path-specific:
$A\phi \rightarrow$ **A**ll ϕ	$X\phi \rightarrow$ Ne**X**t ϕ
$E\phi \rightarrow$ **E**xists ϕ	$F\phi \rightarrow$ **F**inally ϕ
	$G\phi \rightarrow$ **G**lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Specifying using CTL formula

- "Philosophers 1 and 4 will never eat at the same time."
- "Every philosopher will get infinitely many turns to eat."
- "Philosopher 2 will be the first to eat."



Specifying using CTL formula

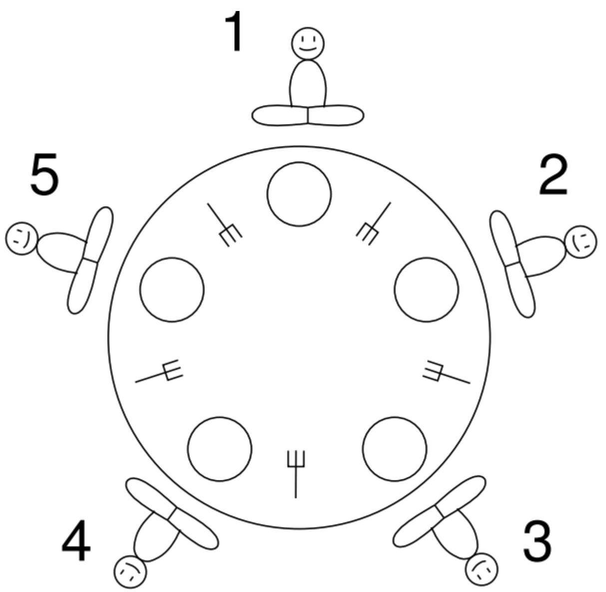
Over paths:	Path-specific:
$A\phi \rightarrow$ **A**ll ϕ	$X\phi \rightarrow$ Ne**X**t ϕ
$E\phi \rightarrow$ **E**xists ϕ	$F\phi \rightarrow$ **F**inally ϕ
	$G\phi \rightarrow$ **G**lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

- "Philosophers 1 and 4 will never eat at the same time."

$$\mathrm{AG}\neg(e_1 \cdot e_4)$$

- "Every philosopher will get infinitely many turns to eat."

- "Philosopher 2 will be the first to eat."



Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Specifying using CTL formula

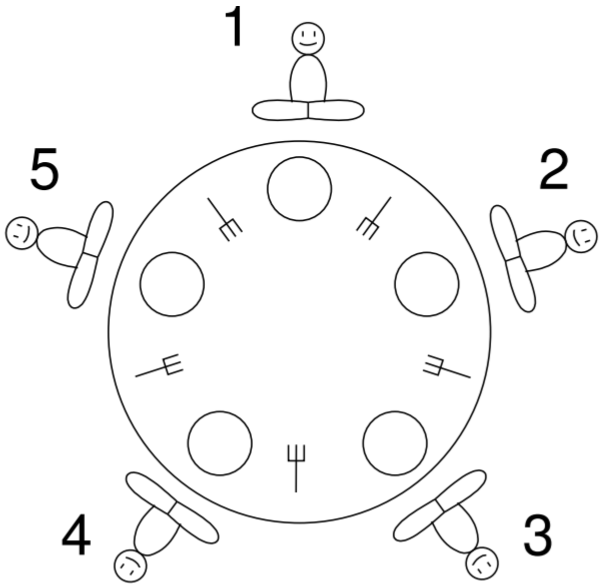
- "Philosophers 1 and 4 will never eat at the same time."

$$\mathrm{AG}\neg(e_1 \cdot e_4)$$

- "Every philosopher will get infinitely many turns to eat."

$$\mathrm{AG}(\mathrm{AF}e_1 \cdot \mathrm{AF}e_2 \cdot \mathrm{AF}e_3 \cdot \mathrm{AF}e_4 \cdot \mathrm{AF}e_5)$$

- "Philosopher 2 will be the first to eat."



Specifying using CTL formula

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

- "Philosophers 1 and 4 will never eat at the same time."

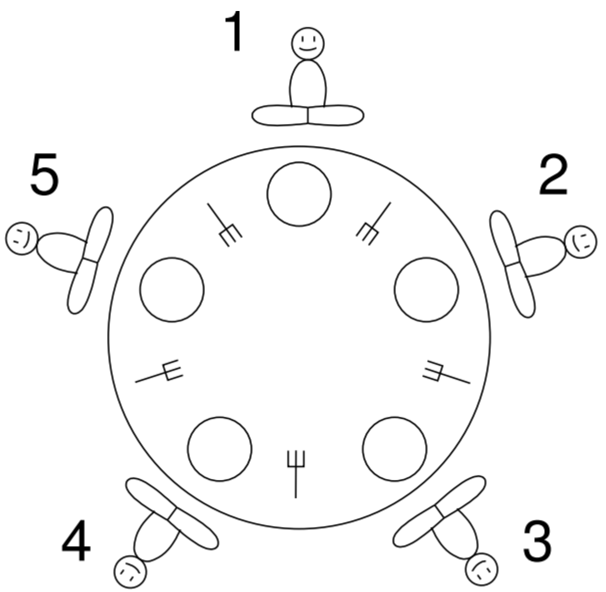
$$\mathrm{AG}\neg(e_1 \cdot e_4)$$

- "Every philosopher will get infinitely many turns to eat."

