

CrashCourse — Verification of Finite Automata

CTL Model-Checking

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TIK

Formulation of CTL properties

Based on atomic propositions (ϕ) and quantifiers

$A\phi$ → «**A**ll ϕ », ϕ holds on all paths

$E\phi$ → «**E**xists ϕ », ϕ holds on at least one path

} Quantifiers
over paths

$X\phi$ → «**N**e**X**t ϕ », ϕ holds on the next state

$F\phi$ → «**F**inally ϕ », ϕ holds at some state along the path

$G\phi$ → «**G**lobally ϕ », ϕ holds on all states along the path

$\phi_1 U \phi_2$ → « ϕ_1 **U**ntil ϕ_2 », ϕ_1 holds until ϕ_2 holds

} Path-specific
quantifiers

Formulation of CTL properties

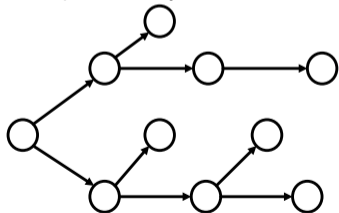
Proper CTL formula: $\{A,E\} \{X,F,G,U\} \phi$

→ Quantifiers **go by pairs**, you need one of each.

Missing Hypothesis

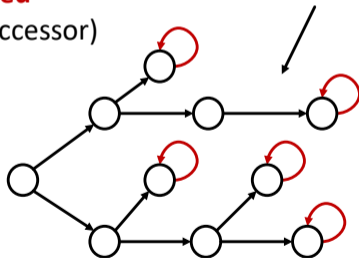
Interpretation on CTL formula

→ Transition functions are **fully defined**
(i.e. every state has at least one successor)



Automaton of interest

→



Automaton to work with

Simple “means” that we
get rid of leaf nodes...
→ They transition
to themselves

Inverting properties is sometimes useful!

$$\text{AG } \phi := \neg \text{EF } \neg \phi$$

$$\text{AF } \phi := \neg \text{EG } \neg \phi$$

$$\text{EF } \phi := \neg \text{AG } \neg \phi$$

$$\text{EG } \phi := \neg \text{AF } \neg \phi$$

Inverting properties is sometimes useful!

“On all paths, for all states, ϕ holds” \iff
“There exists no path along which at some
state ϕ doesn't hold.”




$$AG \phi := \neg EF \neg \phi$$

$$AF \phi := \neg EG \neg \phi$$




$$EF \phi := \neg AG \neg \phi$$

$$EG \phi := \neg AF \neg \phi$$

Inverting properties is sometimes useful!

| | | |
|--------------------------------|-----------------------------------------------------------------------------------|---------------------------------------------------------------------------------------------------------------------------------------|
| $AG \phi := \neg EF \neg \phi$ |  | “On all paths, for all states, ϕ holds” \iff “There exists no path along which at some state ϕ doesn't hold.” |
| $AF \phi := \neg EG \neg \phi$ |  | “On all paths, there exists a state where ϕ holds” \iff “There exists no path along which ϕ doesn't hold for all states.” |
| $EF \phi := \neg AG \neg \phi$ |  | ... |
| $EG \phi := \neg AF \neg \phi$ | | |

Inverting properties is sometimes useful!

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| $AG \phi := \neg EF \neg \phi$ |  | “On all paths, for all states, ϕ holds” \iff “There exists no path along which at some state ϕ doesn't hold.” |
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| $EF \phi := \neg AG \neg \phi$ |  | ... |
| $EG \phi := \neg AF \neg \phi$ | | |

Remark: There exists other temporal logics.

- LTL (Linear Temporal Logic)
- $CTL^* = \{CTL, LTL\}$
- ...

How to verify CTL properties?

Convert the property verification into a reachability problem

1. Start from states in which the property holds;
2. Compute all predecessor states for which the property still holds true;
(same as for computing successor, with the inverse the transition function)
3. If initial states set is a subset, the property is satisfied by the model.

Computation specifics are described in the lecture slides.

So... what is Model-Checking exactly?

An **algorithm**

Input

- A DES model, M
 - Finite automata,
 - Petri nets,
 - Kripke machine, ...
- A logic property, ϕ
 - CTL,
 - LTL, ...

Output

- $M \models \phi$?
- A trace for which the property does not hold!

Your turn to work!

