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## Principles of Distributed Computing Exercise 9

## 1 Communication Complexity of Set Disjointness

In the lecture we studied the communication complexity of the equality function. Now we consider the disjointness function: Alice and Bob are given subsets  $X, Y \subseteq \{1, \ldots, k\}$  and need to determine whether they are disjoint. Each subset can be represented by a string. E.g., we define the  $i^{th}$  bit of  $x \in \{0, 1\}^k$  as  $x_i := 1$  if  $i \in X$  and  $x_i := 0$  if  $i \notin X$ . Now define disjointness of X and Y as:

 $\textit{DISJ}(x,y) := \left\{ \begin{array}{ll} 0 & : \text{ there is an index } i \text{ such that } x_i = y_i = 1 \\ 1 & : \text{ else} \end{array} \right.$ 

- **a)** Write down  $M^{DISJ}$  for the DISJ-function when k = 3.
- b) Use the matrix obtained in a) to provide a fooling set of size 4 for DISJ in case k = 3.
- c) In general, prove that  $CC(DISJ) = \Omega(k)$ .

## **2** Distinguishing Diameter 2 from 4

In the lecture we stated that when the bandwidth of an edge is limited to  $O(\log n)$ , the diameter of a graph can be computed in O(n). In this problem, we show that we can do faster in case we know that all networks/graphs on which we execute an algorithm have either diameter 2 or diameter 4. We start by partitioning the nodes into sets: Let s := s(n) be a threshold and define the set of high degree nodes  $H := \{v \in V \mid d(v) \geq s\}$  and the set of low degree nodes  $L := \{v \in V \mid d(v) < s\}$ . Next, we define: An *H*-dominating set  $\mathcal{D}OM$  is a subset  $\mathcal{D}OM \subseteq V$  of the nodes such that each node in *H* is either in the set  $\mathcal{D}OM$  or adjacent to a node in the set  $\mathcal{D}OM$ .

*Note:* We define  $N_1(v)$  as the closed neighborhood of vertex v (v and its adjacent nodes).

Assume in the following, that we can compute an *H*-dominating set  $\mathcal{D}OM$  of size  $\frac{n \log n}{s}$  in time O(D).

- a) What is the distributed runtime of Algorithm 2-vs-4 (stated next page)? In case you believe that the distributed implementation of a step is not known from the lecture, find a distributed implementation for this step! Hint: The runtime depends on s and n.
- **b)** Find a function s := s(n) such that the runtime is minimized (in terms of n).
- c) Prove that if the diameter is 2, then Algorithm 2-vs-4 always returns 2.

Now assume that the diameter of the network is 4 and that we know vertices u and v with distance 4 to each other.

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Algorithm 1 "2-vs-4".	Input: $G$ with diameter 2 or 4	Output: diameter of $G$
1: if $L \neq \emptyset$ then		
2: choose $v \in L$		$\triangleright$ We know: This takes $O(D)$ .
3: <b>compute</b> a BFS tree from each vertex in $N_1(v)$		
4: <b>else</b>		
5: <b>compute</b> an <i>H</i> -dominating set $\mathcal{D}OM$		$\triangleright$ Use: Assumption
6: <b>compute</b> a BFS tree from each vertex in $\mathcal{D}OM$		
7: end if		
8: if all BFS trees have depth 2 or 1 then		
9: <b>return</b> 2		
10: else		
11: <b>return</b> 4		
12: <b>end if</b>		

- d) Prove that if the algorithm performs a BFS from at least one node  $w \in N_1(u)$  it decides "the diameter is 4".
- e) In case L ≠ Ø: Prove that the algorithm performs a BFS of depth at least 3 from some node w. Hint: use d)
- f) In case  $L = \emptyset$ : Prove that the algorithm performs a BFS of depth at least 3 from some node w.
- g) Give a high level idea, why you think that this does not violate the lower bound of  $\Omega(n/\log n)$  presented in the lecture!
- h) Assume  $s = \frac{n}{2}$ . Prove or disprove: If the diameter is 2, then Algorithm 2-vs-4 will always compute some BFS tree of depth exactly 2.