$$\mathrm{AG}(\mathrm{AF}e_1 \cdot \mathrm{AF}e_2 \cdot \mathrm{AF}e_3 \cdot \mathrm{AF}e_4 \cdot \mathrm{AF}e_5)$$

- "Philosopher 2 will be the first to eat."

$$\neg(e_1 + e_3 + e_4 + e_5)\,\mathrm{AU}\,e_2$$



Computing CTL formula

Over paths:	Path-specific:
$A\phi \rightarrow$ **A**ll ϕ	$X\phi \rightarrow$ Ne**X**t ϕ
$E\phi \rightarrow$ **E**xists ϕ	$F\phi \rightarrow$ **F**inally ϕ
	$G\phi \rightarrow$ **G**lobally ϕ
	$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

- Define $[\![\phi]\!]$ as the set of all initial states of the finite automaton for which CTL formula ϕ is true. A finite automaton with initial state q_0 satisfies ϕ iff

$$q_0 \in [\![\phi]\!]$$

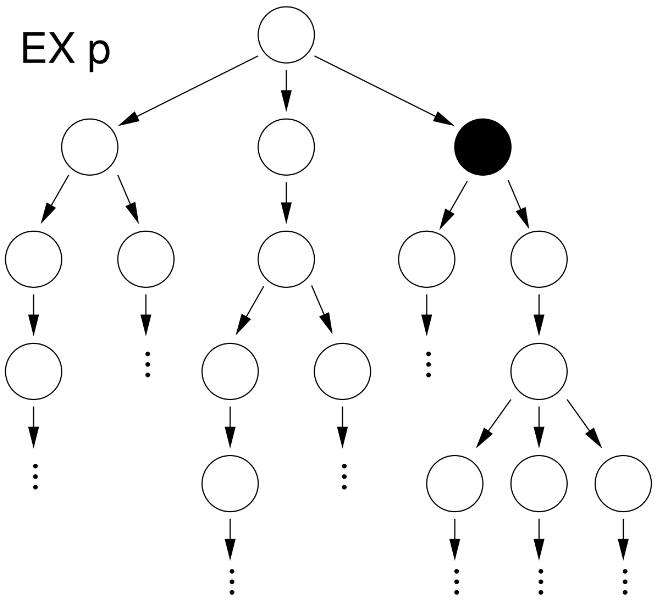
- Now, we can use our "trick": computing with sets of states!
  - $\psi_{[\![\phi]\!]}(q)$ is true if the state q is in the set $[\![\phi]\!]$, i.e., it is a state for which the CTL formula is true.
  - Therefore, we can also say

$$q_0 \in [\![\phi]\!] \equiv \psi_{[\![\phi]\!]}(q_0)$$

characteristic function of the set $[\![\phi]\!]$

Computing CTL formula: EX ϕ

Over paths:	Path-specific:
$A\phi$ → **A**ll ϕ	$X\phi$ → Ne**X**t ϕ
$E\phi$ → **E**xists ϕ	$F\phi$ → **F**inally ϕ
	$G\phi$ → **G**lobally ϕ
	$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

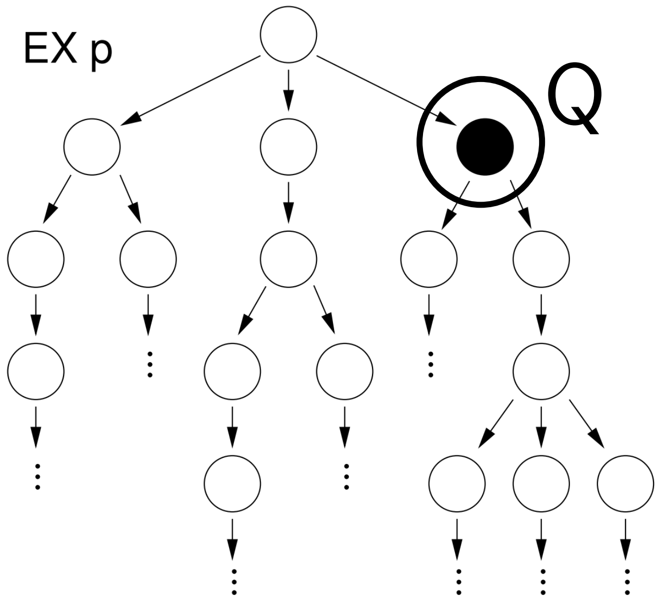


Over paths:
Aϕ → **All** ϕ
Eϕ → **Exists** ϕ

Path-specific:
Xϕ → Ne**X**t ϕ
Fϕ → **F**inally ϕ
Gϕ → **G**lobally ϕ
ϕ_1Uϕ_2 → ϕ_1**U**ntil ϕ_2

Computing CTL formula: EX ϕ

- Suppose that Q is the set of initial states for which the formula ϕ is true.