Ex 1a) Temporal Logic

(i) $EF a : Q = \{0, 1, 2, 3\}$

(ii) $EG a : Q = \{0, 3\}$

(iii) Build the set step-by-step:

$$AX a : Q_1 = \{2, 3\}$$

$$EX AX a : Q_2 = \{1, 2\}$$

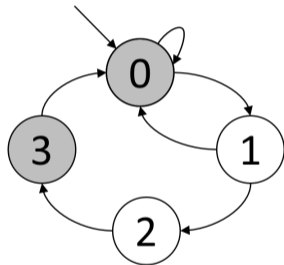
(iv) Build the set step-by-step:

$$\neg a : Q_1 = \{1, 2\}$$

$$EX \neg a : Q_2 = \{0, 1\}$$

$$a \wedge EX \neg a : Q_3 = \{0\}$$

$$EF(a \wedge EX \neg a) : Q_4 = \{0, 1, 2, 3\}$$



Ex 1b) Temporal Logic

$$(i) \quad \neg AF Z = EG \neg Z \quad \implies \quad AF Z = \neg EG \neg Z$$

- (ii)
- To get $EG \neg Z$ iteratively, we start with $Q = \{q : q \notin Z\}$.
 - At each step, require each state $q \in Q$ to have $\exists q' \in Q \cup f(q)$.
→ This will only remove states in Q
 - Stop as soon as nothing changes anymore.

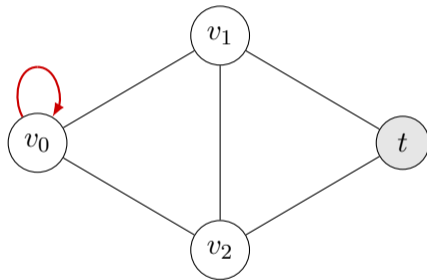
$$\begin{aligned} Q_0 &= S \setminus Z \\ Q_{i+1} &= Q_i \cap \text{pred}(Q_i, f) \\ k &= \min\{i \mid Q_{i+1} = Q_i\} \\ Q_{AF Z} &= Z \setminus Q_k \end{aligned}$$

Require: ψ_Z, ψ_f

```
 $\psi_{cur} \leftarrow \neg \psi_Z$   
 $\psi_{next} \leftarrow \psi_{cur} \wedge \psi_{\text{pred}(\psi_{cur}, f)}$   
while  $\psi_{cur} \neq \psi_{next}$  do  
     $\psi_{cur} \leftarrow \psi_{next}$   
     $\psi_{next} \leftarrow \psi_{cur} \wedge \psi_{\text{pred}(\psi_{cur}, f)}$   
end while  
return  $\psi_{AF Z} = \neg \psi_{cur}$ 
```

Ex 2a) Find all possible loops.

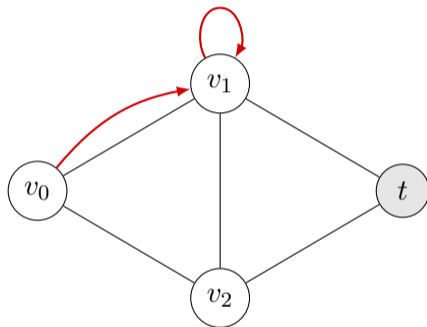
(1) $\rho_1(v_0) = v_0$



Ex 2a) Find all possible loops.

(1) $\rho_1(v_0) = v_0$

(2) $\rho_2(v_0) = v_1, \rho_2(v_1) = v_1$

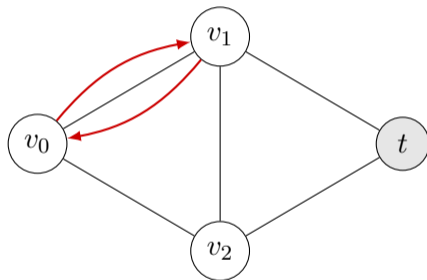


Ex 2a) Find all possible loops.

(1) $\rho_1(v_0) = v_0$

(2) $\rho_2(v_0) = v_1, \rho_2(v_1) = v_1$

(3) $\rho_3(v_0) = v_1, \rho_3(v_1) = v_0$



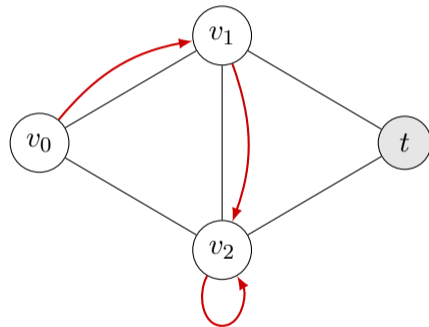
Ex 2a) Find all possible loops.

(1) $\rho_1(v_0) = v_0$

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(3) $\rho_3(v_0) = v_1, \rho_3(v_1) = v_0$

(4) $\rho_4(v_0) = v_1, \rho_4(v_1) = v_2, \rho_4(v_2) = v_2$



Ex 2a) Find all possible loops.