Sets	$Q = [\![\phi]\!]$
Characteristic functions	$\psi_Q(q)$

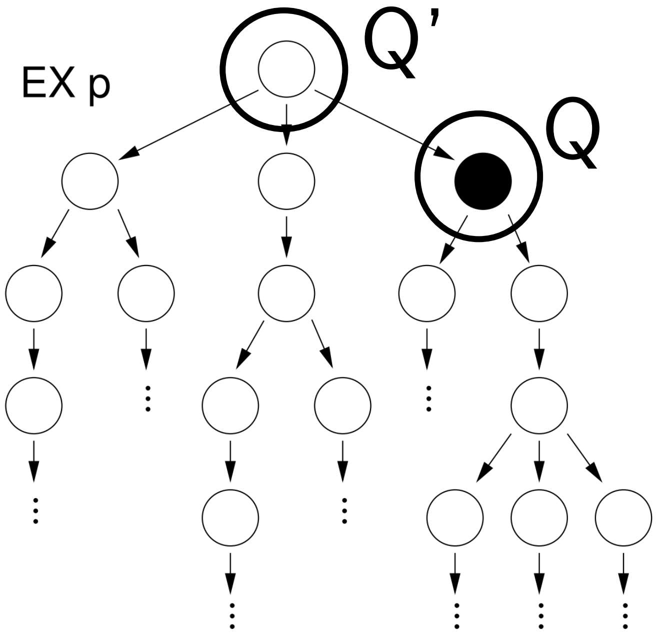
Over paths:
$A\phi \to$ **A**ll ϕ
$E\phi \to$ **E**xists ϕ

Path-specific:
$X\phi \to$ Ne**X**t ϕ
$F\phi \to$ **F**inally ϕ
$G\phi \to$ **G**lobally ϕ
$\phi_1 U \phi_2 \to \phi_1$ **U**ntil ϕ_2

Computing CTL formula: EX ϕ

- Suppose that Q is the set of initial states for which the formula ϕ is true.
- Q' is the set of predecessor states of Q, i.e., the set of states that lead in one transition to a state in Q:

$$Q' = Pre(Q, \delta) = \{q' \mid \exists q : \psi_\delta(q', q) \cdot \psi_Q(q)\}$$



Sets $\quad Q = [\![\phi]\!] \longrightarrow Q' = [\![\mathrm{EX}\phi]\!] = \mathrm{Pre}([\![\phi]\!], \delta)$

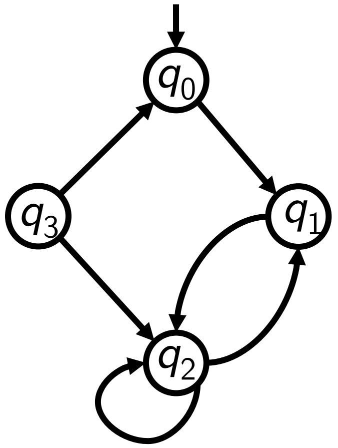
Characteristic functions $\quad \psi_Q(q) \longrightarrow \psi_{Q'}(q') = (\exists q \ : \ \psi_Q(q) \cdot \psi_\delta(q', q))$

Over paths:
$A\phi \to$ **All** ϕ
$E\phi \to$ **Exists** ϕ

Path-specific:
$X\phi \to$ Ne**X**t ϕ
$F\phi \to$ **F**inally ϕ
$G\phi \to$ **G**lobally ϕ
$\phi_1 U \phi_2 \to \phi_1$ **U**ntil ϕ_2

Computing CTL formula: EX ϕ

- Example for EX ϕ : Compute EX q_2



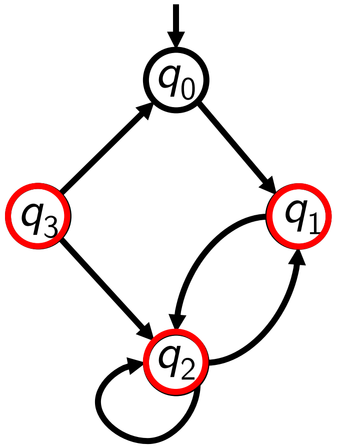
$[\![q_2]\!] = \{q_2\}$

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Computing CTL formula: EX ϕ

- Example for EX ϕ : Compute EX q_2



$$[\![q_2]\!] = \{q_2\}$$

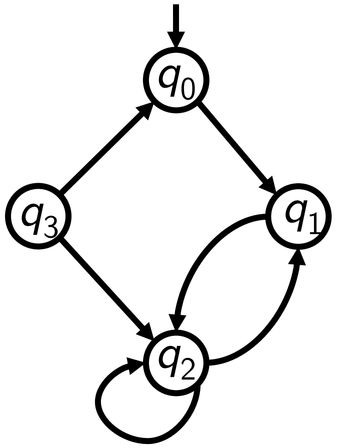
$$Q' = [\![EX\ q_2]\!] = Pre(\{q_2\}, \delta) = \{q_1, q_2, q_3\}$$

$$\{q' \mid \exists q : \psi_\delta(q', q) \cdot \psi_Q(q)\}$$

Computing CTL formula: EX ϕ

Over paths:	Path-specific:
$A\phi$ → **A**ll ϕ	$X\phi$ → Ne**X**t ϕ
$E\phi$ → **E**xists ϕ	$F\phi$ → **F**inally ϕ
	$G\phi$ → **G**lobally ϕ
	$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

- Example for EX ϕ : Compute EX q_2



$$[\![q_2]\!] = \{q_2\}$$

$$Q' = [\![EX\ q_2]\!] = Pre(\{q_2\}, \delta) = \{q_1, q_2, q_3\}$$

$$\{q' \mid \exists q : \psi_\delta(q', q) \cdot \psi_Q(q)\}$$

As $q_0 \notin [\![EX\ q_2]\!] = \{q_1, q_2, q_3\}$, the CTL formula EX q_2 is not true.

Computing CTL formula: EF ϕ

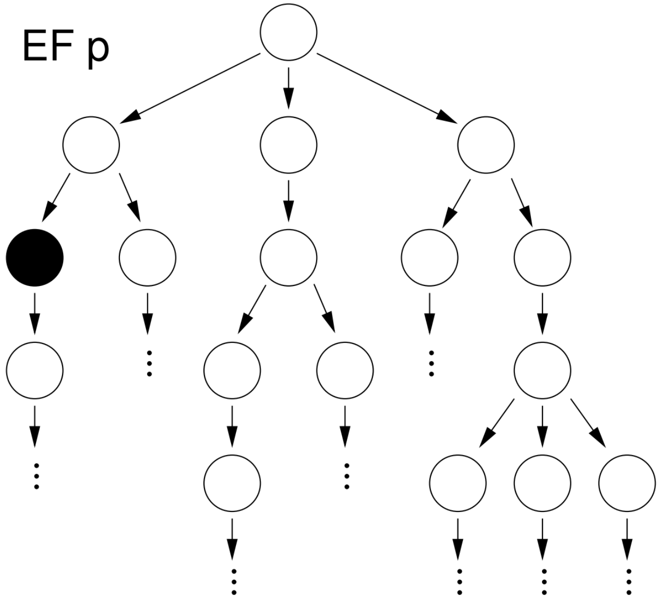
Over paths:	Path-specific:
$A\phi$ → **A**ll ϕ	$X\phi$ → Ne**X**t ϕ
$E\phi$ → **E**xists ϕ	$F\phi$ → **F**inally ϕ
	$G\phi$ → **G**lobally ϕ
	$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

- Start with the set of initial states for which the formula ϕ is true.
- Add to this set the set of predecessor states. Repeat for the resulting set of states, …., until we reach a fixed-point.

$$Q_0 = [\![\phi]\!]$$

$$Q_i = Q_{i-1} \cup \mathrm{Pre}(Q_{i-1}, \delta)$$ for all $i > 1$ until a fixed point Q' is reached

$$[\![\mathrm{EF}\phi]\!] = Q'$$

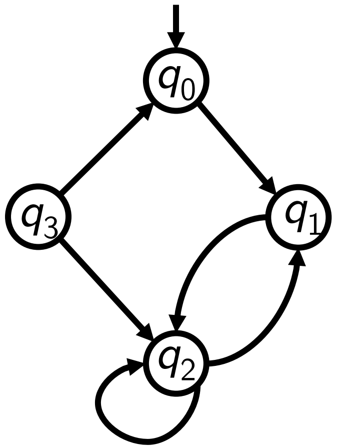


Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Computing CTL formula: EF ϕ

- Example for EFϕ: Compute EF q_2



$$Q_0 = [\![q_2]\!] = \{q_2\}$$

Over paths:

$A\phi \rightarrow$ **All** ϕ

$E\phi \rightarrow$ **Exists** ϕ

Path-specific:

$X\phi \rightarrow$ Ne**X**t ϕ

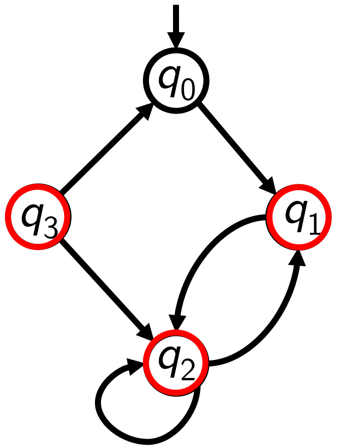
$F\phi \rightarrow$ **F**inally ϕ

$G\phi \rightarrow$ **G**lobally ϕ

$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Computing CTL formula: EF ϕ