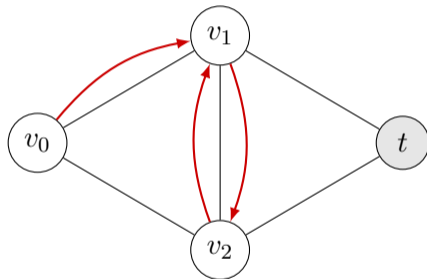
(1) $\rho_1(v_0) = v_0$

(2) $\rho_2(v_0) = v_1, \rho_2(v_1) = v_1$

(3) $\rho_3(v_0) = v_1, \rho_3(v_1) = v_0$

(4) $\rho_4(v_0) = v_1, \rho_4(v_1) = v_2, \rho_4(v_2) = v_2$

(5) $\rho_5(v_0) = v_1, \rho_5(v_1) = v_2, \rho_5(v_2) = v_1$



Ex 2a) Find all possible loops.

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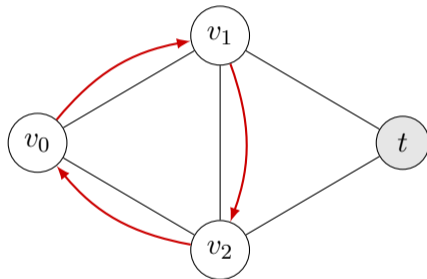
(2) $\rho_2(v_0) = v_1, \rho_2(v_1) = v_1$

(3) $\rho_3(v_0) = v_1, \rho_3(v_1) = v_0$

(4) $\rho_4(v_0) = v_1, \rho_4(v_1) = v_2, \rho_4(v_2) = v_2$

(5) $\rho_5(v_0) = v_1, \rho_5(v_1) = v_2, \rho_5(v_2) = v_1$

(6) $\rho_6(v_0) = v_1, \rho_6(v_1) = v_2, \rho_6(v_2) = v_0$



Ex 2a) Find all possible loops.

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(2) $\rho_2(v_0) = v_1, \rho_2(v_1) = v_1$

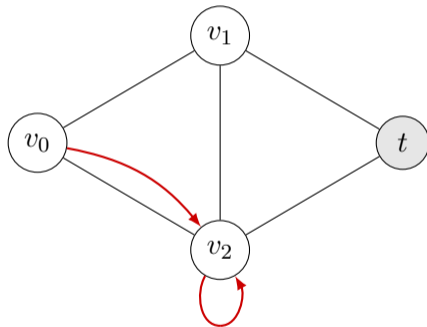
(3) $\rho_3(v_0) = v_1, \rho_3(v_1) = v_0$

(4) $\rho_4(v_0) = v_1, \rho_4(v_1) = v_2, \rho_4(v_2) = v_2$

(5) $\rho_5(v_0) = v_1, \rho_5(v_1) = v_2, \rho_5(v_2) = v_1$

(6) $\rho_6(v_0) = v_1, \rho_6(v_1) = v_2, \rho_6(v_2) = v_0$

(7) $\rho_7(v_0) = v_2, \rho_7(v_2) = v_2$



Ex 2a) Find all possible loops.

(1) $\rho_1(v_0) = v_0$

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(3) $\rho_3(v_0) = v_1, \rho_3(v_1) = v_0$

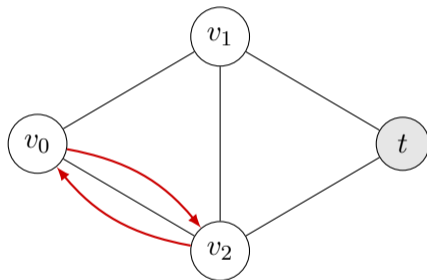
(4) $\rho_4(v_0) = v_1, \rho_4(v_1) = v_2, \rho_4(v_2) = v_2$

(5) $\rho_5(v_0) = v_1, \rho_5(v_1) = v_2, \rho_5(v_2) = v_1$

(6) $\rho_6(v_0) = v_1, \rho_6(v_1) = v_2, \rho_6(v_2) = v_0$

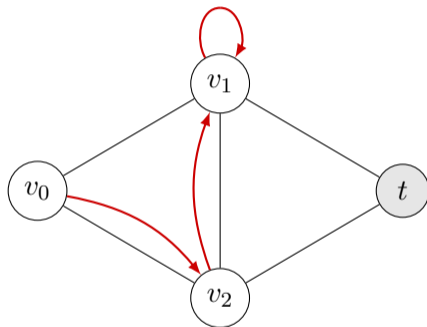
(7) $\rho_7(v_0) = v_2, \rho_7(v_2) = v_2$

(8) $\rho_8(v_0) = v_2, \rho_8(v_2) = v_0$



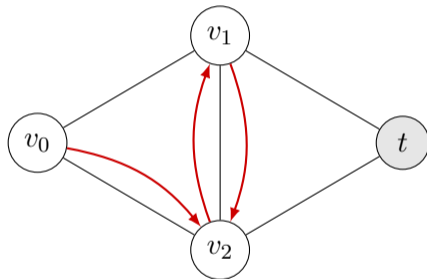
Ex 2a) Find all possible loops.