- Example for EFϕ: Compute EF q_2



$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_1, q_2, q_3\}$$

$$Q_0 = [\![q_2]\!] = \{q_2\}$$

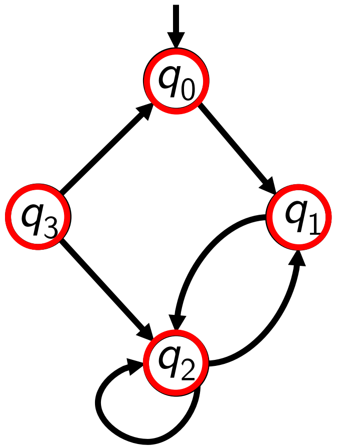
$$Q_1 = \{q_2\} \cup \text{Pre}(\{q_2\}, \delta) = \{q_1, q_2, q_3\}$$

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Computing CTL formula: EF ϕ

- Example for EFϕ: Compute EF q_2



$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_1, q_2, q_3\}$$

$$Q_0 = [\![q_2]\!] = \{q_2\}$$

$$Q_1 = \{q_2\} \cup \mathrm{Pre}(\{q_2\}, \delta) = \{q_1, q_2, q_3\}$$

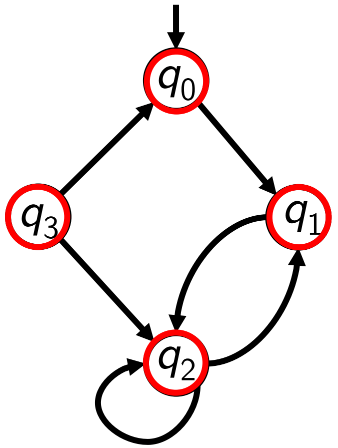
$$Q_2 = \{q_1, q_2, q_3\} \cup \mathrm{Pre}(\{q_1, q_2, q_3\}, \delta) = \{q_0, q_1, q_2, q_3\}$$

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Computing CTL formula: EF ϕ

- Example for EFϕ: Compute EF q_2



$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_1, q_2, q_3\}$$

$$Q_0 = [\![q_2]\!] = \{q_2\}$$

$$Q_1 = \{q_2\} \cup \mathrm{Pre}(\{q_2\}, \delta) = \{q_1, q_2, q_3\}$$

$$Q_2 = \{q_1, q_2, q_3\} \cup \mathrm{Pre}(\{q_1, q_2, q_3\}, \delta) = \{q_0, q_1, q_2, q_3\}$$

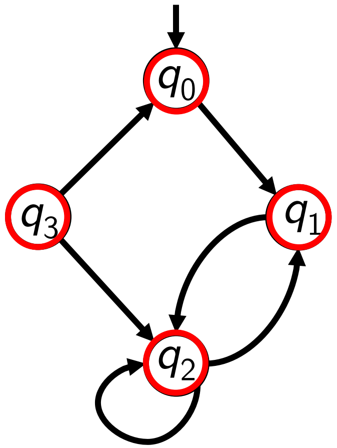
$$Q_3 = \{q_0, q_1, q_2, q_3\} \cup \underline{\mathrm{Pre}(\{q_0, q_1, q_2, q_3\}, \delta)} = \{q_0, q_1, q_2, q_3\}$$

$$[\![\mathrm{EF} q_2]\!] = Q_3 = \{q_0, q_1, q_2, q_3\}$$

Computing CTL formula: EF ϕ

Over paths:	Path-specific:
$A\phi$ → **A**ll ϕ	$X\phi$ → Ne**X**t ϕ
$E\phi$ → **E**xists ϕ	$F\phi$ → **F**inally ϕ
	$G\phi$ → **G**lobally ϕ
	$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

- Example for EFϕ: Compute EF q_2



$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_1, q_2, q_3\}$$

$$Q_0 = [\![q_2]\!] = \{q_2\}$$

$$Q_1 = \{q_2\} \cup \mathrm{Pre}(\{q_2\}, \delta) = \{q_1, q_2, q_3\}$$

$$Q_2 = \{q_1, q_2, q_3\} \cup \mathrm{Pre}(\{q_1, q_2, q_3\}, \delta) = \{q_0, q_1, q_2, q_3\}$$

$$Q_3 = \{q_0, q_1, q_2, q_3\} \cup \mathrm{Pre}(\{q_0, q_1, q_2, q_3\}, \delta) = \{q_0, q_1, q_2, q_3\}$$

$$[\![\mathrm{EF} q_2]\!] = Q_3 = \{q_0, q_1, q_2, q_3\}$$

As $q_0 \in [\![\mathrm{EF} q_2]\!] = \{q_0, q_1, q_2, q_3\}$, the CTL formula EF q_2 is true.

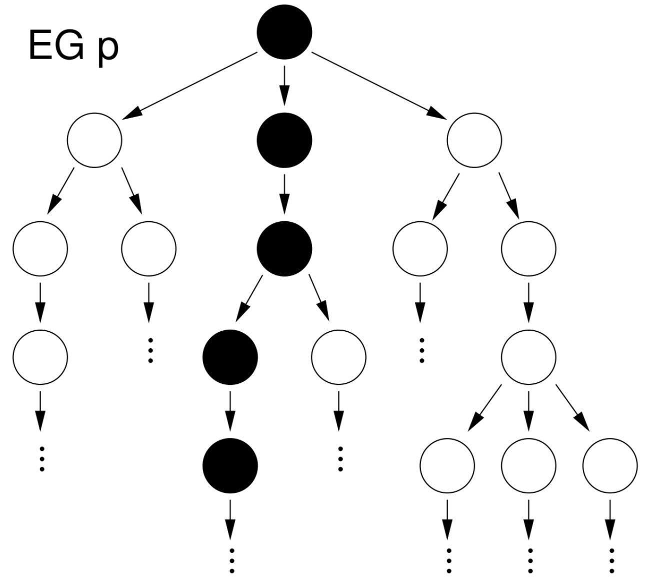
Computing CTL formula: EG ϕ

Over paths:	Path-specific:
$A\phi$ → **A**ll ϕ	$X\phi$ → Ne**X**t ϕ
$E\phi$ → **E**xists ϕ	$F\phi$ → **F**inally ϕ
	$G\phi$ → **G**lobally ϕ
	$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

- Start with the set of initial states for which the formula ϕ is true.
- Cut this set with the set of predecessor states. Repeat for the resulting set of states, …., until we reach a fixed-point.

$$Q_0 = [\![\phi]\!]$$

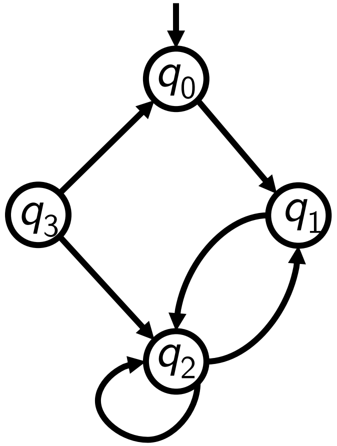
$Q_i = Q_{i-1} \cap \mathrm{Pre}(Q_{i-1}, \delta)$ for all $i > 1$ until a fixed point Q' is reached



Computing CTL formula: EG ϕ

Over paths:	Path-specific:
$A\phi$ → **A**ll ϕ	$X\phi$ → Ne**X**t ϕ
$E\phi$ → **E**xists ϕ	$F\phi$ → **F**inally ϕ
	$G\phi$ → **G**lobally ϕ
	$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

- Example for EG ϕ: Compute EG q_2



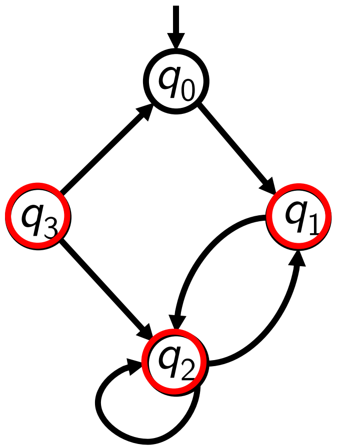
$$Q_0 = [\![q_2]\!] = \{q_2\}$$

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

Computing CTL formula: EG ϕ

- Example for EG ϕ: Compute EG q_2



$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_1, q_2, q_3\}$$

$$Q_0 = [\![q_2]\!] = \{q_2\}$$

$$Q_1 = \{q_2\} \cap \mathrm{Pre}(\{q_2\}, \delta) = \{q_2\}$$

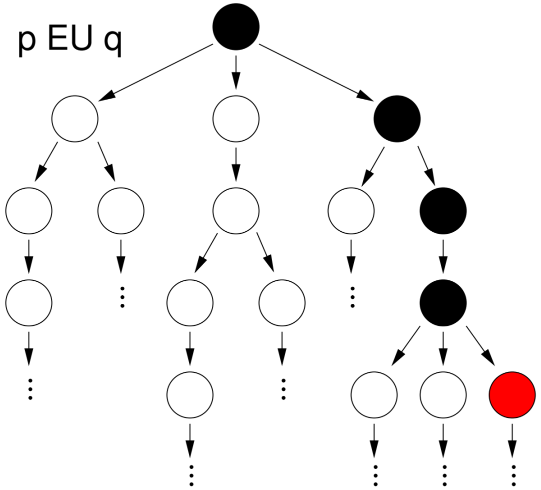
$$[\![\mathrm{EG} q_2]\!] = Q_2 = \{q_2\}$$

As $q_0 \notin [\![\mathrm{EG} q_2]\!] = \{q_2\}$, the CTL formula EG q_2 is not true.