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- (4) $\rho_4(v_0) = v_1, \rho_4(v_1) = v_2, \rho_4(v_2) = v_2$
- (5) $\rho_5(v_0) = v_1, \rho_5(v_1) = v_2, \rho_5(v_2) = v_1$
- (6) $\rho_6(v_0) = v_1, \rho_6(v_1) = v_2, \rho_6(v_2) = v_0$
- (7) $\rho_7(v_0) = v_2, \rho_7(v_2) = v_2$
- (8) $\rho_8(v_0) = v_2, \rho_8(v_2) = v_0$
- (9) $\rho_9(v_0) = v_2, \rho_9(v_2) = v_1, \rho_9(v_1) = v_1$



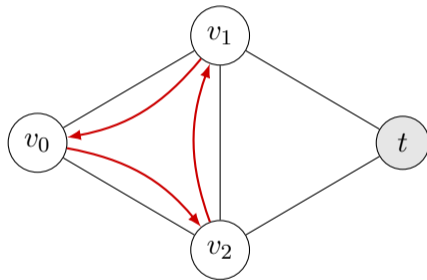
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- (4) $\rho_4(v_0) = v_1, \rho_4(v_1) = v_2, \rho_4(v_2) = v_2$
- (5) $\rho_5(v_0) = v_1, \rho_5(v_1) = v_2, \rho_5(v_2) = v_1$
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- (8) $\rho_8(v_0) = v_2, \rho_8(v_2) = v_0$
- (9) $\rho_9(v_0) = v_2, \rho_9(v_2) = v_1, \rho_9(v_1) = v_1$
- (10) $\rho_{10}(v_0) = v_2, \rho_{10}(v_2) = v_1, \rho_{10}(v_1) = v_2$



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- (3) $\rho_3(v_0) = v_1, \rho_3(v_1) = v_0$
- (4) $\rho_4(v_0) = v_1, \rho_4(v_1) = v_2, \rho_4(v_2) = v_2$
- (5) $\rho_5(v_0) = v_1, \rho_5(v_1) = v_2, \rho_5(v_2) = v_1$
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- (7) $\rho_7(v_0) = v_2, \rho_7(v_2) = v_2$
- (8) $\rho_8(v_0) = v_2, \rho_8(v_2) = v_0$
- (9) $\rho_9(v_0) = v_2, \rho_9(v_2) = v_1, \rho_9(v_1) = v_1$
- (10) $\rho_{10}(v_0) = v_2, \rho_{10}(v_2) = v_1, \rho_{10}(v_1) = v_2$
- (11) $\rho_{11}(v_0) = v_2, \rho_{11}(v_2) = v_1, \rho_{11}(v_1) = v_0$



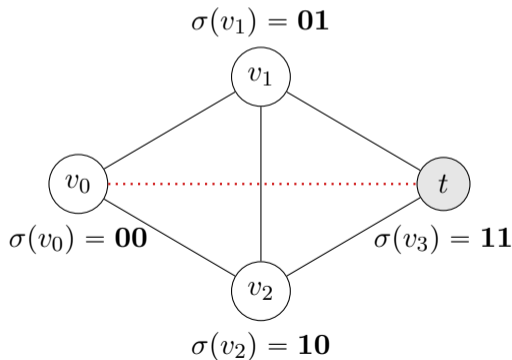
Ex 2b) Encode the physical topology

$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \underbrace{z_1^1 z_1^0}_{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$

G is a complete graph, except for the edge between v_0 and t .

$$\rho(v_0) \neq t$$

$$\psi_{topo}(\mathbf{Z}) = \neg(z_0^1 z_0^0)$$

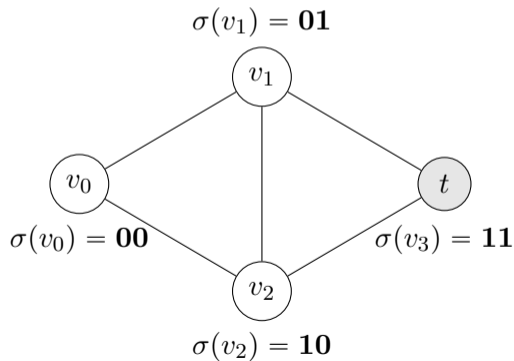


Ex 2c) Packets eventually reach t .

$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \overbrace{z_1^1 z_1^0}^{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$

Enumerate all possible paths to reach t .

$$\psi_t(\mathbf{Z}) =$$

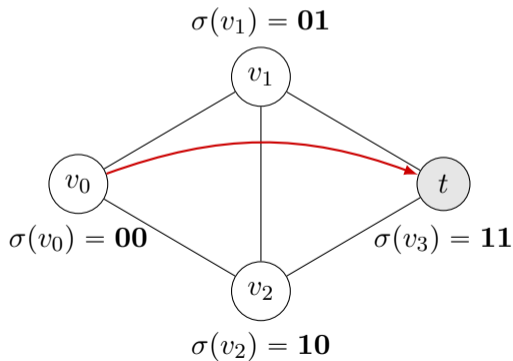


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Enumerate all possible paths to reach t .

$$\psi_t(\mathbf{Z}) = z_0^1 z_0^0$$

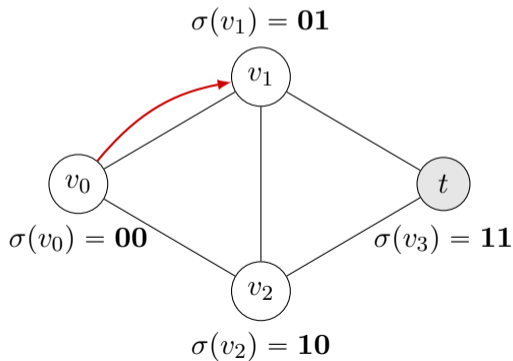


Ex 2c) Packets eventually reach t .

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Enumerate all possible paths to reach t .

$$\psi_t(\mathbf{Z}) = z_0^1 z_0^0 + z_0^{\bar{1}} z_0^0$$

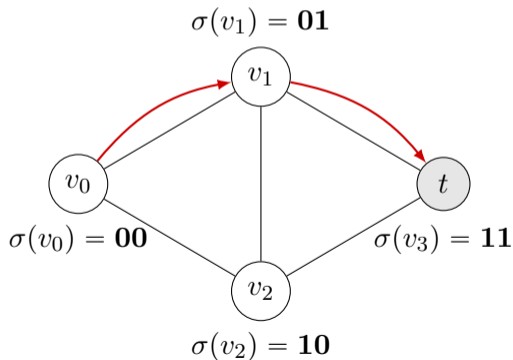


Ex 2c) Packets eventually reach t .

$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \overbrace{z_1^1 z_1^0}^{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$

Enumerate all possible paths to reach t .

$$\psi_t(\mathbf{Z}) = z_0^1 z_0^0 + z_0^{\bar{1}} z_0^0 (z_1^1 z_1^0)$$

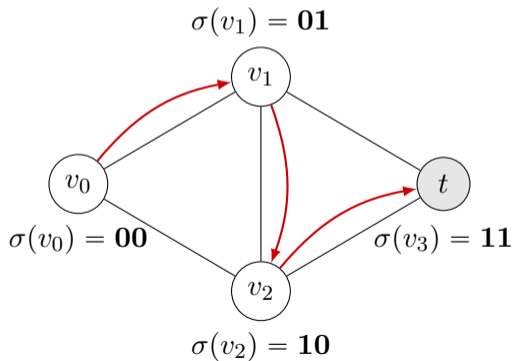


Ex 2c) Packets eventually reach t .

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Enumerate all possible paths to reach t .

$$\begin{aligned} \psi_t(\mathbf{Z}) &= z_0^1 z_0^0 \\ &+ z_0^{\bar{1}} z_0^0 \left(z_1^1 z_1^0 + z_1^1 z_1^{\bar{0}} z_2^1 z_2^0 \right) \end{aligned}$$

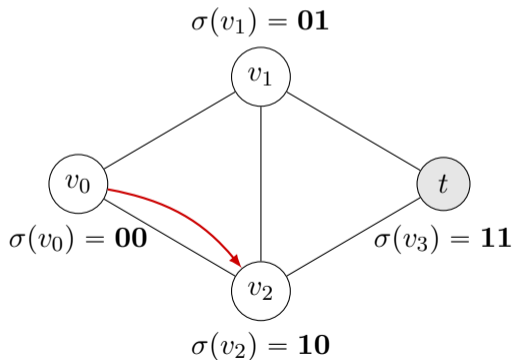


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Enumerate all possible paths to reach t .