Over paths:	Path-specific:
$A\phi$ → **All** ϕ	$X\phi$ → Ne**X**t ϕ
$E\phi$ → **Exists** ϕ	$F\phi$ → **F**inally ϕ
	$G\phi$ → **G**lobally ϕ
	$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

Computing CTL formula: $\phi_1 EU \phi_2$

- Start with the set of initial states for which the formula ϕ_2 is true.
- Add to this set the set of predecessor states for which the formula ϕ_1 is true. Repeat for the resulting set of states we do the same, …., until we reach a fixed-point.
- Like EF ϕ_2; the only difference is that, on our path backwards, we always make sure that also ϕ_1 holds.



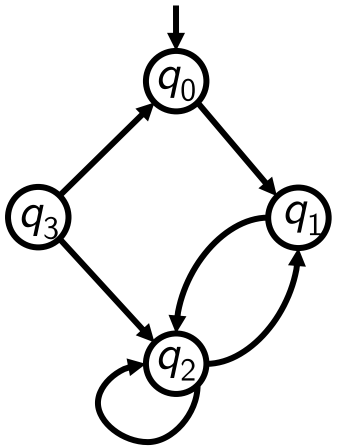
$$Q_0 = [\![\phi_2]\!]$$

$$Q_i = Q_{i-1} \cup (\mathrm{Pre}(Q_{i-1}, \delta) \cap [\![\phi_1]\!])$$ for all $i > 1$ until a fixed point is reached

Over paths:	Path-specific:
$A\phi$ → **All** ϕ	$X\phi$ → Ne**X**t ϕ
$E\phi$ → **Exists** ϕ	$F\phi$ → **F**inally ϕ
	$G\phi$ → **G**lobally ϕ
	$\phi_1 U \phi_2$ → ϕ_1 **U**ntil ϕ_2

Computing CTL formula: $\phi_1 EU \phi_2$

- Example for $\phi_1 EU \phi_2$: Compute $q_0\ EU\ q_1$



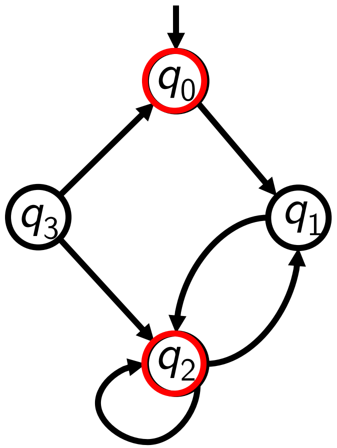
$$Q_0 = [\![q_1]\!] = \{q_1\}$$

Computing CTL formula: $\phi_1 EU \phi_2$

Over paths:
$A\phi \rightarrow$ **All** ϕ
$E\phi \rightarrow$ **Exists** ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
$\phi_1 U \phi_2 \rightarrow \phi_1$ **U**ntil ϕ_2

- Example for $\phi_1 EU \phi_2$: Compute $q_0\ EU\ q_1$



$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_0, q_2\}$$

$$Q_0 = [\![q_1]\!] = \{q_1\}$$

$$Q_1 = \{q_1\} \cup (\text{Pre}(\{q_1\}, \delta) \cap \{q_0\}) = \{q_0, q_1\}$$

Computing CTL formula: $\phi_1 EU \phi_2$

Over paths:
$A\phi \rightarrow$ **A**ll ϕ
$E\phi \rightarrow$ **E**xists ϕ

Path-specific:
$X\phi \rightarrow$ Ne**X**t ϕ
$F\phi \rightarrow$ **F**inally ϕ
$G\phi \rightarrow$ **G**lobally ϕ
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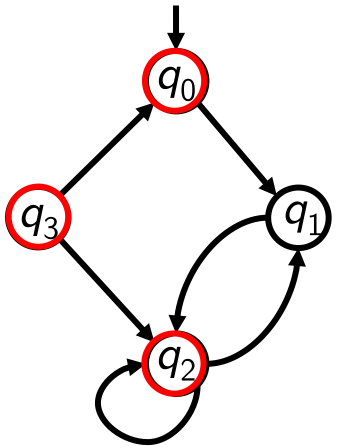
- Example for $\phi_1 EU \phi_2$: Compute $q_0\ EU\ q_1$



$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_0, q_2\}$$

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$$Q_2 = \{q_0, q_1\} \cup (\text{Pre}(\{q_0, q_1\}, \delta) \cap \{q_0\}) = \{q_0, q_1\}$$

$$\{q_0, q_2, q_3\}$$

$$[\![q_0 \text{EU} q_1]\!] = Q_2 = \{q_0, q_1\}$$

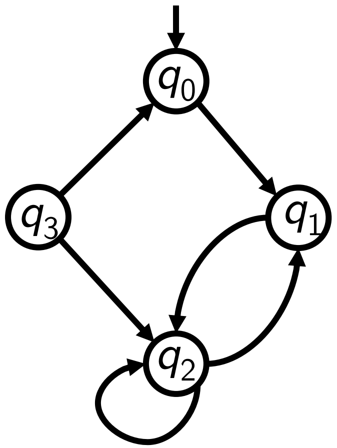
As $q_0 \in [\![q_0 \text{EU} q_1]\!] = \{q_0, q_1\}$, the CTL formula q_0 EU q_1 is true.