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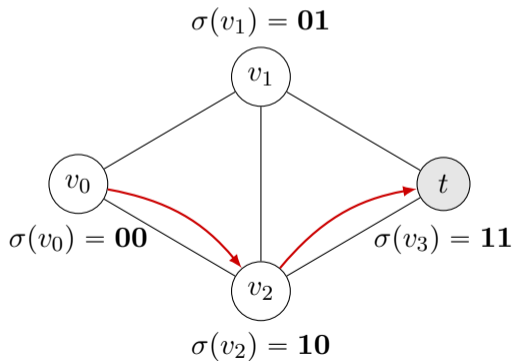


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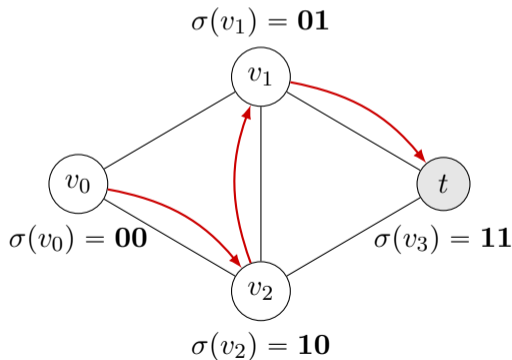


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Enumerate all possible paths to reach t .

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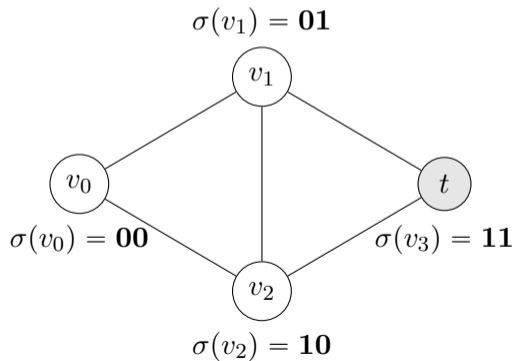


Ex 2d) Packets must traverse v_2 .

$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \underbrace{z_1^1 z_1^0}_{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$

Enumerate all possible paths to reach v_0 .

$$\psi_{v_2}(\mathbf{Z}) =$$

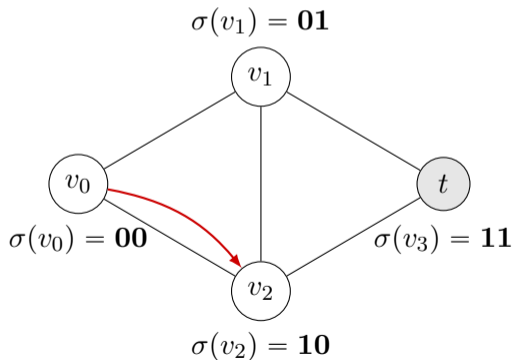


Ex 2d) Packets must traverse v_2 .

$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \underbrace{z_1^1 z_1^0}_{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$

Enumerate all possible paths to reach v_0 .

$$\psi_{v_2}(\mathbf{Z}) = z_0^1 z_0^{\bar{0}} +$$

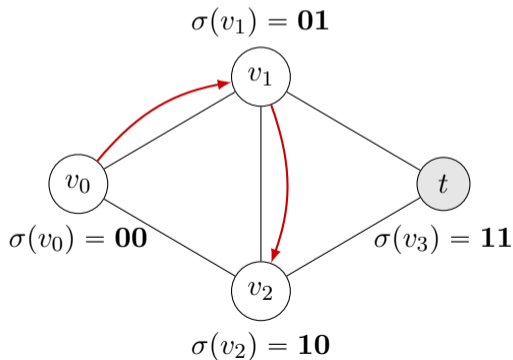


Ex 2d) Packets must traverse v_2 .

$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \underbrace{z_1^1 z_1^0}_{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$

Enumerate all possible paths to reach v_0 .

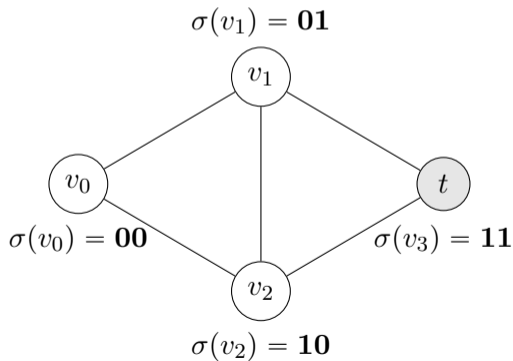
$$\psi_{v_2}(\mathbf{Z}) = z_0^1 \bar{z}_0^0 + \bar{z}_0^1 z_0^0 z_1^1 \bar{z}_1^0$$



Ex 2e) Packets must traverse v_2 and eventually reach t .

$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \underbrace{z_1^1 z_1^0}_{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$

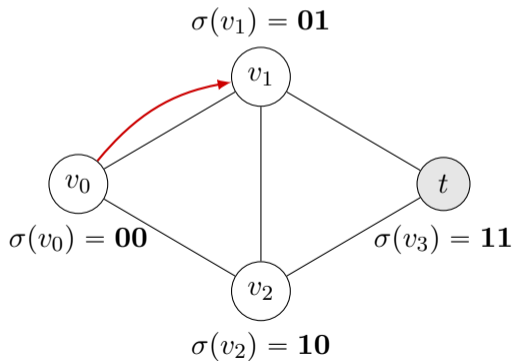
$$\begin{aligned} \psi_\phi(\mathbf{Z}) &= \psi_t(\mathbf{Z}) \cdot \psi_{v_2}(\mathbf{Z}) \\ &= \end{aligned}$$



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$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \underbrace{z_1^1 z_1^0}_{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$

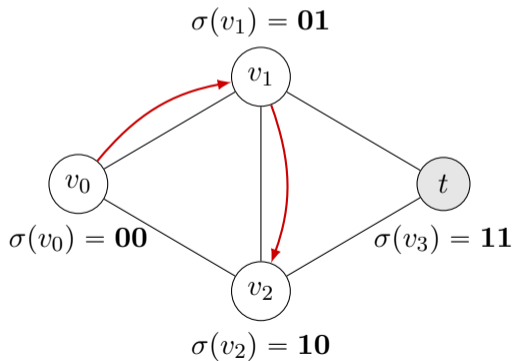
$$\begin{aligned}\psi_\phi(\mathbf{Z}) &= \psi_t(\mathbf{Z}) \cdot \psi_{v_2}(\mathbf{Z}) \\ &= \bar{z}_0^1 z_0^0\end{aligned}$$



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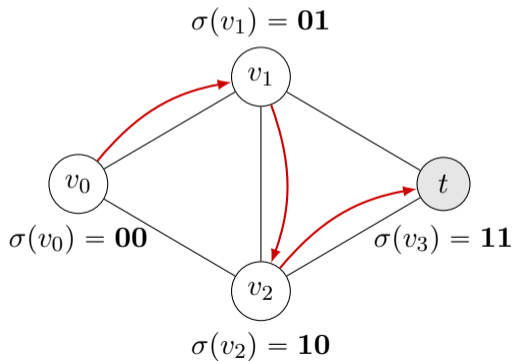
$$\begin{aligned}\psi_\phi(\mathbf{Z}) &= \psi_t(\mathbf{Z}) \cdot \psi_{v_2}(\mathbf{Z}) \\ &= \bar{z}_0^1 z_0^0 z_1^1 \bar{z}_1^0\end{aligned}$$



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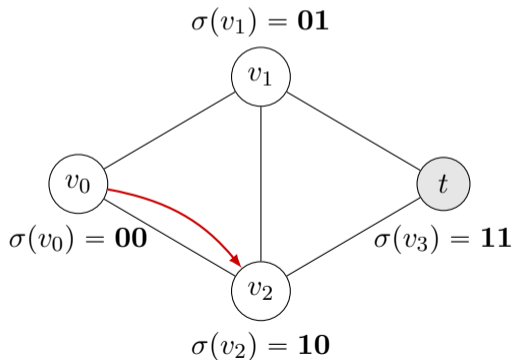
$$\begin{aligned}\psi_\phi(\mathbf{Z}) &= \psi_t(\mathbf{Z}) \cdot \psi_{v_2}(\mathbf{Z}) \\ &= \bar{z}_0^1 z_0^0 z_1^1 \bar{z}_1^0 z_2^1 z_2^0\end{aligned}$$



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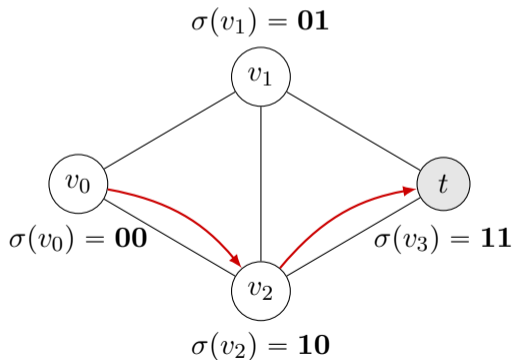
$$\begin{aligned} \psi_\phi(\mathbf{Z}) &= \psi_t(\mathbf{Z}) \cdot \psi_{v_2}(\mathbf{Z}) \\ &= \bar{z}_0^1 z_0^0 z_1^1 \bar{z}_1^0 z_2^1 z_2^0 \\ &\quad + z_0^1 \bar{z}_0^0 \end{aligned}$$