Over paths:
Aϕ → **All** ϕ
Eϕ → **Exists** ϕ

Path-specific:
Xϕ → Ne**X**t ϕ
Fϕ → **F**inally ϕ
Gϕ → **G**lobally ϕ
ϕ_1Uϕ_2 → ϕ_1 **U**ntil ϕ_2

Computing CTL formula: $\phi_1 EU \phi_2$

- Example for $\phi_1 EU \phi_2$: Compute $q_0\ EU\ q_1$



$$\{q' \mid \exists q \text{ with } \psi_Q(q) \cdot \psi_\delta(q', q)\} = \{q_0, q_2\}$$

$$Q_0 = [\![q_1]\!] = \{q_1\}$$

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$$Q_2 = \{q_0, q_1\} \cup (\mathrm{Pre}(\{q_0, q_1\}, \delta) \cap \{q_0\}) = \{q_0, q_1\}$$

$$\{q_0, q_2, q_3\}$$

$$[\![q_0 \mathrm{EU} q_1]\!] = Q_2 = \{q_0, q_1\}$$

As $q_0 \in [\![q_0 \mathrm{EU} q_1]\!] = \{q_0, q_1\}$, the CTL formula q_0 EU q_1 is true.

Compute other CTL expressions as:
$\mathrm{AF}\phi \equiv \neg\mathrm{EG}(\neg\phi)$ $\quad \mathrm{AG}\phi \equiv \neg\mathrm{EF}(\neg\phi)$ $\quad \mathrm{AX}\phi \equiv \neg\mathrm{EX}(\neg\phi)$

So... what is model-checking exactly?

Model-checking is an algorithm which takes two inputs

- a DES model $\boldsymbol{M}$
- a formula $\boldsymbol{\phi}$

Finite automato
Petri nets
Kripke machine
...

CTL, LTL, ...

It explores the state space of $\boldsymbol{M}$ such as to either

- prove that $\boldsymbol{M} \vDash \boldsymbol{\phi}$, or
- return a trace where the formula does not hold in $\boldsymbol{M}$.

So... what is model-checking exactly?

Model-checking is an algorithm which takes two inputs

- a DES model $\boldsymbol{M}$ — Finite automato, Petri nets, Kripke machine, ...
- a formula $\boldsymbol{\phi}$ — CTL, LTL, ...

It explores the state space of $\boldsymbol{M}$ such as to either

- prove that $\boldsymbol{M} \vDash \boldsymbol{\phi}$, or
- return a trace where the formula does not hold in $\boldsymbol{M}$. — a counter-example

Extremely useful!

- Debugging the model
- Searching a specific execution sequence

Your turn to practice!

after the break

1. Familiarise yourself with CTL logic and how to compute sets of states satisfying a given formula
2. Convert a concrete problem into a state reachability question (adapted from state-of-the-art research!)

Efficient state representation

- Set of states as Boolean function
- Binary Decision Diagram representation

Computing reachability

- Leverage efficient state representation
- Explore successor sets of states

Today

Proving properties

- Temporal logic (CTL)
- Encoding as reachability problem

Conclusion and perspectives

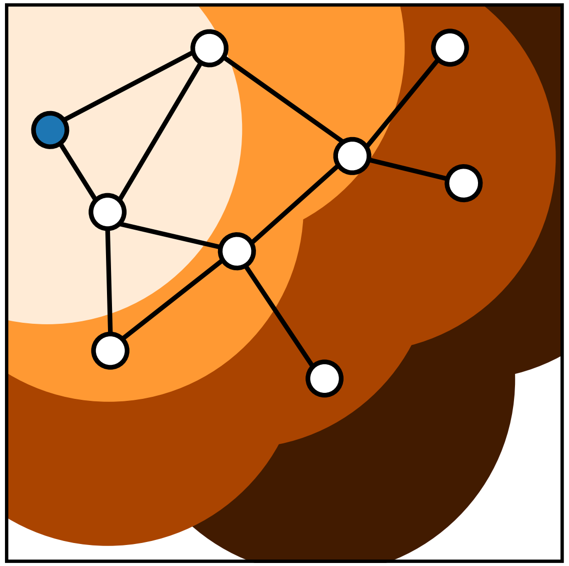
Next week(s) Petri Nets

- asynchronous DES model
- tailored model concurrent distributed systems
- capture an infinite state space with a finite model

a computer
a network

How they work?
How to use them for modeling systems?
How to verify them?

Thanks for your attention and see you next week! ☺



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December 1, 2022

Most materials from Lothar Thiele and Romain Jacob