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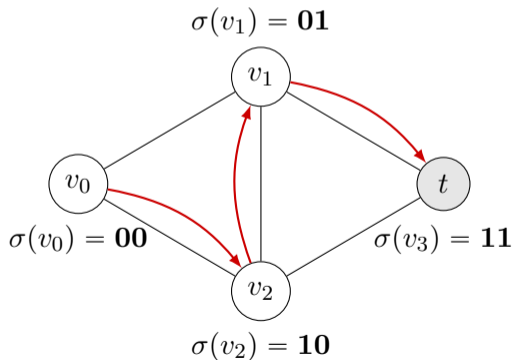
$$\begin{aligned} \psi_\phi(\mathbf{Z}) &= \psi_t(\mathbf{Z}) \cdot \psi_{v_2}(\mathbf{Z}) \\ &= \bar{z}_0^1 z_0^0 z_1^1 \bar{z}_1^0 z_2^1 z_2^0 \\ &\quad + z_0^1 z_0^0 \left(z_2^1 z_2^0 \right) \end{aligned}$$



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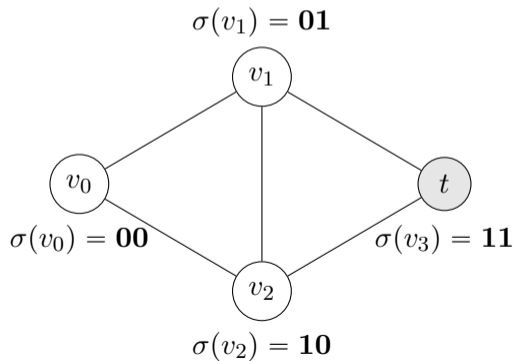
$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \underbrace{z_1^1 z_1^0}_{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$

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Ex 2f) Verify the initial and final state.

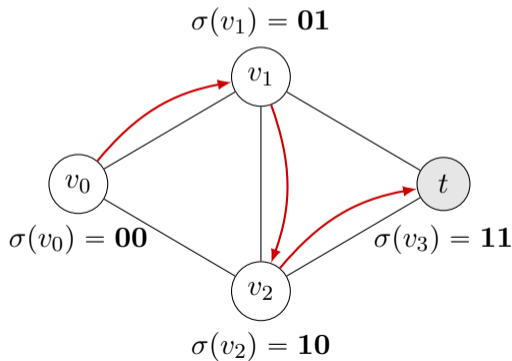
$$\mathbf{Z} = \underbrace{z_0^1 z_0^0}_{\rho(v_0)} \underbrace{z_1^1 z_1^0}_{\rho(v_1)} \underbrace{z_2^1 z_2^0}_{\rho(v_2)}$$



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 $\sigma(\rho_0) = 01\ 10\ 11$
 $\psi_\phi(\psi_{\rho_0}(\mathbf{Z})) = \text{true}$

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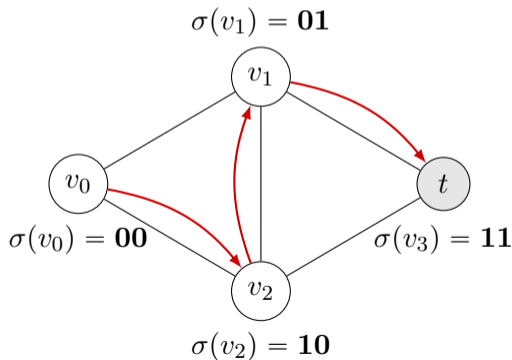


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- Initial state ρ_0
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- Final state ρ_f
 $\sigma(\rho_f) = 1001\ 11$
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Ex 2g) Describing State Transitions.

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Ex 2h) Find a safe migration with a Model Checker.

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$$EG(\phi' \wedge EF \phi_f)$$

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- (4) Invert the CTL to find a **counter-example**.

$$\begin{aligned}\neg EG(\phi' \wedge EF \phi_f) &= AF \neg(\phi' \wedge EF \phi_f) \\ &= AF(\neg\phi' \vee \neg EF \phi_f) \\ &= AF(\neg\phi' \vee AG \neg\phi_f)\end{aligned}$$

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- Characteristic function for the final state: $\psi_f(\mathbf{Z}) = z_0^1 \bar{z}_0^0 \bar{z}_1^1 z_1^0 z_2^1 z_2^0$
- The complete equation:

$$\begin{aligned}\psi^* &= \psi_0(\mathbf{Z}_0) \cdot \psi_f(\mathbf{Z}_3) \\ &\quad \cdot \psi_{trans}(\mathbf{Z}_0, \mathbf{Z}_1) \\ &\quad \cdot \psi_{trans}(\mathbf{Z}_1, \mathbf{Z}_2) \\ &\quad \cdot \psi_{trans}(\mathbf{Z}_2, \mathbf{Z}_3) \\ &\quad \cdot \psi_{topo}(\mathbf{Z}_1) \cdot \psi_\phi(\mathbf{Z}_1) \\ &\quad \cdot \psi_{topo}(\mathbf{Z}_2) \cdot \psi_\phi(\mathbf{Z}_2)\end{aligned}$$

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